MP/M ™

MultiProgramming Monitor Control Program

USER'S GUIDE

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FOREWORD

This manual is intended as a guide for three different levels of MP/M users. Section 1 contains all the information required to enable a person to operate applications programs running under the MP/M Operating System. Thus, the first section of this manual should enable the casual user to operate the system with a minimum amount of study and training.

The second section of this manual describes the MP/M system organization including the structure of memory and system call functions. The intention is to provide the necessary information required to write page relocatable programs and resident system processes which operate under MP/M, and which use the realtime multitasking, peripheral and disk I/O facilities of the system.

The last section provides the information needed to tailor MP/M to another computer system. In particular, the hardware dependent basic and extended I/O system entry points are described. Preparation of the MP/M loader using a CP/M 2.0 BIOS is also covered.

The system generation procedure is also described in the last section. This procedure is of interest to all three levels of MP/M users because it describes how to configure MP/M for a particular applications environment. This configuration includes the specification of memory segmentation, number of consoles, and selection optional resident system processes such as the printer spooler.

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1. MP/M FEATURES AND FACILITIES

1.1 Introduction

The purpose of the MP/M multiprogramming monitor control program is to provide a microcomputer operating system which supports multiterminal access with multiprogramming at each terminal.

OVERVIEW

The MP/M operating system is an upward compatible version of CP/M 2.0 with a number of added facilities. These added facilities are contained in new logical sections of MP/M called the extended I/O system and the extended disk operating system. In this manual the name XIOS will refer to the combined basic and extended I/O system. BDOS will refer to the standard CP/M 2.0 basic disk operating system functions and XDOS will refer to the extended disk operating system. As an upward compatible version, users can easily make the transition from CP/M to the MP/M operating system. In fact, existing CP/M *.COM files can be run under MP/M, providing that the program has been correctly written. That is, BDOS calls are made for I/O, and the only direct BIOS calls made are for console and printer I/O. There must also be at least 4 bytes of extra stack in the CP/M *.COM program.

The following basic facilities are provided:

- multiterminal support
- MultiProgramming at each terminal
- Support for bank switched memory and memory protection
- Concurrency of I/0 and CPU operations
- Interprocess communication, mutual exclusion and synchronization
- Ability to operate in sequential, polled or interrupt driven environments
- System timing functions
- Logical interrupt system utilizing flags
- Selection of system options at system generation time
- Dynamic system configuration at load time

The following optional facilities are provided:

- Spooling list files to the printer
- Scheduling programs to be run by date and time
- Displaying complete system runtime status
- Setting and reading of the date and time

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HARDWARE ENVIRONMENT

The hardware environment for MP/M must include an 8080 or Z80 CPU, a minimum of 32K bytes of memory, 1 to 16 consoles, 1 to 16 logical (or physical) disk drives each containing up to eight megabytes, and a clock/timer interrupt.

The distributed form of the MP/M operating system is configured for a polled I/O environment on the Intel MDS800 with two consoles and a realtime clock. Multiprogramming at two terminals is supported with this configuration. To improve the system performance and capability the following incremental hardware additions can be utilized by the operating system:

a. Full Interrupt System
b. Banked Memory
c. Additional Consoles

MEMORY SIZE

The MP/M operating system requires less than 15K bytes of memory when configured for two consoles and eight memory segments on the Intel MDS800. Each additional console requires 256 bytes.

Optional resident system processes can be specified at system generation which require varying amounts of memory.

PERFORMANCE

When MP/M is configured for a single console and is executing a single process, its speed approximates that of CP/M. In environments where either multiple processes and/or users are running, the speed of each individual process is degraded in proportion to the amount of I/O and compute resources required. A process which performs a large amount of I/O in proportion to computing exhibits only minor speed degradation. This also applies to a process that performs a large amount of computing, but is running concurrently with other processes that are largely I/O bound. On the other hand, significant speed degradation occurs in environments in which more than one compute bound process is running.

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1.2 Functional Description of MP/M

The MP/M Operating System is based on a realtime multitasking nucleus. This nucleus provides process dispatching, queue management, flag management, memory management and system timing functions.

MP/M is a priority driven system. This means that the highest priority ready process is given the CPU resource. The operation of determining the highest priority ready process and then giving it the CPU is called dispatching. Each process in the system has a process descriptor. The purpose of the process descriptor is to provide a data structure which contains all the information the system needs to know about a process. This information is used during dispatching to save the state of the currently running process, to determine which process is to be run, and then to restore that processes state. Process dispatching is performed at each system call, at each interrupt, and at each tick of the system clock. Processes with the same priority are "roundrobin" scheduled. That is, they are given equal slices of CPU time.

Queues perform several critical functions in a realtime multitasking environment. They can be used for the communication of messages between processes, to synchronize processes, and for mutual exclusion. As the name "queue" implies, they provide a first in first out list of messages, and as implemented in MP/M, a list of processes waiting for messages.

The flag management provided by MP/M is used to synchronize processes by signaling a significant event. Flags provide a logical interrupt system for MP/M which is independent of the physical interrupt system. Flags are used to signal interrupts, mapping an arbitrary physical interrupt environment into a regular structure.

MP/M manages memory in predefined memory segments. Up to eight memory segments of 48K can be managed by MP/M. This management of memory is consistent with hardware environments where memory is banked and/or protected in fixed segments.

System timing functions provide time of day, the capability to schedule programs to be loaded from disk and executed, and the ability to delay the execution of a process for a specified period of time.

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1.3 Console Commands

The purpose of this section is to describe the console commands which make up the operator interface to the MP/M operating system. It is important to note from the outset that there are no system defined or builtin commands. That is, the system has no reserved or special commands. All commands in the system are provided by resident system processes specified during system generation and programs residing on disk in either the CP/M *.COM file format or in the MP/M *.PRL (page relocatable) file format.

When MP/M is loaded from disk a configuration table and memory segment map are displayed on console #0. When the loading is complete each of the 1 to 16 configured consoles is a system or master console. Additional slave consoles (maximum total of slave and master consoles is 16) can be accessed using XDOS system calls.

After loading, the following message is displayed on each console:

```
MP/M
xA>
```

The 'x' shown in the prompt is the user code. At cold start an association is made between the user code and console number. The initial user code is equal to the console number. For example, console #0 is initialized to user #0 and the following prompt is displayed on console #0:

```
0A>
```

The default user code can then be changed to any desired user code with the USER command (see USER in section 1.4). All users have access to files with a user code of 0. Thus, system files and programs should have a user code of 0. Caution must be used when operating under a user code of 0 since all its files can be accessed while operating under any other user code. In general, user code 0 should be reserved for files which are accessed by all users. In the event that a file with the same name is present under user code 0 and another user code, the first file foundin the directory will be accessed.

The 'A' in the prompt is the default (currently logged) disk for the console. This can be changed individually at any console by typing in a disk drive name (A,B,C,...,or P) followed by a colon (:) when the prompt has been received. Since there are no builtin commands, the default disk specified must contain the desired command files (such as DIR, REN, ERA etc.) , or each command must be preceeded by an "A:".

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RUNNING A PROGRAM

A program is run by typing in the program name followed by a carriage return, <cr>. some programs obtain parameters on the same line following the program name. Characters on the line following the program name constitute what is called the command tail. The command tail is copied into location 0080H (relative to the base of the memory segment in which the program resides) and converted to upper case by the Command Line Interpreter (CLI). The CLI also parses the command tail producing two file control blocks at 005CH and 006CH respectively.

The programs which are provided with MP/M are described in sections 1.4 and 1.5.

ABORTING A PROGRAM

A program may be aborted by typing a control C (^C) at the console. The affect of the ^C is to terminate the program which currently owns the console. Thus, a detached program cannot be aborted with a C. A detached program must first be attached and then aborted. A running program may also be aborted using the ABORT command (see ABORT in section 1.5).

RUNNING A RESIDENT SYSTEM PROCESS

At the operator interface there is no difference between running a program from disk and running a resident system process. The actual difference is that resident system processes do not need to be loaded from disk because they are loaded by the MP/M loader when a system cold start is performed and remain resident.

DETACHING FROM A PROGRAM

There are two methods for detaching from a running program. The first is to type a control D (^D) at the console. The second method is for a program to make an XDOS detach call.

The restriction on the former method, typing D, is that the running program must be performing a check console status to observe the detach request. A check console status is automatically performed each time a user program makes a BDOS disk function call.

ATTACHING TO A DETACHED PROGRAM

A program which is detached from a console, that is it does not own a console, may be attached to a console by typing 'ATTACH' followed by the program name. A program may only be attached to the console from which it was detached. If the terminal message process (TMP) has ownership of the console and

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the user enters a ^D, the next highest priority ready process which is waiting for the console begins running.

LINE EDITING AND OUTPUT CONTROL

The Terminal message Process (TMP) allows certain line editing functions while typing in command lines:

rubout Delete the last character typed at the console, removes and echoes the last character

ctlC MP/M abort program. Terminate running process.

ctlD MP/M detach console.

ctlE Physical end of line.

ctlH Delete the last character typed at the console, backspaces one character position.

ctlj (line feed) terminate current input.

ctlM (carriage return) terminates input.

ctlR Retype current command line: types a "clean line" following character deletion with rubouts.

ctlU Remove current line after new line.

ctlX Delete the entire line typed at the console, backspaces to the beginning of the current line

ctlZ End input from the console.

The control functions ctlP, ctlQ and ctlS affect console output as shown below.

ctlP Copy all subsequent console output to the list device. Output is sent to both the list device and the console device until the next ctlP is typed. If the list device is not available a 'Printer busy' message is displayed on the console.

ctlQ Obtain ownership of the printer mutual exclusion message. Obtaining the printer using this command will ensure that the MP/M spooler, PIP, and other ctlP or ctlQ commands entered from other consoles will not be allowed access to the printer. The printer is "owned" by the TMP until another ctlP or ctlQ is entered, releasing the printer. The ctlP should be used when a program (such as a CP/M *.COM file) is executed that does

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not obtain the printer mutual exclusion message

prior to accessing the printer. If the list device is not available a 'Printer busy' message is displayed on the console.

ctlS Stop the console output temporarily. Program execution and output continue when the next character is typed at the console (e.g., another ctlS). This feature is used to stop output on high speed consoles, such as CRT's, in order to view a segment of output before continuing.

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1.4 Commonly Used System Programs

The commonly used system programs (CUSPs) or transient commands, as they are called in CP/M, are loaded from the currently logged disk and executed in a relocatable memory segment if their type is PRL or in an absolute TPA if their type is COM.

This section contains a brief description of the CUSPs. Operation of many of the CUSPs is identical to that under CP/M. In these cases the commands are marked with an asterisk '*' and the reader is referred to the Digital Research document titled "An Introduction to CP/M Features and Facilities" for a complete description of the CUSP.

GET/SET USER CODE

The USER command is used to display the current user code as well as to set the user code value. Entering the command USER followed by a <cr> will display the current user code. Note that the user code is already displayed in the prompt.

```
1A>user
user = 1
```

Entering the command USER followed by a space, a user code and then a <cr> will set the user code to the specified user code. Legal user codes are in the range 0 to 15.

```
1A>user 3
user = 3
3A>
```

CONSOLE

The CONSOLE command is used to determine the console number at which the command is entered. The console number is sometimes of interest when examining the system status to determine the processes which are detached from consoles.

```
1A>console
Console = 0
```

DISK RESET

The DSKRESET (disk reset) command is used to enable the operator to change disks. If no parameter is entered all the drives are reset. Specific drives to be reset may be included as parameters.

```
1A>DSKRESET
```


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```
1A>DSKRESET B:,E:
```

If there are any open files on the drive(s) to be reset, the disk reset is denied and the cause of the disk reset failure is shown:

```
1A>DSKRESET B:

Disk reset denied, Drive B: Console 0 Program Ed
```

The reason that disk reset is treated so carefully is that files left open (e.g. in the process of being written) will lose their updated information if they are not closed prior to a disk reset.

ERASE FILE *

The ERA (erase) command removes specified files having the current user code. If no files can be found on the selected diskette which satisfy the erase request, then the message "No file" is displayed at the console.

An attempt to erase all files,

```
2B>ERA *.*
```

will produce the following response from ERA:

```
Confirm delete all user files (Y/N)?
```

A second form of the erase command(ERAQ) enables the operator to selectively delete files that match the specified filename reference. For example:

```
OA>ERAQ *.LST
A:XIOS          LST? y
A:MYFILE        LST? N
```

TYPE A FILE *

The TYPE command displays the contents of the specified ASCII source file on the console device. The TYPE command expands tabs (ctlI characters), assuming tab positions are set at every eighth column.

The TYPE command has a pause mode which is specified by entering a 'P' followed by two decimal digits after the filename. For example:

```
0A>TYPE DUMP.ASM P23
```


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The specified number of lines will be displayed and then TYPE

will pause until a <cr> is entered.

The TYPE program is small and relatively slow because it buffers only one sector at a time. The larger PIP program can be used for faster displays in the following manner:

```
OA>PIP CON:=MYFILE.TEX
```

FILE DIRECTORY *

The DIR (directory) command causes the names of files on the specified or loggedin disk to be listed on the console device. If no files can be found on the selected diskette which satisfy the directory request, then the message "Not found" is typed at the console.

The DIR command can include files which have the system attribute set. This is done by using the 'S' option. For example:

```
OA>DIR *.COM S
```

RENAME FILE *

The REN (rename) command allows the user to change the name of files on disk. If the destination filename exists the operator is given the option of deleting the current destination file before renaming the source file.

TEXT EDITOR *

The ED (editor) command allows the user to edit ASCII text files.

PERIPHERAL INTERCHANGE PROGRAM *

The PIP (peripheral interchange program) command allows the user to perform disk file and peripheral transfer operations. See the Digital Research document titled "CP/M 2.0 User's Guide for CP/M 1.4 Owners" for a detailed description of new PIP operations.

ASSEMBLER *

The ASM (assembler) command allows the user to assemble the specified program on disk.

SUBMIT *

The SUBMIT command allows the user to submit a file of commands for batch processing.

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STATUS *

The STAT (status) command provides general statistical information about the file storage. See the Digital Research document titled "CP/M 2.0 User's Guide for CP/M 1.4 Owners" for a detailed description of new STAT operations.

DUMP *

The DUMP command types the contents of the specified disk file on the console in hexadecimal form.

LOAD *

The LOAD command reads the specified disk file of type HEX and produces a memory image file of type COM which can subsequently be executed.

GENMOD

The GENMOD command accepts a file which contains two concatenated files of type HEX which are offset from each other by 0100H bytes, and produces a file of type PRL (page relocatable) . The form of the GENMOD command is as follows:

```
1A>genmod b:file.hex b:file.prl $1000
```

The first parameter is the file which contains two concatenated files of type HEX. The second parameter is the name of the destination file of type PRL. The optional third parameter is a specification of additional memory required by the program beyond the explicit code space. The form of the third parameter is a '$' followed by four hex ASCII digits. For example, if the program has been written to use all of 'available' memory for buffers, specification of the third parameter will ensure a minimum buffer allocation.

GENHEX

The GENHEX command is used to produce a file of type HEX from a file of type COM. This is useful to be able to generate HEX files for GENMOD input. The GENHEX command has two parameters, the first is the COM file name and the second is the offset for the HEX file. For example:

```
OA>GENHEX PROG.COM 100
```

PRLCOM

The PRLCOM command accepts a file of PRL type and produces a file of COM type. If the destination COM file exists, a query is made to determine if the file should be deleted before continuing.

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```
OA>prlcom b:program.prl a:program.com
```

DYNAMIC DEBUGGING TOOL *

The DDT (dynamic debugging tool) command loads and executes the MP/M debugger. In systems with banked memory multiple DDT programs can be running concurrently in absolute TPAs. A PRL (relocatable) version of DDT is also provided which enables multiple DDTs to run in a nonbanked system. The name of the relocatable DDT is RDT.

MP/M DDT enhancements are described in Appendix J.

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1.5 Standard Resident System Processes

The standard resident system processes (RSPs) are new programs specifically designed to facilitate use of the MP/M operating system. The RSPs may either be present on disk as files of the PRL type, or they may be resident system processes. Resident system processes are selected at the time of system generation.

SYSTEM STATUS

The MPMSTAT command allows the user to display the runtime status of the MP/M operating system. MPMSTAT is invoked by typing 'MPMSTAT' followed by a <cr>. A sample MPMSTAT output is shown below:

```
****** MP/M Status Display ******

Top of memory = FFFFH
Number of consoles = 02
Debugger breakpoint restart # = 06
Stack is swapped on BDOS calls
Z80 complementary registers managed by dispatcher
Ready Process(es)
     MPMSTAT        Idle
Process(es) DQing:
     [Sched    ]    Sched
     [ATTACH   ]    ATTACH
     [CliQ     ]    cli
Process(es) NQing:
Delayed Process(es):
Polling Process (es)
     PIP
Process(es) Flag Waiting:
     01  Tick
     02  Clock
Flag(s) Set:
     03
Queue(s):
     MPMSTAT        SchedCliQ ATTACH    MXParse
     MXList         [TmpO    ]MXDisk
Process(es) Attached to Consoles:
     [0]  MPMSTAT
     [1]  PIP
Process(es) Waiting for Consoles:
     [0]  TMPO      DIR
     [1]  TMPl
Memory Allocation:
Base = OOOOH        Size = 4000H   Allocated to PIP    [1]
Base = 4000H        Size = 2000H * Free *
Base = 6000H        Size = 1100H   Allocated to DIR    [0]
```


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The MP/M status display is intepreted as follows:

Ready Process (es): The ready processes are those processes which are ready to run and are waiting for the CPU. The list of ready processes is ordered by the priority of the processes and includes the console number at which the process was initiated. The highest priority ready process is the running process.

Process(es) DQing: The processes DQing are those processes which are waiting for messages to be written to the specified queue. The queue name is in brackets followed by the names of processes, in priority order, which have executed read queue operations on the queue.

Process(es) NQing: The processes NQing are those processes which are waiting for an available buffer to write a message to the specified queue. The queue name is in brackets followed by the names of the processes, in priority order, which are waiting for buffers.

Delayed Process(es): The delayed processes are those which are delaying for a specified number of ticks of the system time unit.

Polling Process(es): The polling processes are those which are polling a specified I/O device for a device ready status.

Process(es) Flag Waiting: The processes flag waiting are listed by flag number and process name.

Flag(s) Set: The flags which are set are displayed.

Queue(s): All the queues in the system are listed by queue name. Queue names which are all in capital letters are accessible by command line interpreter input. For example, the SPOOL queue can be sent a message to spool a file by entering 'SPOOL' followed by a file name. Processes DQing from queues which have a name that matches the process name are given the console resource when they receive a message. Queue names that begin with 'MX' are called mutual exclusion queues. The display of a mutual exclusion queue includes the name of the process, if any, which has the mutual exclusion message.

Process(es) Attached to Consoles: The process attached to each console is listed by console number and process name.

Process(es) Waiting for. Consoles: The processes waiting for each console are listed by console number and process name in priority order. They are processes which

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have detached from the console and are then waiting for the

console before they can continue execution.

Memory Allocation: The memory allocation map shows the base, size, bank, and allocation of each memory segment. Segments which are not allocated are shown as '* Free *', while allocated segments are identified by process name and the console in brackets associated with the process. Memory segments which are set as preallocated during system generation by specifying an attribute of OFFH are shown as Reserved

SPOOLER

The SPOOL command allows the user to spool ASCII text files to the list device. Multiple file names may be specified in the command tail. The spooler expands tabs (ctlI characters), assuming tab positions are set at every eighth column.

The spooler queue can be purged at any time by using the STOPSPLR command.

An example of the SPOOL command is shown below:

```
1A>SPOOL LOAD.LST,LETTER.PRN
```

The nonresident version of the spooler (SPOOL.PRL) differs in its operation from the SPOOL.RSP as follows: it uses all of the memory available in the memory segment in which it is running for buffer space; it displays a message indicating its status and then detaches from the console; it may be aborted from a console other than the initiator only by specifying the console number of the initiator as a parameter of the STOPSPLR command.

```
3B>STOPSPLR 2
```

DATE AND TIME

The TOD (time of day) command allows the user to read and set the date and time. Entering 'TOD' followed by a <cr> will cause the current date and time to be displayed on the console. Entering 'TOD' followed by a date and time will set the date and time when a <cr> is entered following the prompt to strike a key. Each of these TOD commands is illustrated below:

```
1A>TOD <cr>

Wed 02/06/?0 09:15:37

or

1A>TOD 2/9/80 10:30:00
```


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```
Strike key to set time

Sat 02/09/80 10:30:00
```

Entering 'TOD P' will cause the current time and date to be continuously displayed until a key is struck at the console.

SCHEDULER

The SCHED (scheduler) command allows the user to schedule a program for execution. Entering 'SCHED' followed by a date, time and command line will cause the command line to be executed when the specified date and time is reached.

In the example shown below, the program 'SAMPLE' will be loaded from disk and executed on February 8, 1980 at 10:30 PM. Note that only hours and minutes are specified, not seconds. Programs are scheduled to the nearest minute.

```
1A>SCHED 2/8/79 22:30 SAMPLE
```

ABORT

The ABORT command allows the user to abort a running program. The program to be aborted is entered as a parameter in the ABORT command.

```
1A>ABORT RDT
```

A program initiated from another console may only be aborted by including its console number as a parameter of the ABORT command.

```
3B>ABORT RDT 1
```


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2. MP/M INTERFACE GUIDE

This section describes MP/M system organization including the structure of memory and system call functions. The intention is to provide the necessary information required to write page relocatable programs and resident system processes which operate under MP/M, and which use the realtime, multitasking, peripheral, and disk I/O facilities of the system.

2.1 Introduction

MP/M is logically divided into several modules. The three primary modules are named the Basic and Extended I/O System (XIOS), the Basic Disk Operating System (BDOS), and the Extended Disk Operating System (XDOS). The XIOS is a hardwaredependent module which defines the exact low level interface to a particular computer system which is necessary for peripheral device I/O. Although a standard XIOS is supplied by Digital Research, explicit instructions are provided for field reconfiguration of the XIOS to match nearly any hardware environment.

MP/M memory structure is shown below:

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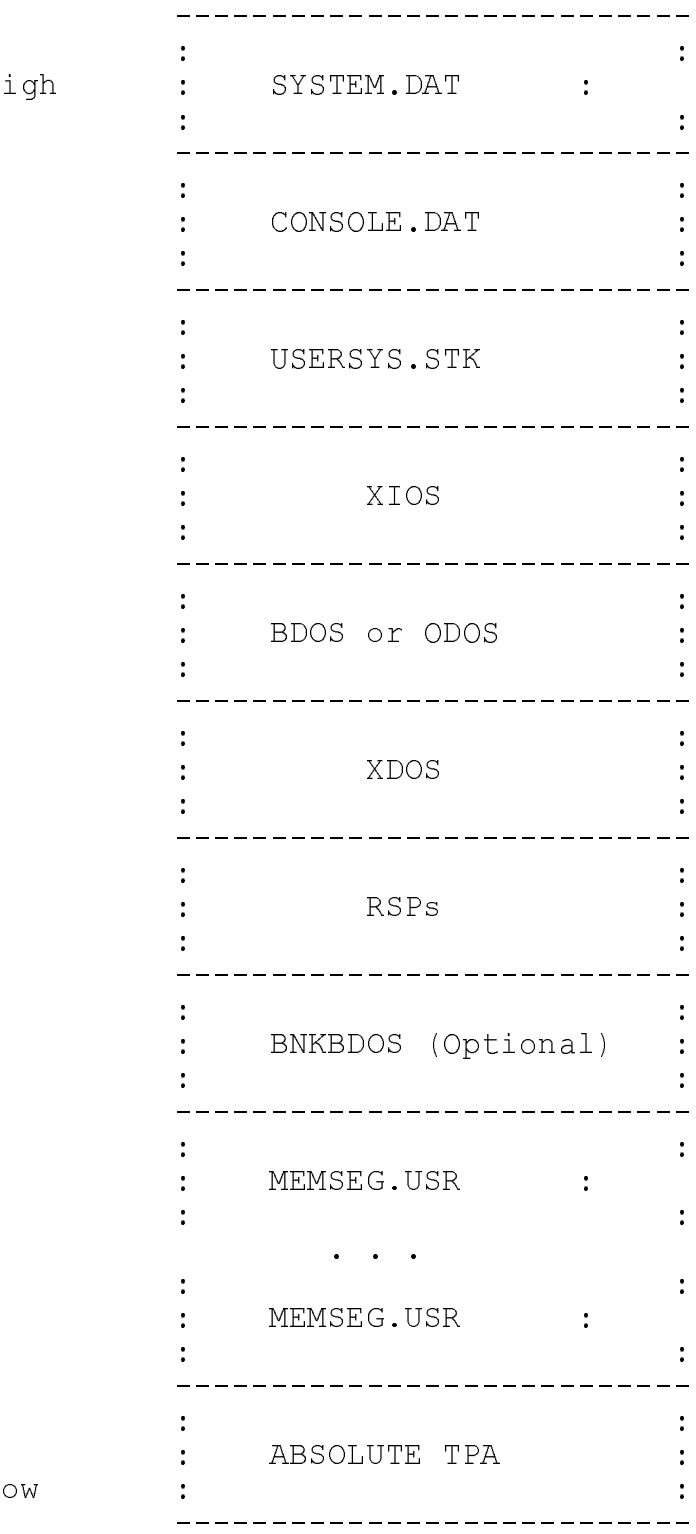

The exact memory addresses for each of the memory segments shown above will vary with MP/M version and depend on the operator specifications made during the system generation process.

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The memory segments are described as follows:

SYSTEM.DAT The SYSTEM.DAT segment contains 256 bytes used by the loader to dynamically configure the system. After loading, the segment is used for storage of system data such as submit flags. See section 3.4 under SYSTEM DATA for a detailed description of the byte allocation.

CONSOLE.DAT The CONSOLE.DAT segment varies in length with the number of consoles. Each console requires 256 bytes which contains the TMP's process descriptor, stack and buffers.

USERSYS.STK The USERSYS.STK segment isoptional depending upon whether or not the user intends to run CP/M *.COM files. This segment contains 64 bytes of stack space per user memory segment and is used as a temporary stack when user programs make BDOS calls. Specification of the option to include this segment is made duringsystem generation. The size of the USERSYS.STK segment varies as follows:

OOOH No user system stacks
100H 1 to 4 memory segments
200H 5 to 8 memory segments

XIOS The XIOS segment contains the user Customized basic and extended I/O system in page relocatable format.

BDOS/ODOS The BDOS segment contains the disk file and multiple console management functions. The segment is about 1400H bytes in length.

The ODOS segment contains the resident portion of the banked BDOS file and console management functions. The segment is about 800H bytes in length.

XDOS The XDOS segment contains the MP/M nucleus and the extended disk operating system. The segment is about 2000H bytes in length.

RSPs The operator makes a selection of Resident System Processes during system generation. The RSPs require varying amounts of memory.

BNKBDOS (Optional) The BNKBDOS segment is present only in systems with a bank switched BDOS. it contains the nonresident portion of the banked BDOS disk file management. This segment is about EOOH bytes in length.

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MEMSEG.USR The user can specifiy 1 to 8 user memory segments during the system generation process. These memory segments may be in the same address space with different bank numbers.

TPA The ABSOLUTE TPA is a user memory segment which is basedat OOOOH. In systems with bank switched memory there may be more than one ABSOLUTE TPA.

Each user memory segment, including the TPA, is further divided into two regions. The first is called the system parameter area. The system parameter area occupies the first 100H bytes of the. memory segment and is defined similarily to that of CP/M. See APPENDIX E for a detailed description of the system parameter area. This area is also called the memory segment base page.

The second region of the user memory segment is the user code area. This area begins at 0100H relative to the base of the memory segment. When a program is loaded, code is placed into the user memory segment beginning at the start of the user code area.

Transient programs are loaded into memory by the Command Line Interpreter (CLI). CLI receives commands from the Terminal Message Process (TMP) which accepts the operator console input. The TMP is a reentrant program which is executed by as many processes as there are system consoles. The operator communicates with the TMP by typing command lines following each prompt. Each command line generally takes one of the forms:

```
command
command file1
command file1 file2
```

where "command" is either a queue such as SPOOL or ATTACH, or the name of a transient command or program.

A brief discussion of CLI operation will describe the loading of transient programs.

When CLI receives a command line it parses the first entry on the command line and then tries to open a queue using the parsed name. If the open queue succeeds the command tail is written to the queue and the CLI operation is finished. If the open queue fails, a file type of PRL is entered for the parsed file name and a file open is attempted. If the file open succeeds then the header of the PRL file is read to determine the memory requirements. A relocatable memory request is made to obtain a memory segment in which to load and run the program. if this request is satisfied the PRL file is read into the memory

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segment, relocated, and it is executed, completing the CLI operation.

If the PRL file type open fails then the file type of COM is entered for the parsed file name and a file open is attempted. If the open succeeds then a memory request is made for an absolute TPA, memory segment based at OOOOH. If this request is satisfied the COM file is read into the absolute TPA and it is executed completing the CLI operation.

If the command is followed by one or two file specifications, the CLI prepares one or two file control block (FCB) names in the system parameter area. These optional FCB's are in the form necessary to access files through MP/M BDOS calls, and are described in the next section.

The CLI creates a process descriptor for each program which is loaded, setting up a 20 level stack which forces a branch to the base of the user code area of the memory segment. The default stack is set up so that a return from the loaded program causes a branch to the MP/M facility which terminates the process. This stack has 19 levels available which can generally be used by the transient program since it is sufficiently large to handle system calls.

The transient program then begins execution, perhaps using the I/O facilities of MP/M to communicate with the operator's console and peripheral devices, including the disk subsystem. The I/O system is accessed by passing a "function number" and an "information address" to MP/M through the entry point at the memory segment base +0005H. In the case of a disk read, for example, the transient program sends the number corresponding to a disk read, along with the address of an FCB to MP/M. MP/M, in turn, performs the operation and returns with either a disk read completion indication or an error number indicating that the disk read was unsuccessful. The function numbers and error indicators are given in sections 2.2 and 2.4,

OPERATING SYSTEM CALL CONVENTIONS

The purpose of this section is to provide detailed information for performing direct operating system calls from user programs. many of the functions listed below, however, are more simply accessed through the I/O macro library provided with the MAC macro assembler, and listed in the Digital Research manual entitled "MAC Macro Assembler: Language manual and Applications Guide."

MP/M facilities which are available for access by transient programs fall into two general categories: simple device I/O, disk file I/O, and the XDOS functions.

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The simple device operations include:

Read/Write a Console Character
Write a List Device Character
Print Console Buffer
Read Console Buffer
Interrogate Console Ready

The BDOS operations which perform disk Input/Output are

Disk System Reset
Drive Selection
File Creation
File Open
File Close
Directory Search
File Delete
File Rename
Random or Sequential Read
Random or Sequential Write
Interrogate Available Disks
Interrogate Selected Disk
Set DMA Address
Set/Reset File Indicators
Reset Drive
Access/Free Drive
Random Write With Zero Fill

The XDOS functions are

Absolute and Relocatable Memory Request
Memory Free
Device Poll
Flag Waiting and Setting
Make Queue
Open Queue
Delete Queue
Read and Conditional Read Queue
Write and Conditional Write Queue
Delay
Dispatch
Terminate and Create Process
Set Priority
Attach and Detach Console
Set and Assign Console
Send CLI Command
Call Resident System Procedure
Parse Filename
Get Console Number
System Data Address
Get Date and Time
Return Process Descriptor Address
Abort Specified Process

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As mentioned above, access to the MP/M functions is

accomplished by passing a function number and information address through the primary entry point at location memory segment base +0005H. In general, the function number is passed in register C with the information address in the double byte pair DE. Single byte values are returned in register A, with double byte values returned in HL (a zero value. is returned when the function number is out of range). For reasons of compatibility, register A = L and register B = H upon return in all cases. Note that the register passing conventions of MP/M agree with those of Intel's PL/M systems programming language.

The list of MP/M BDOS function numbers is given below.

0		System Reset		21	Write Sequential
1		Console Input		22	Make File
2		Console Output		23	Rename File
3	Raw Console Input	24	Return Login Vector		
4	Raw Console Output	25	Return Current Disk		
5		List Output		26	Set DMA Address
6	Direct Console I/O	27	Get Addr(Alloc)		
7		Get I/O Byte		28	Write Protect Disk
8		Set I/O Byte		29	Get R/O Vector
9		Print String		30	Set File Attributes
10	Read Console Buffer	31	Get Addr(Disk Parms)		
11	Get Console Status	32	Set/Get User Code		
12	Return Version Number	33	Read Random		
13	Reset Disk System	34	Write Random		
14		Select Disk		35	Compute File Size
15		Open File		36	Set Random Record
16		Close File	35	Compute File Size	
17	Search for First	36	Set Random Record		
18	Search for Next	37	Reset Drive		
19		Delete File		38	Access Drive
20	Read Sequential	39	Free Drive		
		40	Write Random With Zero Fill		

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The list of MP/M XDOS function numbers is given below.

128	Absolute Memory Rqst	143	Terminate Process
129	Relocatable Mem. Rqst	144	Create Process
130	Memory Free	145	Set Priority
131	Poll	146	Attach Console
132	Flag Wait	147	Detach Console
133	Flag Set	148	Set Console
134	Make Queue	149	Assign Console
135	Open Queue	150	Send CLI Command
136	Delete Queue	151	Call Resident Sys. Proc.
137	Read Queue	152	Parse Filename
138	Cond. Read Queue	153	Get Console Number
139	Write Queue	154	System Data Address
140	Cond. Write Queue	155	Get Date and Time
141	Delay	156	Return Proc. Descr. Adr.
142	Dispatch	157	Abort Specified Process

DISK FILE STRUCTURE

MP/M implements a named file structure on each disk, providing a logical organization which allows any particular file to contain any number of records from completely empty, to the full capacity of the drive. Each drive is logically distinct with a disk directory and file data area. The disk file names are in three parts: the drive select code, the file name consisting of one to eight nonblank characters, and the file type consisting of zero to three nonblank characters. The file type names the generic category of a particular file, while the file name distinguishes individual files in each category. The file types listed below name a few generic categories which have been established, although they are generally arbitrary:

ASM	Assembler Source	PLI	PL/I Source File
PRN	Printer Listing	REL	Relocatable Module
HEX	Hex Machine Code	TEX	TEX Formatter Source
BAS	Basic Source File	BAK	ED Source Backup
INT	Intermediate Code	SYM	SID Symbol File
COM	CCP Command File	$$$	Temporary File
PRL	Page Relocatable	RSP	Resident Sys. Process
SPR	Sys. Page Reloc.	SYS	System File

Source files are treated as a sequence of ASCII characters, where each "line" of the source file is followed by a carriagereturn linefeed sequence (ODH followed by OAH). Thus one 128 byte MP/M record could contain several lines of source text. The end of an ASCII file is denoted by a controlZ character (1AH) or a real end of file (i.e. no more sectors), returned by the MP/M read operation. ControlZ characters embedded within machine code files (e.g., COM files). are ignored, however, and the end of file condition returned by MP/M is used to terminate read operations.

Files in MP/M can be thought of as a sequence of up to

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65536 records of 128 bytes each, numbered from 0 through 65535,

thus allowing a maximum of 8 megabytes per file. Note, however, that although the records may be considered logically contiguous, they are not necessarily physically contiguous in the disk data area. Internally, all files are broken into 16K byte segments called logical extents, so that counters are easily maintained as 8bit values. Although the decomposition into extents is discussed in the paragraphs which follow, they are of no particular consequence to the programmer since each extent is automatically accessed in both sequential and random access modes.

In the file operations starting with function number 15, DE usually addresses a file control block (FCB). Transient programs often use the default file control block area reserved by MP/M at location memory segment base +005CH for simple file operations. The basic unit of file information is a 128 byte record used for all file operations, thus a default location for disk I/O is provided by MP/M at location memory segment base +0080H which is the initial default DMA address (see function 26). All directory operations take place in a reserved area which does not affect write buffers as was the case in CP/M release 1, with the exception of Search First and Search Next, where compatibility is required.

The File Control Block (FCB) data area consists of a sequence of 33 bytes for sequential access and a series of 36 bytes in the case that the file is accessed randomly. The default file control block normally located at memory segment base +005CH can be used for random access files, since the three bytes starting at memory segment base +007DH are available for this purpose.

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The FCB format is shown with the following fields:

```
-------------------------------------------------------------
:dr:f1:f2:/ /:f8:t1:t2:t3:ex:s1:s2:rc:d0:/ /:dn:cr:r0:r1:r2:
-------------------------------------------------------------
 00 01 02 ... 08 09 10 11 12 13 14 15 16 ... 31 32 33 34 35
```

where

dr	drive code (0 16) 0 => use default drive for file 1 => auto disk select drive A, 2 => auto disk select drive B, ... 16=> auto disk select drive P.
fl...f8	contain the file name in ASCII upper case, with high bit = 0
tl,t2,t3	contain the file type in ASCII upper case, with high bit = 0 tl', t2', and t3' denote the bit of these positions, tl' = 1 => Read/only file, t2' = 1 => SYS file, no DIR list t3' = 0 => File has been updated
ex	contains the current extent number, normally set to 00 by the user, but in range 0 31 during file I/O
sl	reserved for internal system use
s2	reserved for internal system use, set to zero on call to OPEN, MAKE, SEARCH
rc	record count for extent "ex" takes on values from 0 - 128
d0..dn	filledin by MP/M, reserved for system use
cr	current record to read or write in a sequential file operation, normally set to zero by user
rO,rl,r2	optional random record number in the range 065535, with overflow to r2, rO,rl constitute a 16bit value with low byte rO, and Iiigh byte rl

Each file beingaccessed through MP/M must have a corresponding FCB which provides the name and allocation

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information for all subsequent file operations. When accessing files, it is the programmer's responsibility to fill the lower sixteen bytes of the FCB and initialize the "cr" field. Normally, bytes 1 through 11 are set to the ASCII character values for the file name and file type, while all other fields are zero.

FCB's are stored in a directory area of the disk, and are brought into central memory before proceeding with file operations (see the OPEN and MAKE functions). The memory copy of the FCB is updated as file operations take place and later recorded permanently on disk at the termination of the file operation (see the CLOSE command).

The CLI constructs the first sixteen bytes of two optional FCB's for a transient by scanning the remainder of the line following the transient name, denoted by "filel" and "file2" in the prototype command line described above, with unspecified fields set to ASCII blanks. The first FCB is constructed at location memory segment base +005CH, and can be used asis for subsequent file operations. The second FCB occupies the dO ... dn portion of the first FCB, and must be moved to another area of memory before use. If, for example, the operator types

```
PROGNAME B:X.ZOT Y.ZAP
```

the file PROGNAME.PRL is loaded into a user memory segment or if it is not on the disk, the file PROGNAME.COM is loaded into the TPA, and the default FCB at memory segment base +005CH is initialized to drive code 2, file name "X" and file type "ZOT". The second drive code takes the default value 0, which is placed at memory segment base +006CH, with the file name "Y" placed into location memory segment base +006DH and file type "ZAP" located 8 bytes later at memory segment base +0075H. All remaining fields through "cr" are set to zero. Note again that it is the programmer's responsibility to move this second file name and type to another area, usually a separate file control block, before opening the file which begins at memory segment base +005CH, due to the fact that the open operation will overwrite the second name and type.

If no file names are specified in the original command, then the fields beginning at memory segment base +005DH and +006DH contain blanks. In all cases, the CLI translates lower case alphabetics to upper case to be consistent with the MP/M file naming conventions.

As an added convenience, the default buffer area at location memory segment base +0080H is initialized to the command line tail typed by the operator following the program name. The first position contains the number of characters, with the characters themselves following the character count.

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Given the above command line, the area beginning at memory segment base +0080H is initialized as follows:

```
     Memory Segment Base +008OH:
     +00 +01 +02 +03 +04 +05 +06 +07 +08 +09 +10 +11 +12 +13 +14
      14 " " "B" ":"  "X" "." "Z" "O" "T" " " "Y" "." "Z" "A" "P"
```

where the characters are translated to upper case ASCII with uninitialized memory following the last valid character. Again, it is the responsibility of the programmer to extract the information from this buffer before any file operations are performed, unless the default DMA address is explicitly changed.

The individual functions are described in detail in the sections which follow.

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2.2 Basic Disk operating System Functions

In general, the Basic Disk Operating System (BDOS) facilities are identical to that of CP/M 2.0. Each function is covered in this section by describing the entry parameters, returned values, and any differences between CP/M and MP/M.

```
****************************************
*                                      *
*    FUNCTION 0: SYSTEM RESET          *
*                                      *
****************************************
*    Entry Parameters:                 *
*       Register    C:   00H           *
****************************************
```

The SYSTEM RESET function terminates the calling program, releasing the memory segment, console, and mutual exclusion messages owned by the calling program. When the console is released it is usually given back to the terminal message process (TMP) for that console.

Effectively the operation of the SYSTEM RESET function is the same for MP/M as it is for CP/M 2.0 because the program is terminated and the operator receives the prompt to enter another command. However, MP/M does not reinitialize the disk subsystem by selecting and loggingin disk drive A.

```
****************************************
*                                      *
*     FUNCTION 1:. CONSOLE INPUT       *
*                                      *
****************************************
*  Entry Parameters:                   *
*      RegisterC:   01H          *
*                                      *
*  Returned         Value:             *
*       Register  A:  ASCII Character *
****************************************
```

The CONSOLE INPUT function reads the next console character to register A. Graphic characters, along with carriage return, line feed, and backspace (ctlH) are echoed to the console. Tab characters (ctlI) are expanded in columns of eight characters. A check is made for start/stop scroll (ctlS) and start/stop printer echo (ctlP). The BDOS does not return to the calling program until a character. has been typed, thus suspending execution if a character is not ready.

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```
*****************************************

*                                       *
*              FUNCTION  2: CONSOLE OUTPUT      *
*                                       *
*****************************************
*    Entry Parameters:                  *
*    Register  C:   02H                 *
*    Register  E:   ASCII Character     *
*                                       *
*****************************************
```

The ASCII character from registerE is sent to the console device. Similar to function 1, tabs are expanded and checks are made for start/stop scroll and printer echo.

```
*****************************************
*                                       *
*    FUNCTION 3: RAW CONSOLE INPUT      *
*****************************************
*    Entry Parameters:                  *
*    Register  C:   03H                 *
*                                  *
*   Returned   Value:                   *
*   Register   A:   ASCII Character     *
*****************************************
```

The RAW CONSOLE INPUT function reads the next console character to Register A. There is no testing of the input character, that is, the system wi11 directly pass through all characters including the control characters without any interpretation. This function does not require that the console be attached, nor does it attach the console.

The READER INPUT function is not supported under MP/M. All character I/O devices such as the reader/punch are treated as consoles. MP/M supports up to 16 consoles or character I/O devices.

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```
*****************************************

*                                       *
*  FUNCTION 4: RAW CONSOLE OUTPUT       *
*                                       *
*****************************************
*  Entry Parameters:                    *
*  Register    C: 04H                   *
*  Register    E: ASCII Character       *
*                                       *
*****************************************
```

The RAW CONSOLE OUTPUT function sends the ASCII character from register E to the console device. There is no testing of the output character, that is, tabs are not expanded and no checks are made for start/stop scroll and printer echo. This function does not require that the console be attached, nor does it attach the console. Thus, unsolicited messages may be sent to other consoles by simply changing the console byte of the process descriptor and then using this function.

The PUNCH OUTPUT function is not supported under MP/M.

```
*****************************************
*                                       *
*   FUNCTION 5: LIST OUTPUT             *
*                                       *
*****************************************
*   Entry Parameters:                   *
*   Register   C: 05H                   *
*   Register   E: ASCII Character       *
*                                       *
*****************************************
```

The LIST OUTPUT function sends the ASCII character in register E to the logical listing device.

Caution must be observed in the use of the printer since there is no implicit list device ownership. That is, the list device is not "opened" or "closed". MP/M affords a secondary explicit means to resolve printer mutual exclusion. A queue named 'MXList' is created by the system to handle mutual exclusion. To properly obtain use of the printer a program should open the 'MXList' queue and read the message. When the message is obtained the printer may be used. When printing is completed the message should be written back to the 'MXList' queue. This technique is used by the MP/M PIP, SPOOLer, and TMP ctlP operations.

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```
*****************************************

*                                       *
*   FUNCTION 6: DIRECT CONSOLE I/O      *
*                                       *
*****************************************
*   Entry Parameters:                   *
*   Register   C:   06H                 *
*   Register        E:   OFFH (input) or   *
*                                0FEH (status)or   *
*                                char (output)     *
*                                   *
*   Returned   Value:               *
*   Register   A:   char or status  *
*                                (no value)        *
*****************************************
```

Direct console I/O is supported under MP/M for those specialized applications where unadorned console input and output is required. Use of this function should, in general, be avoided since it bypasses all of MP/M's normal control character functions (e.g., controlS and controlP) . Programs which perform direct I/O through the BIOS under previous releases of CP/M, however, should be changed to use direct I/O under BDOS so that they can be fully supported under MP/M and CP/M.

Upon entry to function 6, register E either contains hexadecimal FF, denoting a console input request, a hexadecimal FE, denoting a console input status request, or register E contains an ASCII character. If the input value is FF, then function 6 returns the next console input character.

If the input value is FE, then function 6 returns a value of FF if a character is ready, or a 00 if no character has been received.

If the input value in E is not FF or FE, then function 6 assumes that E contains a valid ASCII character which is sent to the console.

Note that BDOS functions 3 and 4 (raw console input/output) can be used for totally transparent console I/O. When using functions 3 and 4, the console status operation can be performed by using function 6 with a parameter of FE.

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```
*****************************************

*                                       *
*  FUNCTION 7: GET I/O BYTE             *
*                                       *
*****************************************
*                                       *
*  Not supported under MP/M             *
*                                       *
*****************************************
```

The GET I/O BYTE function is not supported under MP/M.

```
*****************************************
*                                       *
*  FUNCTION 8: SET I/O BYTE             *
*                                       *
*****************************************
*                                       *
*  Not supported under MP/M             *
*                                       *
*****************************************
```

The SET I/O BYTE function is not supported under MP/M.

```
*****************************************
*                                       *
*  FUNCTION 9: PRINT STRING             *
*                                       *
*****************************************
*                                       *
*  Entry Parameters:                    *
*  Register    C: 09H                   *
*  Registers DE: String Address         *
*                                       *
*****************************************
```

The PRINT STRING function sends the character string stored in memory at the location given by DE to the console device, until a "$" is encountered in the string. Tabs are expanded as in function 2, and checks are made for start/stop scroll and printer echo.

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```
*****************************************

*                                       *
*   FUNCTION 10: READ CONSOLE BUFFER    *
*                                       *
*****************************************
*  Entry Parameters:                    *
*     Register    C: OAH                *
*     Registers DE: Buffer Address      *
*                                       *
*  Returned         Value:              *
*     Console Characters in Buffer      *
*****************************************
```

The READ BUFFER function reads a line of edited console input into a buffer addressed by registers DE. Console input is terminated when either the input buffer overflows. The READ BUFFER takes the form:

```
DE: +0 +1 +2 +3 +4 +5 +6 +7 +8    . . .   +n
   ----------------------------------------
   :mx:nc:c1:c2:c3:c4:c5:c6:c7:   . . .  :??:
   ----------------------------------------
```

where "mx" is the maximum number of characters which the buffer will hold (1 to 255), "nc" is the number of characters read (set by BDOS upon return), followed by the characters read from the console. if nc < mx, then uninitialized positions follow the last character, denoted by "??" in the above figure. A number of control functions are recognized during line editing:

```
rub/del   removes and echoes the last character
ctlC reboots when at the beginning of line
ctlE causes physical end of line
ctlH backspaces one character position
ctlJ (line feed) terminates input line
     ctlM (return) terminates input line
     ctlR retypes the current line after new line
     ctlU removes current line after new line
     ctlX backspaces to beginning of current line
```

Note also that certain functions which return the carriage to the leftmost position (e.g., ctlX) do so only to the column position where the prompt ended (in earlier releases, the carriage returned to the extreme left margin). This convention makes operator data input and line correction more legible.

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```
*****************************************

*                                       *
*   FUNCTION 11: GET CONSOLE STATUS     *
*                                       *
*****************************************
*   Entry Parameters:                   *
*      RegisterC:   OBH                 *
*                                       *
*   Returned   Value:                   *
*   Register   A:   Console Status      *
*****************************************
```

The CONSOLE STATUS function checks to see if a character has been typed at the console. If a character is ready, the value OFFH is returned in register A. Otherwise a OOH value is returned.

```
*****************************************
*                                       *
*  FUNCTION 12: RETURN VERSION NUMBER   *
*                                       *
*****************************************
*   Entry Parameters:                   *
*     Register C:   OCH                 *
*                                       *
*  Returned    Value:                   *
*  Registers HL: Version Number         *
*****************************************
```

Function 12 provides information which allows version independent programming. A twobyte value is returned, with H = 00 designating the CP/M release (H = 01 for MP/M), and L = 00 for all releases previous to 2.0. CP/M 2.0 returns a hexadecimal 20 in register L, with subsequent version 2 releases in the hexadecimal range 21, 22, through 2F. Using function 12, for example, you can write application programs which provide both sequential and random access functions, with random access disabled when operating under early releases of CP/M.

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```
*****************************************

*                                       *
*   FUNCTION 13: RESET DISK SYSTEM      *
*                                       *
*****************************************
*   Entry Parameters:                   *
*     Register C:   ODH                 *
*                                       *
*   Returned Value:                     *
*   Register   A:   Return Code         *
*****************************************
```

The RESET DISK function is used to programmatically restore the file system to a reset state where all disks are set to read/write (see functions 28 and 29), and the default DMA address is reset to the memory segment base +0080H. This function can be used, for example, by an application program which requires a disk change without a system reboot.

The RESET DISK SYSTEM function is qualified in MP/M. if there are any open files on any drive, the reset disk system is denied and the reason is displayed on the console. The returned value indicates whether or not the reset disk was successful. If any process is currently accessing a drive, an error code of OFFH is returned in the A register. A return code of 0 indicates success.

```
*****************************************
*                                       *
*   FUNCTION 14: SELECT DISK            *
*                                       *
*****************************************
*  Entry Parameters:                    *
*                                       *
*   Register   C:   OEH                 *
*   Register   E:   Selected Disk       *
*                                       *
*****************************************
```

The SELECT DISK function designates the disk drive named in register E as the default disk for subsequent file operations, with E = 0 for drive A, 1 for drive B, and soforth through 15 corresponding to drive P in a full sixteen drive system. The drive is placed in an "online" status which, in particular, activates its directory until the next cold start, warm start, or disk system reset operation. If the disk media is changed while it is online, the drive automatically goes to a read/only status in a standard MP/M environment (see function 28). FCB's which specify drive code zero (dr = OOH) automatically reference the

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currently selected default drive. Drive code values between 1 and 16, however, ignore the selected default drive and directly reference drives A through P.

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```
*****************************************

*                                       *
*   FUNCTION 15: OPEN FILE              *
*                                       *
*****************************************
*   Entry Parameters:                   *
*   Register   C:   OFH                 *
*   Registers DE: FCB Address           *
*                                       *
*    Returned  Value:                   *
*    Register  A:   Directory Code      *
*****************************************
```

The OPEN FILE operation is used to activate a file which currently exists in the disk directory for either the currently active user code or user code 0. The BDOS scans the referenced disk directory for a match in positions 1 through 14 of the FCB referenced by DE (byte s1 is automatically zeroed), where an ASCII question mark (3FH) matches any directory character in any of these positions. Normally, no question marks are included and, further, bytes "ex" and "s2" of the FCB are zero.

If a directory element is matched, the relevant directory information is copied into bytes d0 through dn of the FCB, thus allowing access to the files through subsequent read and write operations. Note that an existing file must not be accessed until a sucessful open operation is completed. Upon return, the open function returns a "directory code" with the value 0 through 3 if the open was successful, or OFFH (255 decimal) if the file cannot be found. If question marks occur in the FCB then the first matching FCB is activated. Note that the current record ("cr") must be zeroed by the program if the file is to be accessed sequentially from the first record.

The openfile operation will succeed for files with either the current user code or user code 0. This presents a problem when files with the same name exist under both the current user code and under user code 0. When such a situation exists the first one found in the directory will be opened. Even though this should not present a problem because user code 0 is intended only for system and commonly used files, a potential problem can be detected by using the search file function. The search file function enables examination of the directory FCB and thus the actual file user code can be determined.

Opening a file sets the appropriate bit in the drive active vector of the calling processes process descriptor. This bit is cleared only by terminating the process or making a free drive (function 39) call. Setting of the bit in the drive active vector will prevent any other process from resetting the drive on which the file was opened.

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```
*****************************************

*                                       *
*   FUNCTION 16: CLOSE FILE             *
*                                       *
*****************************************
*   Entry Parameters:                   *
*     Register C:   10H                 *
*     Registers DE: FCB Address         *
*                                       *
*  Returned    Value:                   *
*  Register    A:   Directory Code      *
*****************************************
```

The CLOSE FILE function performs the inverse of the open file function. Given that the FCB addressed by DE has been previously activated through an open or make function (see functions 15 and 22), the close function permanently records the new FCB in the referenced disk directory. The FCB matching process for the close is identical to the open function. The directory code returned for a successful close operation is 0, 1, 2, or 3, while a OFFH (255 decimal) is returned if the file name cannot be found in the directory. A file need not be closed if only read operations have taken place. If write operations have occurred, however, the close operation is necessary to permanently record the new directory information.

Note that the close file function does not affect the drive active vector of the calling processes process descriptor. The free drive function (function 39) must be used to reset the bit of the drive active vector.

```
*****************************************
*                                       *
* FUNCTION 17: SEARCH FOR FIRST         *
*                                       *
*****************************************
* Entry Parameters:                     *
*    Register  C:   11H                 *
*    Registers DE: FCB Address          *
*                                       *
*    Returned  Value:                   *
*    Register  A:   Directory Code      *
*****************************************
```

SEARCH FIRST scans the directory for a match with the file given by the FCB addressed by DE. Files with either the currently active user code or user code 0 will match. The value 255 (hexadecimal FF) is returned if the file is not found, otherwise 0, 1, 2, or 3 is returned indicating the file is present. In the case that the file is found, the current DMA

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address is filled with the record containing the directory entry, and the relative starting position is A * 32 (i.e., rotate the A

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register left 5 bits, or ADD A five times). Although not normally required for application programs, the directory information can be extracted from the buffer at this position.

An ASCII question mark (63 decimal, 3F hexadecimal) in any position from "fl" through "ex" matches the corresponding field of any directory entry on the default or autoselected disk drive. If the "dr" field contains an ASCII question mark, then the auto disk select function is disabled, the default disk is searched, with the search function returning any matched entry, allocated or free, belonging to any user number. This latter function is not normally used by application programs, but does allow complete flexibility to scan all current directory values. If the "dr" field is not a question mark, the "s2" byte is automatically zeroed.

To determine the user code of a successful search (it may be the currently active user code or user code 0), the returned directory code can be used as described above to index into the DMA buffer and the user code of the directory FCB can be obtained.

```
****************************************
*                                      *
* FUNCTION 18: SEARCH FOR NEXT         *
*                                      *
****************************************
* Entry Parameters:                    *
* Register     C:   12H                *
*                                      *
* ReturnedValue:                       *
* RegisterA:   Directory Code          *
****************************************
```

The SEARCH NEXT function is similar to the Search First function, except that the directory scan continues from the last matched entry. Similar to function 17, function 18 returns the decimal value 255 in A when no more directory items match.

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```
*****************************************

*                                       *
* FUNCTION 19: DELETE FILE              *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   13H                *     
* Registers DE: FCB Address             *
*                                       *
* Returned     Value:                   *
* RegisterA:   Directory Code     *     
*****************************************
```

The DELETE FILE function removes files which match the FCB addressed by DE. The filename and type may contain ambiguous references (i.e., question marks in various positions), but the drive select code cannot be ambiguous, as in the Search and Search Next functions.

Function 19 returns a decimal 255 if the referenced file or files cannot be found, otherwise a value in the range 0 to 3 is returned.

```
*****************************************
*                                       *
* FUNCTION 20: READ SEQUENTIAL          *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   14H                *     
* Registers DE: FCB Address             *
*                                       *
* Returned     Value                    *
* RegisterA:   Directory Code     *     
*****************************************
```

Given that the FCB addressed by DE has been activated through an open or make function (numbers 15 and 22), the READ SEQUENTIAL function reads the next 128 byte record from the file Into memory at the current DMA address. The record is read from position "cr" of the extent, and the "cr" field is automatically Incremented to the next record position. If the "cr" field overflows then the next logical extent is automaticall1y opened and the “cr" field is reset to zero in preparation for the next read operation. The value 00H is returned in the A register if the read operation was successful, while a nonzero value is returned if no data exists at the next record position (e.g. end of file occurs).

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```
*************************************

*                                   *
* FUNCTION 21: WRITE SEQUENTIAL     *
*                                   *
*************************************
* Entry Parameters:                 *
* RegisterC:   15H                  *
* Registers DE: FCB Address         *
*                                   *
* ReturnedValue:                    *
* RegisterA:   Directory Code       *
*************************************
```

Given that the FCB addressed by DE has been activated through an open or make function (numbers 15 and 22), the WRITE SEQUENTIAL function writes the 128 byte data record at the current DMA address to the file named by the FCB. the record is placed at position "cr" of the file, and the "cr" field is automatically incremented to the next record position. If the "cr" field overflows then the next logical extent is automatically opened and the "cr" field is reset to zero in preparation for the next write operation. Write operations can take place into an existing file, in which case newly written records overlay those which already exist in the file. Register A = OOH upon return from a successful write operation, while a nonzero value indicates a full disk.

```
*************************************
*                                   *
* FUNCTION 22: MAKE FILE            *
*                                   *
*************************************
* Entry Parameters:                 *
* RegisterC:   16H                  *
* Registers DE: FCB Address         *
*                                   *
* ReturnedValue:                    *
* RegisterA:   Directory Code       *
*************************************
```

The MAKE FILE operation is similar to the open file operation except that the FCB must name a file which does not exist in the currently referenced disk directory (i.e., the one named explicitly by a nonzero "dr" code, or the default disk if "dr" is zero). The FDOS creates the file and initializes both the directory and main memory value to an empty file. The programmer must ensure that no duplicate file names occur, and a preceding delete operation is sufficient if there is any possibility of duplication. Upon return, register A = 0, 1, 2,

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or 3 if the operation was successful and OFFH (255 decimal) if no more directory space is available. The make function has the sideeffect of activating the FCB and thus a subsequent open is

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not necessary.

Making a file sets the appropriate bit in the drive active vector of the calling processes process descriptor. This bit is cleared only by terminating the process or making a free drive (function 39) call. Setting of the bit in the drive active vector will prevent any other process from resetting the drive on which the file was opened.

```
****************************************
*                                      *
* FUNCTION 23: RENAME FILE             *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   17H                     *
* Registers DE: FCB Address            *
*                                      *
* ReturnedValue:                       *
* RegisterA:   Directory Code          *
****************************************
```

The RENAME FILE function uses the FCB addressed by DE to change all occurrences of the file named in the first 16 bytes to the file named in the second 16 bytes. The drive code "dr" at position 0 is used to select the drive, while the drive code for the new file name at position 16 of the FCB is assumed to be zero. Upon return, register A is set to a value between 0 and 3 if the rename was successful, and OFFH (255 decimal) if the first file name could not be found in the directory scan.

```
****************************************
*                                      *
* FUNCTION 24: RETURN LOGIN VECTOR     *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   18H                     *
*                                      *
* ReturnedValue:                       *
* Registers HL: Login Vector           *
****************************************
```

The login vector value returned by MP/M is a 16bit value in HL, where the least significant bit of L corresponds to the first drive A, and the high order bit of H corresponds to the sixteenth drive, labelled P. A "0" bit indicates that the drive is not online, while a "l" bit marks an drive that is actively

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online due to an explicit disk drive selection, or an implicit drive select caused by a file operation which specified a nonzero "dr" field. Note that compatibility is maintained with

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earlier releases, since registers A and L contain the same values upon return.

```
****************************************
*                                      *
* FUNCTION 25: RETURN CURRENT DISK     *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   19H                     *
*                                      *
* ReturnedValue:                       *
* RegisterA:   Current Disk            *
****************************************
```

Function 25 returns the currently selected default disk number in register A. The disk numbers range from 0 through 15 corresponding to drives A through P.

```
****************************************
*                                      *
* FUNCTION 26: SET DMA ADDRESS         *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   1AH                     *
* Registers DE: DMA Address            *
****************************************
```

"DMA" is an acronym for Direct Memory Address, which is often used in connection with disk controllers which directly access the memory of the mainframe computer to transfer data to and from the disk subsystem. Although many computer systems use nonDMA access (i.e., the data is transfered through programmed I/O operations), the DMA address has, in MP/M, come to mean the address at which the 128 byte data record resides before a disk write and after a disk read. Upon cold start, warm start, or disk system reset, the DMA address is automatically set to BOOT+0080H. The Set DMA function, however, can be used to change this default value to address another area of memory where the data records reside. Thus, the DMA address becomes the value specified by DE until it is changed by a subsequent Set DMA function, cold start, warm start, or disk system reset.

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```
*****************************************

*                                       *
* FUNCTION 27: GET ADDR(ALLOC)          *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   1BH                *     *
*                                       *
* ReturnedValue:                  *     *
* Registers HL: ALLOC Address           *
*****************************************
```

An "allocation vector" is maintained in main memory for each online disk drive. Various system programs use the information provided by the allocation vector to determine the amount of remaining storage (see the STAT program). Function 27 returns the base address of the allocation vector for the currently selected disk drive. The allocation information may, however, be invalid if the selected disk has been marked read/only. Although this function is not normally used by application programs, additional details of the allocation vector are found in the "CP/M 2.0 Alteration Guide."

```
*****************************************
*                                       *
* FUNCTION 28: WRITE PROTECT DISK       *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   1CH                *     *
*                                       *
*****************************************
```

The disk write protect function provides temporary write protection for the currently selected disk. Any attempt to write to the disk, before the next cold or warm start operation produces the message

Bdos Err on d: R/O

Use of this function is not recommended while operating under MP/M because it will deny read/write access to files on the disk by another user.

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```
*****************************************

*                                       *
* FUNCTION 29: GET READ/ONLY VECTOR     *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   1DH                *     *
*                                       *
* ReturnedValue:                  *     *
* Registers HL: R/O Vector Value        *
*****************************************
```

Function 29 returns a bit vector in register pair HL which indicates drives which have the temporary read/only bit set. Similar to function 24, the least significant bit corresponds to drive A, while the most significant bit corresponds to drive P. The R/O bit is set either by an explicit call to function 28, or by the automatic software mechanisms within MP/M which detect changed disks.

```
*****************************************
*                                       *
* FUNCTION 30: SET FILE ATTRIBUTES      *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   1EH                *     *
* Registers DE: FCB Address             *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Directory Code     *     *
*****************************************
```

The SET FILE ATTRIBUTES function allows programmatic manipulation of permanent indicators attached to files. In particular, the R/0, System, and Update attributes (tl', t2', and t3') can be set or reset. The DE pair addresses an unambiguous file name with the appropriate attributes set or reset. Function 30 searches for a match, and changes the matched directory entry to contain the selected indicators. Indicators fl' through f4' are not presently used, but may be useful for applications programs, since they are not involved in the matching process during file open and close operations. Indicators f5' through f8' are reserved for future system expansion.

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```
*****************************************

*                                       *
* FUNCTION 31: GET ADDR(DISK PARMS)     *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   1FH                *     *
*                                       *
* ReturnedValue:                  *     *
* Registers HL: DPB Address             *
*****************************************
```

The address of the BIOS resident disk parameter block is returned in HL as a result of this function call. This address can be used for either of two purposes. First, the disk parameter values can be extracted for display and space computation purposes, or transient programs can dynamically change the values of current disk parameters when the disk environment changes, if required. Normally, application programs will not require this facility.

```
*****************************************
*                                       *
* FUNCTION 32: SET/GET USER CODE        *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   20H                *     *
* RegisterE:   OFFH (get) or      *     *
*                   User Code (set)     *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Current Code or    *     *
*                   (no value)          *
*****************************************
```

An application program can change or interrogate the currently active user number by calling function 32. If register E = OFFH, then the value of the current user number is returned in register A, where the value is in the range 0 to 15. If register E is not OFFH, then the current user number is changed to the value of E (modulo 16) .

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```
*****************************************

*                                       *
* FUNCTION 33: READ RANDOM              *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   21H                *     *
* Registers DE: FCB Address             *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return Code        *     *
*****************************************
```

The READ RANDOM function is similar to the sequential file Read operation of previous releases, except that the read operation takes place at a particular record number, selected by the 24bit value constructed from the three byte field following the FCB (byte positions rO at 33, rl at 34, and r2 at 35). Note that the sequence of 24 bits is stored with least significant byte first (rO) middle byte next (rl), and high byte last (r2). MP/M does not reference byte r2, except in computing the size of a file (function 35). Byte r2 must be zero, however, since a nonzero value indicates overflow past the end of file.

Thus, the r0,rl byte pair is treated as a doublebyte, or "word" value, which contains the record to read. This value ranges from 0 to 65535, providing access to any particular record of the 8 megabyte file. In order to process a file using random access, the base extent (extent 0) must first be opened. Although the base extent may or may not contain any allocated data, this ensures that the file is properly recorded in the directory, and is visible in DIR requests. The selected record number is then stored into the random record field (rO,rl), and the BDOS is called to read the record. Upon return from the call, register A either contains an error code, as listed below, or the value 00 indicating the operation was successful. In the latter case, the current DMA address contains the randomly accessed record. Note that contrary to the sequential read operation, the record number is not advanced. Thus, subsequent random read operations continue to read the same record.

Upon each random read operation, the logical extent and current record values are automatically set. Thus, the file can be sequentially read or written, starting from the current randomly accessed position. Note, however, that in this case, the last randomly read record will be reread as you switch from random mode to sequential read, and the last record will be rewritten as you switch to a sequential write operation. You can, of course, simply advance the random record position following each random read or write to obtain the effect of a sequential I/O operation.

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Error codes returned in register A following a random read

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are listed below.

```
          01        reading unwritten data
          02        (not returned in random mode)
          03        cannot close current extent
          04        seek to unwritten extent
          05        (not returned in read mode)
          06        seek past physical end of disk
```

Error code 01 and 04 occur when a random read operation accesses A data block which has not been previously written, or an extent which has not been created, which are equivalent conditions. Error 3 does not normally occur under proper system operation, but can be cleared by simply rereading, or reopening extent zero as long as the disk is not physically write protected. Error code 06 occurs whenever byte r2 is nonzero under the current 2.0 release. Normally,nonzero return codes can be treated as missing data, with zero return codes indicating operation complete.

```
*****************************************
*                                       *
* FUNCTION 34: WRITE RANDOM             *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   22H                      *
* Registers DE: FCB Address             *
*                                       *
* ReturnedValue:                        *
* RegisterA:   Return Code              *
*****************************************
```

The WRITE RANDOM operation is initiated similar to the READ RANDOM call, except that data is written to the disk from the current DMA address. Further, if the disk extent or data block which is the target of the write has not yet been allocated, the allocation is performed before the write operation continues. As in the Read Random operation, the random record number is not changed as a result of the write. The logical extent number and current record positions of the file control block are set to correspond to the random record which is being written. Again, sequential read or write operations can commence following a random write, with the notation that the currently addressed record is either read or rewritten again as the sequential operation begins. You can also simply advance the random record position following each write to get the effect of a sequential write operation. Note that in particular, reading or writing the last record of an extent in random mode does not cause an automatic extent switch as it does in sequential mode.

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The error codes returned by a random write are identical to

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the random read operation with the addition of error code 05,

which indicates that a new extent cannot be created due to directory overflow.

```
****************************************
*                                      *
* FUNCTION 35: COMPUTE FILE SIZE       *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   23H                     *
* Registers DE: FCB Address            *
*                                      *
* ReturnedValue:                       *
* Random Record Field Set              *
****************************************
```

When computing the size of a file, the DE register pair addresses an FCB in random mode format (bytes rO, rl, and r2 are present). The FCB contains an unambiguous file name which is used in the directory scan. Upon return, the random record bytes contain the "virtual" file size which is, in effect, the record address of the record following the end of the file. if, following a call to function 35, the high record byte r2 is 01, then the file contains the maximum record count 65536. otherwise; bytes rO and rl constitute a 16bit value (rO is the least significant byte, as before) which is the file size.

Data can be appended to the end of an existing file by simply calling function 35 to set the random record position to the end of file, then performing a sequence of random writes starting at the preset record address.

The virtual size of a file corresponds to the physical size when the file is written sequentially. If, instead, the file was created in random mode and "holes" exist in the allocation, then the file may in fact contain fewer records than the size indicates. If, for example, only the last record of an eight megabyte file is written in random mode (i.e., record number 65535), then the virtual size is 65536 records, although only one block of data is actually allocated.

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```
*****************************************

*                                       *
* FUNCTION 36: SET RANDOM RECORD        *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   24H                *     *
* Registers DE: FCB Address             *
*                                       *
* ReturnedValue:                  *     *
* Random Record Field Set               *
*****************************************
```

The SET RANDOM RECORD function causes the BDOS to automatically produce the random record position from a file which has been read or written sequentially to a particular point. The function can be useful in two ways.

First, it is often necessary to initially read and scan a sequential file to extract the positions of various "key" fields. As each key is encountered, function 36 is called to compute the random record position for the data corresponding to this key. If the data unit size is 128 bytes, the resulting record position is placed into a table with the key for later retrieval. After scanning the entire file and tabularizing the keys and their record numbers, you can move instantly to a particular keyed record by performing a random read using the corresponding random record number which was saved earlier. The scheme is easily generalized when variable record lengths are involved since the program need only store the bufferrelative byte position along with the key and record number in order to find the exact starting position of the keyed data at a later time.

A second use of function 36 occurs when switching from a sequential read or write over to random read or write. A file is sequentially accessed to a particular point in the file, function 36 is called which sets the record number, and subsequent random read and write operations continue from the selected point in the file.

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```
*****************************************

*                                       *
* FUNCTION 37: RESET DRIVE              *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   25H                *     *
* Register DE: Drive Vector             *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return Code        *     *
*****************************************
```

The RESET DRIVE function allows resetting of specified drive(s). The passed parameter is a 16 bit vector of drives to be reset, the least significant bit is drive A:. If there are any open files on a specified drive, the reset drive is denied and the reason is displayed on the console.

The returned value indicates whether or not the reset drive was successful. If any process is currently accessing a drive to be reset, an error code of OFFH is returned in the A register. A return code of 0 indicates success.

```
*****************************************
*                                       *
* FUNCTION 38: ACCESS DRIVE             *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   26H                *     *
* Register DE: Drive Vector             *
*                                       *
*****************************************
```

The ACCESS DRIVE function allows setting the drive access bit(s) in the calling processes process descriptor. The passed parameter is a 16 bit vector of drive(s) to be accessed, the least significant bit is drive A:.

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```
*****************************************

*                                       *
* FUNCTION 39: FREE DRIVE                 *
*                                         *
*****************************************
* Entry Parameters:                       *
* RegisterC:   27H                *       *
* RegisterDE:  Drive Vector       *       *
*                                         *
*****************************************
```

The FREE DRIVE function allows freeing the drive access bit(s) in the calling processes process descriptor. The passed parameter is a 16 bit vector of drive(s) to be freed, the least significant bit is drive A:.

```
*****************************************
*                                       *
* FUNCTION 40: WRITE RANDOM WITH          *
*                  ZERO FILL              *
*****************************************
* Entry Parameters:                       *
* RegisterC:   28H                *       *
* RegisterDE:  FCB Address        *       *
*                                         *
* Returned Value:                         *
* RegisterA:   Return Code        *       *
*****************************************
```

The WRITE RANDOM WITH ZERO FILL operation is similar to FUNCTION 34: WRITE RANDOM with the exception that a previously unallocated record is filled with zeroes before the data is written.

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2.3 Queue and Process Descriptor Data Structures

This section contains a description of the queue and process descriptor data structures used by the MP/M Extended Disk Operating System (XDOS) .

QUEUE DATA STRUCTURES

A queue is a first in first out (FIFO) mechanism which has been implemented in MP/M to provide several essential functions in a multitasking environment. Queues can be used for the communication of messages between processes, to synchronize processes, and to provide mutual exclusion.

MP/M has been designed to simplify queue management for both user and system processes. In fact, queues are treated in a manner similar to disk files. Queues can be created, opened, written to, read from, and deleted.

A few illustrations should suffice to describe applications for queues:

COMMUNICATION:

A queue can be used for communication to provide a FIFO list of messages produced by a producer for consumption by a consumer. For example, consider a data logging application where data is continuously received via a serial communication link and is to be written to a disk file. This would be a difficult application for a sequential operating system such as CP/M because arriving serial data would be lost while buffers were being written to disk. Under MP/M a queue could be used by the producer to send blocks of received serial data (or simply buffer pointers) to a consumer which would write the blocks on disk. MP/M supports concurrency of these operations, allowing the producer to quickly write a buffer to the queue and then resume monitoring the serial input.

SYNCHRONIZATION:

When a process attempts to read a message at a queue and there are no messages posted at the queue, the process is placed in a priority ordered list of processes waiting for messages at the queue. The process will remain in that state until a message arrives. Thus synchronization of processes can be achieved, allowing the waiting (DQing) process to continue execution when a message is sent to the queue.

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MUTUAL EXCLUSION:

A queue can also be used for mutual exclusion. Mutual exclusion messages generally have a length of zero. A good example of mutual exclusion is that which is used by MP/M to control access to the printer. A queue is created (MXList) and sent one message. When the printer is to be used by the spooler or by entering a controlP (^P) at the console an attempt is made to read the message from the list mutual exclusion queue. This attempt is made using the MP/M conditional read queue function. If the message is available, that is it has not been consumed by some other process, it is read and the printer is used. When finished with the printer, the message is written back to the list mutual exclusion queue. If the message is not available the user who entered the ^P receives a message indicating that the printer is busy. In the case of the spooler, it waits until the printer is available before continuing.

QUEUE DATA STRUCTURES

The queue data structures include the queue control block and the user queue control block. There are two types of queue control blocks, circular or linked. The type of queue control block used depends upon the message size. Message sizes of 0 to 2 bytes use circular queues while message sizes of 3 or more bytes use linked queues.

CIRCULAR QUEUES

The following example illustrates how to setup a queue control block for a circular queue with 80 messages of a one byte length. Each example in this section will be shown both in PL/M and assembly language.

PL/M:

```
DECLARE CIRCULAR$QUEUE STRUCTURE (
     QL ADDRESS,
     NAME(8) BYTE,
     MSGLEN ADDRESS,
     NMBMSGS ADDRESS,
     DQPH ADDRESS,
     NQPH ADDRESS,
     MSG$IN ADDRESS,
     MSG$OUT ADDRESS,
     MSG$CNT ADDRESS,
     BUFFER (80) BYTE         )
     INITIAL (0,'CIRCQUE ', 1,80);
```


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Assembly Language:

```
          CRCQUE:
               DS        2    QL
               DB        'CIRCQUE '; NAME
               DW        1    MSGLEN
               DW        80   NMBMSGS
               DS        2    DQPH
               DS        2    NQPH
               DS        2    MSGIN
               DS        2    MSGOUT
               DS        2    MSGCNT
     BUFFER: DS     80   BUFFER
```

The elements of the circular queue shown above are defined as follows:

QL	= 2	byte link, set by system
NAME	= 8	ASCII character queue name, set by user
MSGLEN	= 2	bytes, length of message, set by user
NMBMSGS	= 2	bytes, number of messages, set by user
DQPH	= 2	bytes, DQ process head, set by system
NQPH	= 2	bytes, NQ process head, set by system
MSG$IN	= 2	bytes, pointer to next message in, set by system
MSG$OUT	= 2	bytes, pointer to next message out, set by system
MSG$CNT	= 2	bytes, number of messages in the queue, set by system
BUFFER	= n	bytes, where n is equal to the message length times the number of messages, space allocated by user, set by system Note: Mutual exclusion queues require a two byte buffer for the owner process descriptor address.

Queue Overhead 24 bytes

LINKED QUEUES

The following example illustrates how to setup a queue control block for a linked queue containing 4 messages. each 33 bytes in length:

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P L/M:

```
DECLARE LINKED$QUEUE STRUCTURE (
     QL ADDRESS,
     NAME (8) BYTE,
     MSGLEN ADDRESS,
     NMBMSGS ADDRESS,
     DQPH ADDRESS,
     NQPH ADDRESS,
     MH ADDRESS,
     MT ADDRESS,
     BH ADDRESS,
     BUFFER (140) BYTE    )
     INITIAL (0,'LNKQUE  ',33,4);
```

Assembly Language:

```
LNKQUE:
          DS        2    ; QL
          DB        'LNKQUE  ' ; NAME
          DW        33   ; MSGLEN
          DW        4    ; NMBMSGS
          DS        2    ; DQPH
          DS        2    ; NQPH
          DS        2    ; MH
          DS        2    ; MT
          DS        2    ; BH
BUFFER:   DS        2    ; MSG #1 LINK
          DS        33   ; MSG #1 DATA
          DS        2    ; MSG #2 LINK
          DS        33   ; MSG #2 DATA
          DS        2    ; MSG #3 LINK
          DS        33   ; MSG #3 DATA
          DS        2    ; MSG #4 LINK
          DS        33   ; MSG #4 DATA
```

The elements of the linked queue shown above are defined as follows:

```
QL        = 2  byte link, set by system
NAME      = 8  ASCII character queue name,
               set by user
MSGLEN    = 2  bytes, length of message,
               set by user
NMBMSGS   = 2  bytes, number of messages,
               set by user
DQPH      = 2  bytes, DQ process head,
               set by system
NQPH      = 2  bytes, NQ process head,
               set by system
MH        = 2  bytes, message head,
               set by system
```


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```
MT        = 2  bytes, message tail,

                set by system
BH        = 2  bytes, buffer head,
                set by system
BUFFER = nbytes where n is equal to
                the message length plus two,
                times the number of messages,
                space allocated by the user,
                set by the system
```

USER QUEUE CONTROL BLOCK

The user queue control block data structure is used to provide read/write access to queues in much the same manner that a file control block provides access to a disk file. Queues are "opened", an operation which fills in the actual queue control block address, and then can be read from or written to.

If the actual queue address is known it can be filled in the pointer field of the user queue control block, the 8 byte name field can be omitted, and an open operation is not required in order to access the queue.

The following example illustrates a user queue control block:

PL/M:

```
DECLARE USER$QUEUE$CONTROL$BLOCK STRUCTURE (
POINTER ADDRESS,
MSGADR ADDRESS,
NAME (8) BYTE   )
INITIAL (0, .BUFFER, 'SPOOL   ‘);

DECLARE BUFFER (33) BYTE;
```

Assembly Language:

```
UQCB:
     DS        2          ; POINTER
     DW        BUFFER     ; MSGADR
     DB        'SPOOL   ‘; NAME
BUFFER:
     DS        33         ; BUFFER
```


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The elements of the user queue control block shown above are defined as follows:

```
POINTER = 2 bytes, set by system to address of
          actual queue during an open queue
          operation, or set by the user if the
          actual queue address is known
MSGADR  = 2 bytes, address ofuser buffer,
          set by user
NAME    = 8 bytes,  ASCII queue name,
          set byuser, may be omitted if the
          pointer field is set by the user
```

QUEUE NAMING CONVENTIONS

The following conventions should be used in the naming of queues. Queues which are to be directly written to bythe Terminal Message Process (TMP) via the Command Line Interpreter (CLI) must have an upper case ASCII name. Thus when an operator enters the queue name followed by a command tail at a console, the command tail is written to the queue.

In order to make a queue inaccessible by a user at a console it must contain at least one lower case character. Mutual exclusion queues should be named upper case 'MX' followed by 1 to 6 additional ASCII characters. These queues are treated specially in that they must have a two byte buffer in which MP/M places the address of the process descriptor owning the mutual exclusion message.

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PROCESS DESCRIPTOR

Each process in the MP/M system has a process descriptor which defines all the characteristics of the process. The following example illustrates the process descriptor:

PL/M:

```
DECLARE CNS$HNDLR STRUCTURE (
     PL ADDRESS,
     STATUS BYTE,
     PRIORITY BYTE,
     STKPTR ADDRESS,
     NAME (8) BYTE,
     CONSOLE BYTE,
     MEMSEG BYTE,
     B ADDRESS,
     THREAD ADDRESS,
     DISK$SET$DMA ADDRESS,
     DISK$SLCT BYTE,
     DCNT ADDRESS,
     SEARCHL BYTE,
     SEARCHA ADDRESS,
     DRVACT ADDRESS,
     REGISTERS (20) BYTE,
     SCRATCH (2) BYTE )
     INITIAL (0, 0, 200, .CNS$STK (19),
          'CNS     ',1,0FFH);

DECLARE CNS$STK (20) ADDRESS INITIAL (
     0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,
     0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,
     0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,0C7C7H,
     0C7C7H,STRT$CNS);
```


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Assembly Language:

```
     CNSHND:
          DW   0          ; PL
          DB   0          ; STATUS
          DB   200        ; PRIORITY
          DW   CNSTK+38   ; STKPTR
          DB   'CNS     '; NAME
          DB   0          ; CONSOLE
          DB   OFFH       ; MEMSEG (FF = resident)
          DS   2          ; B
          DS   2          ; THREAD
          DS   2          ; DISK SET DMA
          DS   1          ; DISK SLCT
          DS   2          ; DCNT
          DS   1          ; SEARCHL
          DS   2          ; SEARCHA
          DS   2          ; DRVACT
          DS   20         ; REGISTERS
          DS   2          ; SCRATCH

     CNSTK:
          DW   OC7C7H,OC7C7H,OC7C7H,OC7C7H
          DW   OC7C7H,OC7C7H,OC7C7H,OC7C7H
          DW   OC7C7H,OC7C7H,OC7C7H,OC7C7H
          DW   OC7C7H,OC7C7H,OC7C7H,OC7C7H
          DW   OC7C7H,OC7C7H,OC7C7H
          DW   CNSPR      ; CNSTK+38 = PROCEDURE ADR
```

The elements of the process descriptor shown above are defined as follows:

PL	= 2	byte link field, initially set by user to address of next process descriptor, or zero if no more
STATUS	= 1	byte, process status, set by system
PRIORITY	= 1	byte, process priority, set by user
STKPTR	= 2	bytes, stack pointer, initially set by user
NAME	= 8	bytes, ASCII process name, set by user

The high order bit of each byte of the process name is reserved for use by the system. The high order bit of the first byte (identified as NAME(O)') "on" indicates that the process is performing direct console BIOS calls and that MP/M is to ignore all control characters. It is also used to suppress the normal console status check done when BDOS disk functions are invoked. This bit may be set by the user.

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```
CONSOLE        = 1  byte, console to be used by process,
                    set by user
MEMSEG         = 1  byte, memory segment table index
B              = 2  bytes, system scratch area
THREAD         = 2  bytes, process list thread, set
                    by system
DISK$SET$DMA   = 2  bytes, default DMA address, set by user
DISK$SLCT      = 1  byte, default disk/user code
DCNT           = 2  bytes, system scratch byte
SEARCHL        = 1  byte, system scratch byte
SEARCHA        = 2  bytes, system scratch bytes
DRVACT         = 2  bytes, 16 bit vector of drives being
                    accessed by the process
REGISTERS      = 20 bytes, 8080 / Z80 register save area
SCRATCH        = 2  bytes, system scratch bytes
```

PROCESS NAMING CONVENTIONS

The following conventions should be used in the naming of processes. Processes which wait on queues that are to be sent command tails from the TMPs are given the console resource if their name matches that of the queue which they are reading. Processes which are to be protected from abortion by an operator using the ABORT command must have at least one lower case character in the process name.

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2.4 Extended Disk Operating System Functions

The Extending Disk Operating System (XDOS) functions are covered in this section by describing the entry parameters and returned values for each XDOS function. The XDOS calling conventions are identical to those of the BDOS which are described in OPERATING SYSTEM CALL CONVENTIONS in section 2.1.

```
*****************************************
*                                       *
* FUNCTION 128:ABSOLUTE MEMORY   *
*                    REQUEST            *
*****************************************
* Entry Parameters:                     *
* Register C: 80H                       *
* DE: MD Address                        *
*                                       *
* ReturnedValue:                 *
* RegisterA: Return code         *
* MD filled in                          *
*****************************************
```

The ABSOLUTE MEMORY REQUEST function allocates an absolute block of memory specified by the passed memory descriptor parameter. This function allows nonrelocatable programs, such as CP/M *.COM files based at the absolute TPA address of 0100H, to run in the MP/M 1.0 environment. The single passed parameter is the address of a memory descriptor. The memory descriptor contains four bytes: the memory segment base page address, the memory segment page size, the memory segment attributes, and bank. The only parameters filled in by the user are the base and size, the other parameters are filled in by XDOS.

The operation returns a "boolean" indicating whether or not the allocation was made. A returned value of FFH indicates failure to allocate the requested memory and a value of 0 indicates success. Note that base and size specify base page address and page size where a page is 256 bytes.

Memory Descriptor Data Structure:

```
PL/M:
Declare memory$descriptor structure (
     base byte,
     size byte,
     attrib byte,
     bank byte          );
```


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Assembly Language:

```
     MEMDES:
          DS   1    ; base
          DS   1    ; size
          DS   1    ; attributes
          DS   1    ; bank


*****************************************
*                                       *
* FUNCTION 129:  RELOCATABLE MEMORY     *
*                   REQUEST             *
*****************************************
* Entry Parameters:                     *
* Register C: 81H                       *
* DE: MD Address                        *
*                                       *
* Returned Value:                       *
* Register A: Return code               *
* MD filled in                          *
*****************************************
```

The RELOCATABLE MEMORY REQUEST function allocates the requested contiguous memory to the calling program. The single passed parameter is the address of a memory descriptor. The only memory descriptor parameter filled in by the calling program is the size, the other parameters, base, attributes and bank, are filled in by XDOS.

The operation returns a boolean indicating whether or not the memory request could be satisfied. A returned value of FFH indicates failure to satisfy the request and a value of 0 indicates success.

Note that base and size specify base page address and page size where a page is 256 bytes. (See function 128: ABSOLUTE MEMORY REQUEST for a description of the memory descriptor data structure.)

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```
*****************************************

*                                       *
* FUNCTION 130: MEMORY FREE             *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   82H                *     *
*              DE:  MD Address          *
*                                       *
*****************************************
```

The MEMORY FREE function releases the specified memory segment back to the operating system. The passed parameter is the address of a memory descriptor. Nothing is returned as a result of this operation. (See function 128: ABSOLUTE MEMORY REQUEST for a description of the memory descriptor data structure.)

```
*****************************************
*                                       *
* FUNCTION 131: POLL                    *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC: 83H                  *     *
*              E: Device Number         *
*                                       *
*****************************************
```

The POLL function polls the specified device until a ready condition is received. The calling process relinquishes the processor until the poll is satisfied, allowing other processes to execute.

Note that the POLL function is intended for use in the custom XIOS since an association is made in the XIOS between the device number and the actual code executed for the poll operation. This does not exclude other uses of the poll function but it does mean that an application program making a poll call must be matched to a specific XIOS.

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```
*****************************************

*                                       *
* FUNCTION 132: FLAG WAIT                *
*                                        *
*****************************************
* Entry Parameters:                      *
* RegisterC:   84H                *      *
*              E: Flag Number            *
*                                        *
* ReturnedValue:                  *      *
* Register     A: Return code            *
*****************************************
```

The FLAG WAIT function causes a process to relinquish the processor until the flag specified in the call is set. The flag wait operation is used in an interrupt driven system to cause the calling process to 'wait' until a specific interrupt condition occurs.

The operation returns a boolean indicating whether or not a successful FLAG WAIT was performed. A returned value of FFH indicates that no flag wait occurred because another process was already waiting on the specified flag. A returned value of 0 indicates success.

Note that flags are nonqueued, which means that access to flags must be carefully managed. Typically the physical interrupt handlers will set flags while a single process will wait on each flag.

```
*****************************************
*                                       *
* FUNCTION 133: FLAG SET                 *
*                                        *
*****************************************
* Entry Parameters:                      *
* RegisterC:   85H                *      *
*              E: Flag number            *
*                                        *
* ReturnedValue:                  *      *
* RegisterA:   Return code        *      *
*****************************************
```

The FLAG SET function wakes up a waiting process. The FLAG SET function is usually called by an interrupt service routine after servicing an interrupt and determining which flag is to be set.

The operation returns a boolean indicating whether or not a successful FLAG SET was performed. A returned value of FFH

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indicates that a flag overrun has occurred, i.e. the flag was already set when a flag set function was called. A returned value of 0 indicates success.

```
*****************************************
*                                       *
* FUNCTION 134: MAKE QUEUE                *
*                                         *
*****************************************
* Entry Parameters:                       *
* Register C: 86H                         *
*          DE: QCB Address                *
*                                         *
*****************************************
```

The MAKE QUEUE function sets up a queue control block. A queue is configured as either circular or linked depending upon the message size. Message sizes of 0 to 2 bytes use circular queues while message sizes of 3 or more bytes use linked queues.

A single parameter is passed to make a queue, the queue control block address. The queue control block must contain the queue name, message length, number of messages, and sufficient space to accomodate the messages (and links if the queue is linked).

The queue control block data structures for both circular and linked queues are described in section 2.3.

Queues can only be created either in common memory or by user programs in nonbanked systems. The reason is that queues are all maintained on a linked list which must be accessible at all times. I.E., a queue cannot reside in a memory segment which is bank switched. However, a queue created in common memory can be accessed by all system and user programs.

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```
*****************************************

*                                       *
* FUNCTION 135: OPEN QUEUE              *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   87H                *     *
*              DE:  UQCB Address        *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return code        *     *
*****************************************
```

The OPEN QUEUE function places the actual queue control block address into the user queue control block. The result of this function is that a user program can obtain access to queues by knowing only the queue name, the actual address of the queue itself is obtained as a result of opening the queue. Once a queue has been opened, the queue may be read from or written to using the queue read and write operations.

The function returns a boolean indicating whether or not the open queue operation found the queue to be opened. A returned value of OFFH indicates failure while a zero indicates success.

The user queue control block data structure is described in section 2.3.

```
*****************************************
*                                       *
* FUNCTION 136: DELETE QUEUE            *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   88H                *     *
*              DE:  QCB Address         *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return Code        *     *
*****************************************
```

The DELETE QUEUE function removes the specified queue from the queue list. A single parameter is passed to delete a queue, the address of the actual queue.

The function returns a boolean indicating whether or not the delete queue operation deleted the queue. A returned value of OFFH indicates failure, usually because some process is DQing

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from the queue. A returned value of 0 indicates success.

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```
*****************************************

*                                       *
* FUNCTION 137: READ QUEUE              *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 89H                       *
*          DE: UQCB Address             *
*                                       *
* ReturnedValue:                  *     *
* Message read                          *
*****************************************
```

The READ QUEUE function reads a message from a specified queue. If no message is available at the queue the calling process relinquishes the processor until a message is posted at the queue. The single passed parameter is the address of a user queue control block. When a message is available at the queue, it is copied into the buffer pointed to by the MSGADR field of the user queue control block.

```
*****************************************
*                                       *
* FUNCTION 138: CONDITIONAL READ        *
*               QUEUE                   *
*****************************************
* Entry Parameters:                     *
* Register C: 8AH                       *
* DE: UQCB Address                      *
*                                       *
* ReturnedValue:                  *     *
* RegisterA: Return code          *     *
* message read if available             *
*****************************************
```

The CONDITIONAL READ QUEUE function reads a message from a specified queue if a message is available. The single passed parameter is the address of a user queue control block. If a message is available at the queue, it is copied into the buffer pointed to by the MSGADR field of the user queue control block.

The operation returns a boolean indicating whether or not a message was available at the queue. A returned value of OFFH indicates no message while a zero indicates that a message was available and that it was copied into the user buffer.

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```
*****************************************

*                                       *
* FUNCTION 139: WRITE QUEUE             *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   8BH                *     *
* DE:UQCB Address                 *     *
* Message to be sent                    *
*                                       *
*****************************************
```

The WRITE QUEUE function writes a message to a specified queue. If no buffers are available at the queue, the calling process relinquishes the processor until a buffer is available at the queue. The single passed parameter is the address of a user queue control block. When a buffer is available at the queue, the buffer pointed to by the MSGADR field of the user queue control block is copied into the actual queue.

```
*****************************************
*                                       *
* FUNCTION 140:                CONDITIONAL WRITE *
*                   QUEUE               *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   8CH                *     *
*              DE:UQCB Address          *
*              Message to be sent       *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return code        *     *
*****************************************
```

The CONDITIONAL WRITE QUEUE function writes a message to a specified queue if a buffer is available. The single passed parameter is the address of a user queue control block. If a buffer is available at the queue, the buffer pointed to by the MSGADR field of the user queue control block is copied into the actual queue.

The operation returns a boolean indicating whether or not a buffer was available at the queue. A returned value of OFFH indicates no buffer while a zero indicates that a buffer was available and that the user buffer was copied into it.

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```
*****************************************

*                                       *
* FUNCTION 141: DELAY                   *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 8DH                       *
*          DE: Number of Ticks          *
*                                       *
*****************************************
```

The DELAY function delays execution of the calling process for the specified number of system time units. Use of the delay operation avoids the typical programmed delay loop. It allows other processes to use the processor while the specified period of time elapses. The system time unit is typically 60 Hz (16.67 milliseconds) but may vary according to application. For example it is likely that in Europe it would be 50 Hz (20 milliseconds).

The delay is specified as a 16bit integer. Since calling the delay procedure is usually asynchronous to the actual time base itself, there is up to one tick of uncertainty in the exact amount of time delayed. Thus a delay of 10 ticks gaurantees a delay of at least 10 ticks, but it may be nearly 11 ticks.

```
*****************************************
*                                       *
* FUNCTION 142: DISPATCH                *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   8EH                *     *
*                                       *
*****************************************
```

The DISPATCH operation allows the operating system to determine the highest priority ready process and then to give it the processor. This call is provided in XDOS to allow systems without interrupts the capability of sharing the processor among compute bound processes. Since all user processes usually run at the same priority, invoking the dispatch operation at various points in a program will allow other users to obtain the processor in a roundrobin fashion. Invoking the dispatch function does not take the calling process off of the ready list.

Dispatch is intended for noninterrupt driven environments in which it is desirable to enable a compute bound process to relinquish the use of the processor.

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Another use of the dispatch function is to safely enable interrupts following the execution of a disable interrupt instruction (DI) .

```
*****************************************
*                                       *
* FUNCTION 143: TERMINATE PROCESS       *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   8FH                      *
*              D:   Conditional         *
*                   Memory Free         *
*              E: Terminate Code        *
*                                       *
*****************************************
```

The TERMINATE PROCESS function terminates the calling process. The passed parameters indicate whether or not the process should be terminated if it is a system process and if the memory segment is to be released. A OFFH in the E register indicates that the process should be unconditionally terminated, a zero indicates that only a user process is to be deleted. If a user process is being terminated and Register D is a OFFH, the memory segment is not released. Thus a process which is a child of a parent process both executing in the same memory segment can terminate without freeing the memory segment which is also occupied by the parent.

There are no results returned from this operation, the calling process simply ceases to exist as far as MP/M is concerned.

```
*****************************************
*                                       *
* FUNCTION 144: CREATE PROCESS          *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 90H                       *
* DE: PD Address                        *
*                                       *
* ReturnedValue:                        *
* PD filled in                          *
*****************************************
```

The CREATE PROCESS function creates one or more processes by placing the passed process descriptors on the MP/M ready list.

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A single parameter is passed, the address of a process descriptor. The first field of the process descriptor is a link field which may point to another process descriptor.

Processes can only be created either in common memory or by

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user programs in nonbanked systems. The reason is that process descriptors are all maintained on linked lists which must be accessible at all times.

The process descriptor data structure is described in section 2.3.

```
****************************************
*                                      *
* FUNCTION 145: SET PRIORITY           *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC: 91H                       *
*              E: Priority             *
*                                      *
****************************************
```

The SET PRIORITY function sets the priority of the calling process to that of the passed parameter. This function is useful in situations where a process needs to have a high priority during an initialization phase, but after that is to run at a lower priority.

A single passed parameter contains the new process priority. There are no results returned from setting priority.

```
****************************************
*                                      *
* FUNCTION 146: ATTACH CONSOLE         *
*                                      *
****************************************
* Entry Parameters:                    *
* RegisterC:   92H                     *
*                                      *
****************************************
```

The ATTACH CONSOLE function attaches the console specified in the CONSOLE field of the process descriptor to the calling process. If the console is already attached to some other process, the calling process relinquishes the processor until the console is detached from that process and the calling process is the highest priority process waiting for the console.

There are no passed parameters and there are no returned results.

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```
*****************************************

*                                       *
* FUNCTION 147: DETACH CONSOLE          *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   93H                      *
*                                       *
*****************************************
```

The DETACH CONSOLE function detaches the console specified in the CONSOLE field of the process descriptor from the calling process. If the console is not currently attached no action takes place.

There are no passed parameters and there are no returned results.

```
*****************************************
*                                       *
* FUNCTION 148: SET CONSOLE             *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC: 94H                        *
*    E: Console                         *
*                                       *
*****************************************
```

The SET CONSOLE function detaches the currently attached console and then attaches the console specified as a calling parameter. If the console to be attached is already attached to another process descriptor, the calling process relinquishes the processor until the console is available.

A single passed parameter contains the console number to be attached. There are no returned results.

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```
*****************************************

*                                       *
* FUNCTION 149: ASSIGN CONSOLE          *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 95H                       *
*          DE: APB Address              *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Return code        *     *
*****************************************
```

The ASSIGN CONSOLE function directly assigns the console to a specified process. This assignment is done regardless of whether or not the console is currently attached to some other process. A single parameter is passed to assign console which is the address of a data structure containing the console number for the assignment, an 8 character ASCII process name, and a boolean indicating whether or not a match with the console field of the process descriptor is required (true or OFFH indicates it is required).

The operation returns a boolean indicating whether or not the assignment was made. A returned value of OFFH indicates failure to assign the console, either because a process descriptor with the specified name could not be found, or that a match was required and the console field of the process descriptor did not match the specified console. A returned value of zero indicates a successful assignment.

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```
*****************************************

*                                       *
* FUNCTION 150: SEND CLI COMMAND        *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 96H                       *
*          DE: CLICMD Address           *
*                                       *
*****************************************
```

The SEND CLI COMMAND function permits running programs to send command lines to the Command Line Interpreter. A single parameter is passed which is the address of a data structure containing the default disk/user code, console and command line itself (shown below).

The default disk/user code is the first byte of the data structure. The high order four bits contain the default disk drive and the low order four bits contain the user code. The second byte of the data structure contains the console number for the program being executed. The ASCII command line begins with the third byte and is terminated with a null byte.

There are no results returned to the calling program.

The following example illustrates the SEND CLI COMMAND data structure:

PL/M:

```
Declare CLI$command structure (
     disk$user byte,
     console byte,
     command$line (129) byte);
```

Assembly Language:

```
CLICMD:
     DS        1    ; default disk / user code
     DS        1    ; console number
     DS        129  ; command line
```


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```
*****************************************

*                                       *
* FUNCTION 151:  CALL RESIDENT          *
* SYSTEM PROCEDURE                      *
*****************************************
* Entry Parameters:                     *
* Register C: 97H                       *
*         DE: CPB Address               *
*                                       *
* Returned     Value:                   *
* Registers HL: Return code             *
*****************************************
```

The CALL RESIDENT SYSTEM PROCEDURE function permits programs to call the optional resident system procedures. A single passed parameter is the address of a call parameter block data structure (shown below) which contains the address of an 8 character ASCII resident system procedure name followed by a two byte parameter to be passed to the resident system procedure.

The operation returns a 0001H if the resident system procedure called is not present, otherwise it returns the code passed back from the resident system procedure. Typically a returned value of FFH indicates failure while a zero indicates success.

The following example illustrates the call parameter block data structure:

PL/M:

```
Declare CALL$PB structure (
  Name$adr address,
Param address ) initial (
 .name,0);

Declare name (8) byte initial (
  'Procl   ');
```

Assembly Language:

```
CALLPB:
     DW        NAME
     DW        0    ; parameter
NAME:
     DB        'Procl   '
```


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```
*****************************************

*                                       *
* FUNCTION 152: PARSE FILENAME          *
*                                       *
*****************************************
* Entry Parameters:                     *
* Register C: 98H                       *
*         DE: PFCB Address              *
*                                       *
* Returned Value:                       *
* Registers HL: Return code             *
* Parsed file control block             *
*****************************************
```

The PARSE FILENAME function prepares a file control block from an input ASCII string containing a file name terminated by a null or a carriage return. The parameter is the address of a data structure (shown below) which contains the address of the ASCII file name string followed by the address of the target file control block.

The operation returns an FFFFH if the input ASCII string contains an invalid file name. A zero is returned if the ASCII string contains a single valid file name, otherwise the address of the first character following the file name is returned.

The following example illustrates the parse file name control block data structure:

PL/M:

```
Declare Parse$FN$CB structure (
  File$name$adr address,
  FCB$adr address   )    initial (
  .fileqname,.fcb );

Declare file$name (128) byte;
Declare fcb (36) byte;
```

Assembly Language:

```
PFNCB:
     DW        FLNAME
     DW        FCB
FLNAME:
     DS        128
     DS        36
```


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```
*****************************************

*                                       *
* FUNCTION 153: GET CONSOLE NUMBER      *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   99H                *     *
*                                       *
* ReturnedValue:                  *     *
* RegisterA:   Console Number     *     *
*****************************************
```

The GET CONSOLE NUMBER function obtains the value of the console field from the process descriptor of the calling program. There are no passed parameters and the returned result is the console number of the calling process.

```
*****************************************
*                                       *
* FUNCTION 154: SYSTEM DATA ADDRESS     *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   9AH                *     *
*                                       *
* Returned     Value:                   *
* Registers HL:System Data Page   *     *
*                    Address            *
*****************************************
```

The SYSTEM DATA ADDRESS function obtains the base address of the system data page. The system data page resides in the top 256 bytes of available memory. It contains configuration information used by the MP/M loader as well as run time data including the submit flags. The contents of the system data page are described in section 3.4 under SYSTEM DATA.

There are no passed parameters and the returned result is the base address of the system data page.

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```
*****************************************

*                                       *
* FUNCTION 155: GET DATE AND TIME       *
*                                       *
*****************************************
* Entry Parameters:                     *
* RegisterC:   9BH                *     *
*              DE:  TOD Address         *
*                                       *
* ReturnedValue:                  *     *
* Time and date                         *
*****************************************
```

The GET DATE AND TIME function obtains the current encoded date and time. A single passed parameter is the address of a data structure (shown below) which is to contain the date and time. The date is represented as a 16bit integer with day 1 corresponding to January 1, 1978. The time is respresented as three bytes: hours, minutes and seconds stored as two BCD digits.

The following example illustrates the TOD data structure:

PL/M:

```
Declare TOD structure (
date address,
hour byte,
min byte,
sec byte );
```

Assembly Language:

```
TOD:          DS   2    ; Date
     DS       1         ; Hour
     DS       1         ; Minute
     DS       1         ; Second
```

```
*****************************************
*                                       *
* FUNCTION 156: RETURN PROCESS          *
*               DESCRIPTOR ADDRESS      *
*****************************************
* Entry Parameters:                     *
* RegisterC:   9CH                *     *
*                                       *
* ReturnedValue:                  *     *
* Register HL: PD Address               *
*                                       *
*****************************************
```


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The RETURN PROCESS DESCRIPTOR ADDRESS function obtains the address of calling processes process descriptor. By definition this is the head of the ready list.

```
****************************************
*                                      *
* FUNCTION 157:ABORT SPECIFIED   *
*                    PROCESS           *
****************************************
* Entry Parameters:                    *
* RegisterC:   9DH                *
* RegisterDE:  APB Address        *
*                                      *
* Returned     Value:                  *
* RegisterA:   Return Code        *
****************************************
```

The ABORT SPECIFIED PROCESS function permits a process to terminate another specified process. The passed parameter is the address of an Abort Parameter Block (ABTPB) which contains the following data structure:

PL/M:

```
Declare Abort$paramter$ block structure (
  pdadr address,
termination$code address,
  name (8) byte,
  console byte );
```

Assembly Language:

```
APB:
     DS        2    ; process desciptor address
     DS        2    ; termination code
     DS        8    ; process name
     DS        1    ; console used by process
```

If the process descriptor address is known it can be filled in and the process name and console can be omitted. Otherwise the process descriptor address field should be a zero and the process name and console must be specified. In either case the termination code must be supplied which is the parameter passed to FUNCTION 143: TERMINATE PROCESS.

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2.5 Preparation of Page Relocatable Programs

A page relocatable program is stored on diskette as a file of type 'PRL'. Appendix K contains a PRL file specification describing the file format. A page relocatable program is prepared by assembling the source program twice, in which the second assembly has 100H added to each ORG statement. The two hex files generated by assembling the source file twice are concatenated with PIP and then provided as input to the GENMOD program. The G9NMOD program (described in section 1.4) produces a file of type 'PRL'.

This section describes APPENDIX G: Sample Page Relocatable Program. The example program illustrates the required use of ORG statements to access the BDOS and the default file control block. Note that the initial ORG is OOOOH. Its purpose is to establish the equate for the symbol BASE, the base of the relocatable segment. Next an ORG 100H statement establishes the actual beginning of code for the program. During the second assembly these two ORG statements are changed to 100H and 200H respectively. Note that the first assembly will generate a file which can be LOADed to produce an executable 'COM' file. In fact, it is desirable to first debug the program as a 'COM' file and then proceed to make the 'PRL' file.

It is VERY important to use BASE to offset all memory segment base page references. Do not make a call to absolute 0005H for BDOS calls. In this example BASE is used to offset the BDOS, FCB, and BUFF equates. When a user program needs to determine the top of its memory segment the following equate and code sequence should be used:

```
MEMSIZE   EQU       BASE+6

          . . .

          LHLD      MEMSIZE ;HL = TOP OF MEMORY SEGMENT
```

The following steps show how to generate a page relocatable file for this example using the Digital Research Macro Assembler (MAC):

* Prepare the user program, DUMP.ASM in this example, with proper origin statements as described above.

* Assuming a system disk in drive A: and the DUMP.ASM file is on drive B:, enter the commands

```
1A>MAC B:DUMP $PP+S
     ;assemble and list the DUMP.ASM file
1A>ERA B:DUMP.HXO
```


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```
1A>REN B:DUMP.HXO=B:DUMP.HEX

1A>MAC B:DUMP $PZSZ+R
     ;assemble the DUMP.ASM file again, offset by 100H
     ;the offset is generated with the +R MAC option
1A>PIP B:DUMP.HEX=B:DUMP.HXO,B:DUMP.HEX
     ;concatenate the HEX files
1A>GENMOD B:DUMP.HEX B:DUMP.PRL
     ;generate the relocatable DUMP.PRL file
```

The following steps show how to generate a page relocatable file for thisexample using the Digital Research Assembler (ASM):

* Prepare the user program, DUMP.ASM in this example, with proper origin statements as described above.

* Assuming a system disk in drive A: and the DUMP.ASM file is on drive B:, enter the commands

```
1A>ASM B:DUMP
     ;assemble the DUMP.ASM file
1A>ERA B:DUMP.HXO
1A>REN B:DUMP.HXO;B:DUMP.HEX
IA>PIP LST:=B:DUMP.PRN[T8]
1A>ERA B:DUMP.PRN
```

* Edit the DUMP.ASM file, adding 100H to each ORG statement. This can be done by concatenating a preamble to the program which contains the two initial ORG statements. A submit file to perform this function, named ASMPRL.SUB is provided on the distribution diskette.

```
1A>ASM B:DUMP.BBZ
     ;assemble the DUMP.ASM file a second time
1A>PIP B:DUMP.HEX=B:DUMP.HXO,B:DUMP.HEX
     ;concatenate the HEX files
1A>GENMOD B:DUMP.HEX B:DUMP.PRL
     ;generate the relocatable DUMP.PRL file
```


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2.6 Installation of Resident System Processes

This section contains a description of APPENDIX H: Sample Resident System Process. The example program illustrates the required structure of a resident system process as well as the BDOS/XDOS access mechanism.

The first two bytes of a resident system process are set to the address of the BDOS/XDOS entry point. The address is filled in by the loader, providing a simple means for a resident system process to access the BDOS/XDOS by loading HL from the base of the program area and then executing a PCHL instruction.

The process descriptor for the resident system process must immediately follow the first two bytes which contain the address of the BDOS/XDOS entry point. Observe the manner in which the process descriptor is initialized in the example. The DS's are used where storage is simply allocated. The DB's and DW's are used where data in the process descriptor must be initialized. Note that the stack pointer field of the process descriptor points to the address immediately following the stack allocation. This is the return address which is the actual process entry point.

It is important that the HEX file generated by assembling the RSP span the entire program and data area. For this reason the first two bytes of the resident system process which will contain the address of the BDOS/XDOS entry point are defined with a DW. Using a DS would not generate any HEX file code for those two bytes. The end of the program and data area must be defined in a likewise manner. If your RSP has DS statements preceding the END statement it will be necessary to place a DB statment after the DS statements before the END statement.

The steps to produce a resident system process closely follow those illustrated in the previous section on page relocatable programs. The only exception to the procedure is that the GENMOD output file should have a type of 'RSP' rather than 'PRL' and the code in the RSP is ORGed at OOOH rather than 100H.

In addition to resident system processes MP/M supports resident system procedures. The purpose of a resident system procedure is to provide a means to use a piece of code as a serially reusable resource. A resident system procedure is set up by a resident system process. The function of the process is to create a queue which has the name of the resident system procedure and to send it one 16 bit message containing the address of the resident system procedure. Once this is accomplished the resident system process terminates itself. Access to the resident system procedure is made by opening the queue with the resident system procedure name and then reading the two byte message to obtain the actual memory address of the

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procedure itself. Since there is only one message posted at the queue, only one process will gain access to the procedure at a time. When the process executing the resident system procedure leaves the procedure it sends the two byte message containing the procedure address back to the queue. This action enables the next waiting process to use the resident system procedure.

When the MP/M system generation program is executed it searches the directory for all files with the type 'RSP'. The user is then prompted with the file name and asked if it should be included in the generated system file.

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3. MP/M ALTERATION GUIDE

3.1 Introduction

The standard MP/M system assumes operation on an Intel MDS800 microcomputer development system, but is designed so that the user can alter a specific set of subroutines which define the hardware operating environment. In this way, the user can produce a diskette which operates with any IBM3741 format compatible diskette subsystem and other peripheral devices.

Although standard MP/M is configured for single density floppy disks, fieldalteration features allow adaptation to a wide variety of disk subsystems from single drive minidisks through highcapacity "hard disk" systems.

In order to achieve device independence, MP/M is distinctly separated into an XIOS module which is hardware environment dependent and several other modules which are not dependent upon the hardware configuration.

The user can rewrite the distribution version of the MP/M XIOS to provide a new XIOS which provides a customized interface betweenthe remaining MP/M modules and the user's own hardware system. The user can also rewritethe distribution version of the LDRBIOS which is used to load the MP/M system from disk.

The purpose of this section is to provide the following stepbystep procedure for writing both your LDRBIOS and new XIOS for MP/M:

(1) Implement CP/M 2.0 on the target computer

To simplify the MP/M adaptation process, we assume (and STRONGLY recommend) that CP/M 2.0 has already been implemented on the target MP/M machine. If this is not the case it will be necessary for the user to implement the CP/M 2.0 BIOS as described in the Digital Research document titled "CP/M 2.0 Alteration Guide" in addition to the MP/M XIOS. The reason that both the BIOS and XIOS have to be implemented is that the MP/M loader uses the CP/M 2.0 BIOS to load and relocate MP/M. Once loaded, MP/M uses the XIOS and not the BIOS. The CP/M 2.0 BIOS used by the MP/M loader is called the LDRBIOS.

Another good reason for implementing CP/M 2.0 on the target MP/M machine is that debugging your XIOS is greatly simplified by bringing up MP/M while running SID or DDT under a CP/M 2.0 system.

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(2) Prepare your custom MPMLDR by writing a LDRBIOS

Study the BIOS given in the "CP/M 2.0 Alteration Guide" and write a version which has a ORG of 1700H. Call this new BIOS by the name LDRBIOS (loader BIOS). Implement only the primitive disk read operations on a single drive, and console output functions.

The first LDRBIOS call made by the MPMLDR is SELDSK:, select disk. If there are devices which require initialization a call to the LDRBIOS cold start or other initialization code should be placed at the beginning of the SELDSK handler.

Note: The MPMLDR uses 4000H 6FFFH as a buffer area when loading and relocating the MPM.SYS file.

Test LDRBIOS completely to ensure that it properly performs console character output and disk reads. Be especially careful to ensure that no disk write operations occur accidently during read operations, and check that the proper track and sectors are addressed on all reads. Failure to make these checks may cause destruction of the initialized MP/M system after it is patched.

The following steps can be used to integrate a custom LDRBIOS into the MPMLDR.COM:

A.) Obtain access to CP/M version 1.4 or 2.0 and prepare the LDRBIOS.HEX file.

B.) Read the MPMLDR.COM file into memory using either DDT or SID.

```
A>DDT MPMLDR.COM
DDT VERS 2.0
NEXT PC
1A00 0100
```

C.) Using the input command ('I') specify that the LDRBIOS.HEX file is to be read in and then read ('R') in the file. The effect of this operation is to overlay the BIOS portion of the MP/M loader.

```
I LDRBIOS. HEX
R
NEXT PC
1A00 0000
```

D.) Return to the CP/M console command processor (CCP) by executing a jump to location zero.

```
G0
```


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E.) Write the updated memory image onto a disk file using the CP/M 'SAVE' command. The 'X' placed in front of the file name is used simply to designate an experimental version, preserving the original.

```
A>SAVE 26 XMPMLDR.COM
```

F.) Test XMPMLDR.COM and then rename it to MPMLDR.COM.

(3) Prepare your custom XIOS

If MP/M is being tailored to your computer system for the first time, the new XIOS requires some relatively simple software development and testing. The standard XIOS is listed in APPENDIX I, and can be used as a model for the customized package.

The XIOS entry points, including both basic and extended, are described in sections 3.2 and 3.3. These sections along with APPENDIX I provides you with the necessary information to write your XIOS. We suggest that your initial implementation of an XIOS utilize polled I/O without any interrupts. The system will run without even a clock interrupt. The origin of your XIOS should be OOOOH. Note the two equates needed to access the dispatcher and XDOS from the XIOS:

```
          ORG  OOOOH
PDISPEQU  $3
XDOS      EQU  PDISP3
```

The procedure to prepare an XIOS.SPR file from your customized XIOS is as follows:

A.) Assemble your XIOS.ASM and then rename the XIOS.HEX file to XIOS.HXO.

B.) Assemble your XIOS.ASM again specifying the +R option which offsets the ORG statements by 100H bytes. Or, edit your XIOS.ASM and change the initial ORG OOOH to an ORG 100H and assemble it again.

C.) Use PIP to concatenate your two HEX files:

```
A>PIP XIOS.HEX=XIOS.HXO,XIOS.HEX
```

D.) Run the GENMOD program to produce the XIOS.SPR file from the concatenated HEX files.

```
A>GENMOD XIOS.HEX XIOS.SPR
```


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*** Warning ***

Make certain that your XIOS.ASM file contains A defined byte of zero at the end. This is especially critical if your XIOS.ASM file ends with a defined storage. The reason for this requirement is that there are no HEX file records produced for defined store (DS) statements. Thus, the output HEX file is misleading because it does not identify the true length of your XIOS. The following example illustrates a properly terminated XIOS:

```
begdat    equ  $
dirbuf:   ds   128
alvo:ds   31
csvo:ds   16
          db   0    force out hex record at end
          end
```

Note that this same technique must be applied to any other PRL or RSP programs that you prepare.

(4) Debug your XIOS

An XIOS or a resident system process can be debugged using DDT or SID running under CP/M 1.4 or 2.0. The debugging technique is outlined in the following steps:

A.) Determine the amount of memory which is available to MP/M with the debugger and the CP/M operating system resident. This can be done by loading the debugger and then listing the jump instruction at location 0005H. This jump is to the base of the debugger.

```
A>DDT
DDT VERS 2.0

L5

0005 JMP D800
```

B.) Using GENSYS running under CP/M, generate a MPM.SYS file which specifies the top of memory determined by the previous step, allowing at least 256 bytes for a patch area.

```
...
Top page of memory = D6
...
```

Also while executing GENSYS specify the breakpoint restart number as that used by the CP/M SID or DDT which you will be executing. This restart is usually #7.

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```
          ...

     Breakpoint RST # =  7
          ...
```

C.) If a resident system process is being debugged make certain that it is selected for inclusion in MPM.SYS.

D.) Using CP/M 1.4 or 2.0, load the MPMLDR.COM file into memory.

```
          A>DDT MPMLDR.COM
          DDT VERS 2.0
          NEXT PC
          lAO0 0100
```

E.) Place a 'B' character into the second position of default FCB. This operation can be done with the 'I' command:

```
          IB
```

F.) Execute the MPMLDR.COM program by entering a 'G' command:

```
          G
```

G.) At point the MP/M loader will load the MP/M operating system into memory, displaying a memory map.

H.) If you are debugging an XIOS, note the address of the XIOS.SPR memory segment. If you are debugging a resident system process, note the address of the resident system process. This address is the relative OOOOH address of the code being debugged. You must also note the address of SYSTEM.DAT.

I.) Using the 'S' command, set the byte at SYSTEM.DAT + 2 to the restart number which you want the MP/M debugger to use. Do not select the same restart as that being used by the CP/M debugger.

```
          ...
          Memory Segment Table:
          SYSTEM DAT D600H 0100H
          ...

          SD602
          D602 07 05
```

J.) Using the 'X' command, determine the MP/M beginning execution address. The address is the first location past the current program counter.

```
          X
```


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```
. . . . . P = OA93 . . . .
```

K.) Begin execution of MP/M using the 'G' command, specifying any breakpoints which you need in your code. Actual memory address can be determined using the 'H' command to add the code segment base address given in the memory map to the relative displacement address in your XIOS or resident system process listing,

The following example shows how to set a breakpoint to debug an XIOS list subroutine given the memory map:

```
...
XIOS    SPR    CDOOH     0500H

GA94,CDOF
```

L.) At this point you have MP/M running with CP/M and its debugger also in memory. Since interrupts are left enabled during operation of the CP/M debugger, care must be taken to ensure that interrupt driven code does not execute through a point at which you have broken.

Since the CP/M debugger operates with interrupts left enabled it is a somewhat difficult task to debug an interrupt driven console handler. This problem can be approached by leaving console #0 in a polled mode while debugging the other consoles in an interrupt driven mode. Once this is done very little, if any, debugging would be required to adapt the interrupt driven code from another console to console #0. It is further recommended that you maintain a debug version of your XIOS which has polled I/O for console #0. Otherwise it will not be possible to run the CP/M debugger underneath the MP/M system because the CP/M debugger will not be able to get any console input, as it will all go to the MP/M interrupt driven console #0 handler.

(5) Directly booting MP/M from a cold start

In systems where MP/M is to be booted directly at cold start rather than loaded and run as a transient program under CP/M, the customized MPMLDR.COM file and cold start loader can be placed on the first two tracks of a diskette. If a CP/M SYSGEN.COM program is available it can be used to write the MPMLDR.COM file on the first two tracks. If a SYSGEN.COM program is not available, or if SYSGEN.COM will not work because a different media such as a minidiskette or "hard" disk is to be used, the user must write a simple memory loader, called GETSYS, which brings the MP/M loader into memory and a program called PUTSYS, which places the MPMLDR on the first two tracks of a diskette.

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Either the SID or DDT debugger can be used in place of writing a GETSYS program as is shown in the following example which also uses SYSGEN in place of PUTSYS. Sample skeletal GETSYS and PUTSYS programs are described later in this section (for a more detailed description of GETSYS and PUTSYS see the "CP/M 2.0 Alteration Guide").

In order to make the MP/M system load and run automatically, the user must also supply a cold start loader, similar to the one described in the "CP/M 2.0 Alteration Guide". The purpose of the cold start loader is to load the MP/M loader into memory from the first two tracks of the diskette. The CP/M 2.0 cold start loader must be modified in the following manner: the load address must be changed to 0100H and the execution address must also be changed to 0100H.

The following techniques are specifically for the MDS800 which has a boot ROM that loads the first track into location 3000H. However, the steps shown can be applied in general to any hardware.

If a SYSGEN program is available, the following steps can be used to prepare a diskette that cold starts MP/M:

A.) Prepare the MPMLDR.COM file by integrating your custom LDRBIOS as described earlier in this section. Test the MPMLDR.COM and verify that it operates properly.

B.) Execute either DDT or SID.

```
A>DDT
DDT VERS 2.0
```

C.) Using the input command ('I') specify that the MPMLDR.COM file is to be read in and then read ('R') in the file with an offset of 880H bytes.

```
IMPMLDR.COM
R880
NEXT PC
2480 0100
```

D.) Using the 'I' command specify that the BOOT.HEX file is to be read in and then read in the file with an offset that will load the boot into memory at 900H. The 'H' command can be used to calculate the offset.

```
H900 3000
3900 D900

IBOOT.HEX
RD900
```


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```
NEXT PC


2480 0000
```

E.) Return to the CP/M console command processor (CCP) by jumping to location zero.

```
GO
```

F.) Use the SYSGEN program to write the new cold start loader onto the first two tracks of the diskette.

```
A>SYSGEN
SYSGEN VER 2.0
SOURCE DRIVE NAME (OR RETURN TO SKIP)<cr>
DESTINATION DRIVE NAME (OR RETURN TO REBOOT)B
DESTINATION ON B, THEN TYPE RETURN<cr>
FUNCTION COMPLETE
```

If a SYSGEN program is not available then the following steps can be used to prepare a diskette that cold starts MP/M:

A.) Write a GETSYS program which reads the custom MPMLDR.COM file with location 3380H and the cold start loader (or boot program) into location 3300H. Code GETSYS so that it starts at location 100H (base of the TPA).

As in the previous example, note that SID or DDT can be used to perform this function instead of writing a GETSYS program.

Run the GETSYS program using an initialized MP/M diskette to see if GETSYS loads the MP/M loader starting at 3380H (the operating system actually starts 128 bytes later at 3400H).

C.) Write the PUTSYS program which writes memory starting at 3380H back onto the first two tracks of the diskette. The PUTSYS program should be located at 200H.

D.) Test the PUTSYS program using a blank uninitialized diskette by writing a portion of memory to the first two tracks; clear memory and read it back. Test PUTSYS completely, since this program will be used to alter the MP/M system diskette.

E.) Use PUTSYS to place the MP/M loader and cold start loader onto the first two tracks of a blank diskette.

SAMPLE PUTSYS PROGRAM

The following program provides a framework for the PUTSYS program. The WRITESEC subroutine must be inserted by the user to write the specific sectors.

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```
;  PUTSYS PROGRAM  WRITE TRACKS 0 AND 1 FROM MEMORY AT 3380M

;  REGISTER         USE
;    A    (SCRATCH REGISTER)
;    B    TRACK COUNT (0, 1)
;    C    SECTOR COUNT (1,2,. . . .,26)
;    DE   (SCRATCH REGISTER PAIR)
;    HL   LOAD ADDRESS
;    SP   SET TO STACK ADDRESS

START:
     LXI       SP,3380M       ;SET STACK POINTER TO SCRATCH AREA
     LXI       H, 3380M       ;SET BASE LOAD ADDRESS
     Mvi       B, 0           ;START WITH TRACK 0
WRTRK:                        ;WRITE NEXT TRACK (INITIALLY 0)
     Mvi       C,1            ;WRITE STARTING WITH SECTOR I
     WRSEC:                   ;WRITE NEXT SECTOR
     CALL      WRITESEC       ;USERSUPPLIED SUBROUTINE
     LXI       D,128     ;MOVE LOAD ADDRESS TO NEXT 1/2 PAGE
     DAD       D              ;HL = HL + 128
     INR       C              ;SECTOR = SECTOR + 1
     MOV       A,C            ;CHECK FOR END OF TRACK
     CPI       27
     JC        WRSEC     ;CARRY GENERATED IF SECTOR < 27

;  ARRIVE HERE AT END OF TRACK, MOVE TO NEXT TRACK
     INR       B
     MOV       A,B            ;TEST FOR LAST TRACK
     CPI       2
     JC        WRTRK     ;CARRY GENERATED IF TRACK < 2

;  ARRIVE HERE AT END OF LOAD, HALT FOR NOW
     HLT

;  USERSUPPLIED SUBROUTINE TO WRITE THE DISK
WRITESEC:
;  ENTER WITH TRACK NUMBER IN REGISTER 8,
;    SECTOR NUMBER IN REGISTER C, AND
;    ADDRESS TO FILL IN HL

     PUSH      B              ;SAVE B AND C REGISTERS
     PUSH      H              ;SAVE HL REGISTERS
. . . . . .
perform disk write at this point, branch to

label START if an error occurs
. . . . . .
     POP       H              ;RECOVER HL
     POP       B              ;RECOVER B AND C REGISTERS
     RET                      ;BACH TO MAIN PROGRAM

     END       START
```


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on each copy which is made of your customized MP/M diskette.

DISKETTE ORGANIZATION

The sector allocation for the standard distribution version of MP/M is given here for reference purposes. The first sector (see table on the following page) contains an optional software boot section. Disk controllers are often set up to bring track 0, sector 1 into memory at a specific location (often location OOOOH). The program in this sector, called BOOT, has the responsibility of bringing the remaining sectors into memory starting at location 0100H. If your controller does not have a builtin sector load, you can ignore the program in track 0, sector 1, and begin the load from track 0 sector 2 to location 0100H.

As an example, the Intel MDS800 hardware cold start loader brings track 0, sector 1 into absolute address 3000H. Upon loading this sector, control transfers to location 3000H, where the bootstrap operation commences by loading the remainder of track 0, and all of track 1 into memory, starting at 0100H. The user should note that this bootstrap loader is of little use in a nonMDS environment, although it is useful to examine it since some of the boot actions will have to be duplicated in your cold start loader.

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Track#	Sector#	Page#	Memory Address	MP/M Module name
00	01		(boot address)	Cold Start Loader
00	02	00	0100H	MPMLDR
00	03	00	0180H	"
00	04	01	0200H	"
00	05	01	0280H	"
00	06	02	0300H	"
00	07	02	0380H	"
00	08	03	0400H	"
00	09	03	0480H	"
00	10	04	0500H	"
00	11	04	0580H	"
00	12	05	0600H	"
00	13	05	0680H	"
00	14	06	0700H	"
00	15	06	0780H	"
00	16	07	0800H	"
00	17	07	0880H	"
00	18	08	0900H	"
00	19	08	0980H	"
00	20	09	OAOOH	"
00	21	09	OA80H	"
00	22	10	OBOOH	"
00	23	10	OB80H	"
00	24	11	OCOOH	"
00	25	11	OC80H	MPMLDR
00	26	12	ODOOH	LDRBDOS
01	01	12	OD80H	"
01	02	13	OEOOH	"
01	03	13	OE80H	"
01	04	14	OFOOH	"
01	05	14	OF80H	"
01	06	15	1000H	"
01	07	15	1080H	"
01	08	16	1100H	"
01	09	16	1180H	"
01	10	17	1200H	"
01	11	17	1280H	"
01	12	18	1300H	"
01	13	18	1380H	"
01	14	19	1400H	"
01	15	19	1480H	"
01	16	20	1500H	"
01	17	20	1580H	"
01	18	21	1600H	"
01	19	21	1680H	LDRBDOS
01	20	22	1700H	LDRBIOS
01	21	22	1780H	"
01	22	23	1800H	"
01	23	23	1880H	"
01	24	24	1900H	"
01	25	24	1980H	"
01	26	25	lAOOH	LDRBIOS

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3.2 Basic I/O System Entry Points

The entry points into the BIOS from the cold start loader and BDOS are detailed below. Entry to the BIOS is through a "jump vector" located at the base of the BIOS, as shown below (see Appendix I as well). The jump vector is a sequence of17 jump instructions which send program control to the individual BIOS subroutines. The BIOS subroutines may be empty for certain functions (i.e., they may contain a single RET operation) during regeneration of MP/M, but the entries must be present in the jump vector. The extended I/O system entry points (XIOS) immediately follow the last BIOS entry point.

The jump vector takes the form shown below, where the individual jump addresses are given to the left:

```
BIOS+OOH  JMP BOOT       ;COLD START
BIOS+03H  JMP WBOOT      ;WARM START
BIOS+06H  JMP CONST      ;CHECK FOR CONSOLE CHAR READY
BIOS+09H  JMP CONIN      ;READ CONSOLE CHARACTER IN
BIOS+OCH  JMP CONOUT;WRITE CONSOLE CHARACTER OUT
BIOS+OFH  JMP LIST       ;WRITE LISTING CHARACTER OUT
BIOS+12H  JMP PUNCH      ;WRITE CHARACTER TO PUNCH DEVICE
BIOS+15H  JMP READER;READ READER DEVICE
BIOS+18H  JMP HOME       ;MOVE TO TRACK 00
BIOS+lBH  JMP'SELDSK;SELECT DISK DRIVE
BIOS+lEH  JMP SETTRK;SET TRACK NUMBER
BIOS+21H  JMP SETSEC;SET SECTOR NUMBER
BIOS+24H  JMP SETDMA;SET DMA ADDRESS
BIOS+27H  JMP READ       ;READ SELECTED SECTOR
BIOS+2AH  JMP WRITE      ;WRITE SELECTED SECTOR
BIOS+2DH  JMP LISTST;RETURN LIST STATUS
BIOS+30H  JMP SECTRAN    ;SECTOR TRANSLATE SUBROUTINE
```

Each jump address corresponds to a particular subroutine which performs the specific function, as outlined below. There are three major divisions in the jump table: the system (re)initialization which results from calls on BOOT and WBOOT,' simple character I/O performed by calls on CONST, CONIN, CONOUT, LIST, and LISTST, and diskette I/O performed by calls on HOME, SELDSK, SETTRK, SETSEC, SETDMA, READ, WRITE, and SECTRAN.

All simple character I/O operations are assumed to be performed in ASCII, upper and lower case, with high order (parity bit) set to zero. An endoffile condition for an input device is given by an ASCII controlz (1AH). Peripheral devices are seen by MP/M as "logical" devices, and are assigned to physical devices within the BIOS.

In order to operate, the BDOS needs only the CONST, CONIN,

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and CONOUT subroutines (LIST and LSTST may be used by PIP, but not the BDOS).

The characteristics of each device are

CONSOLE — The principal interactive consoles which communicate with the operators, accessed through CONST, CONIN, and CONOUT. Typically, CONSOLEs are devices such as CRTs or Teletypes.

LIST — The principal listing device, if it exists on your system, which is usually a hardcopy device, such as a printer or Teletype.

DISK — Disk I/O is always performed through a sequence of calls on the various disk access subroutines which set up the disk number to access, the track and sector on a particular disk, and the direct memory access (DMA) address involved in the I/O operation. After all these parameters have been set up, a call is made to the READ or WRITE function to perform the actual I/O operation. Note that there is often a single call to SELDSK to select a disk drive, followed by a number of read or write operations to the selected disk before selecting another drive for subsequent operations. Similarly, there may be a single call to set the DMA address, followed by several calls which read or write from the selected DMA address before the DMA address is changed. The track and sector subroutines are always called before the READ or WRITE operations are performed.

Note that the READ and WRITE routines Should perform several retries (10 is standard) before reporting the error condition to the BDOS. If the error condition is returned to the BDOS, it will report the error to the user. The HOME subroutine may or may not actually perform the track 00 seek, depending upon your controller characteristics; the important point is that track 00 has been selected for the next operation, and is often treated in exactly the same manner as SETTRK with a parameter of 00.

The exact responsibilities of each entry point subroutine are given below:

BOOT — The BOOT entry point gets called from the MP/M loader after it has been loaded by the cold start

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loader and is responsible for basic system initialization. Note that under MP/M a return must be made from BOOT to continue execution of the MP/M loader.

WBOOT The WBOOT entry point performs a BDOS system reset, terminating the calling process.

CONST Sample the status of the console device specified by register D and return OFFE in register A if a character is ready to read, or OOH in register A if no console characters are ready.

CONIN Read the next character from the console device specified by register D into register A, and set the parity bit (high order bit) to zero. If no console character is ready, wait until a character is typed before returning.

CONOUT Send the character from register C to the console output device specified by register D. The character is in ASCII, with high order parity bit set to zero. You may want to include a delay on a line feed or carriage return, if your console device requires some time interval at the end of the line (such as a TI Silent 700 terminal). You can, if you wish, filter out control characters which cause your console device to react in a strange way (a controlz causes the Lear Seigler terminal to clear the screen, for example).

LIST Send the character from register C to the listing device. The character is in ASCII with zero parity.

PUNCH The punch device is not implemented under MP/M. The transfer vector position is preserved to maintain CP/M compatibility. Note that MP/M supports up to 16 character I/0 devices, any of which can be a reader/punch.

READER The reader device is not implemented under MP/M. See the note above for PUNCH.

HOME Return the disk head of the currently selected disk (initially disk A) to the track 00 position. if your controller allows access to the track 0 flag from the drive, stepthe head until the track 0 flag is detected. if your controller does not support this feature, you can translate the HOME call into a call on SETTRK with a parameter of 0.

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SELDSK Select the disk drive given by register C for

further operations, where register C contains 0 for drive A, 1 for drive B, and soforth up to 15 for drive P (the standard MP/M distribution version supports four drives). On each disk select, SELDSK must return in HL the base address of a 16byte area, called the Disk Parameter Header, described in the digital research document titled "CP/M 2.0 Alteration Guide". For standard floppy disk drives, the contents of the header and associated tables does not change, and thus the program segment included in the sample XIOS performs this operation automatically. If there is an attempt to select a nonexistent drive, SELDSK returns HL=OOOOH as an error indicator.

On entry to SELDSK it is possible to determine whether it is the first time the specified disk has been selected. Register E, bit 0(least significant bit) is a zero if the drive has not been previously selected. This information is of interest in systems which read configuration information from the disk in order to set up a dynamic disk definition table.

Although SELDSK must return the header address on each call, it is advisable to postpone the actual physical disk select operation until an I/O function (seek, read or write) is actually performed, since disk selects often occur without utimately performing any disk I/0, and many controllers will unload the head of the current disk before selecting the new drive. This would cause an excessive amount of noise and disk wear.

SETTRK Register BC contains the track number for subsequent disk accesses on the currently selected drive. You can choose to seek the selected track at this time, or delay the seek until the next read or write actually occurs. Register BC can take on values in the range 076 corresponding to valid track numbers for standard floppy disk drives, and 065535 for nonstandard disk subsystems.

SETSEC Register BC contains the sector number (1 through 26) for subsequent disk accesses on the currently selected drive. You can choose to send this information to the controller at this point, or instead delay sector selection until a read or write operation occurs.

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SETDMA Register BC contains the DMA (disk memory access) address for subsequent read or write operations. For example, if B = OOH and C = 80H when SETDMA is called, then all subsequent readoperations read their datainto 80H through OFFH, and all subsequent write operations get their data from 80H through OFFH, until the next call to SETDMA occurs. The initial DMA address is assumed to be 80H. Note that the controller need not actually support direct memory access. If, for example, all data is received and sent through I/O ports, the XIOS which you construct will use the 128 byte area starting at the selected DMA address for the memory buffer during the following read or write operations.

READ Assuming the drive has been selected, the track has been set, the sector has been set, and the DMA address has been specified, theREAD subroutineattempts to read one sector based upon theseparameters, and returns the following error codes in register A:

0 no errors occurred
1 nonrecoverable error condition occurred

Currently, MP/M responds only to a zero or nonzero value as the return code. That is, if the value in register A is 0 then MP/M assumes that the disk operation completed properly. If an erroroccurs, however, the XIOS should attempt at least 10 retries to see if the error is recoverable. when an error is reported the BDOS will print the message "BDOS ERR ON x: BAD SECTOR". The operator then has the option of typing <cr> to ignore the error, or ctlC to abort.

WRITEWrite the data from the currently selected DMA address to the currently selected drive, track, and sector. The data should be marked as "non deleted data" to maintain compatibility with other MP/M systems. The error codes given in the READ command are returned in register A, with error recovery attempts as described above.

LISTST Return the ready status of the list device. The value 00 is returned in A if the list device is not ready to accept a character, and OFFH if a character can be sent to the printer. Note that a 00 value always suffices.

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SECTRAN Performssector logical to physical sector translation in order to improve the overall response of MP/M. Standard MP/M systems are shipped with a "skew factor" of 6, where six physical sectors are skipped between each logical read operation. This skew factor allows enough time between sectorsfor most programs to load their buffers without missing the next sector. In particular computer systemswhich use fast processors, memory, and disk subsystems, the skew factor may be changed to improve overall response. Note, however, that you should maintain a single density IBM compatible version of MP/M for information transfer into and out of your computer system, using a skew factor of 6. In general, SECTRAN receives a logical sector number in BC, and a translate table address in DE. The sector number is used as an index into the translate table, with the resulting physical sector number in HL.For standard systems, the tables and indexing code is provided in the XIOS and need not be changed.

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3.3 Extended I/O System Entry Points

The extended I/O facilities include the hardware environment dependent code to poll devices, handle interrupts and perform memory management functions.

A jump vector containing the extended I/O system entry points is located immediately following the BIOS jump vector as shown below:

```
BIOS+33H        JMP  SELMEMORY      ;SELECT MEMORY
BIOS+36H        JMP  POLLDEVICE;POLL DEVICE
BIOS+39H        JMP  STARTCLOCK;START CLOCK
BIOS+3CH        JMP  STOPCLOCK      ;STOP CLOCK
BIOS+3FH        JMP  EXITREGION;EXIT CRITICAL REGION
BIOS+42H        JMP  MAXCONSOLE;MAXIMUM CONSOLE NUMBER
BIOS+45H        JMP  SYSTEMINIT;SYSTEM INITIALIZATION
BIOS+48H        JMP  IDLE           ;IDLE PROCEDURE (Optional)
```

Each jump address corresponds to a particular subroutine which performs the specific function. The exact responsibilities of each entry point subroutine are given below:

SELMEMORY — Each time a process is dispatched to run a call is made to the XIOS memory protection procedure. If the hardware environment has memory bank selection/protection it can use the passed parameter to select/protect areas of memory. The passed parameter (in registers BC) is a pointer to a memory descriptor from which the memory base, size, attributes and bank of the executing process can be determined. Thus, all other regions of memory can to be write protected.

POLLDEVICE — In hardware environments where there are no interrupts a polled environment can be created by coding an XIOS device poll handler. The device poll handler (POLLDEVICE) is called by the XDOS with the device to be polled in the C register as a single parameter. The user written POLLDEVICE procedure can be coded to access the device polling routines via a table which contains the addresses of the device polling procedures. An association is made between a device number to be polled and the polling procedure itself. The polling procedures must return a value of OFFH in the accumulator if the device is ready, or OOH if the device is not ready.

STARTCLOCK — When a process delays for a specified number of

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ticks of the system time unit, the start clock procedure is called.

The purpose of the STARTCLOCK procedure is to eliminate unneccessary system clock interrupt overhead when there are not any delayed processes.

In some hardware environments it is not acutally possible to shut off the system time unit clock while still maintaining the one second flag used for the purposes of keeping time of day. In this situation the STARTCLOCK procedure simply sets a boolean variable to true, indicating that there is a delayed process. The clock interrupt handler can then determine if system time unit flag is to be set by testing the boolean.

STOPCLOCK When the system delay list is emptied the stop clock procedure is called.

The purpose of the STOPCLOCK procedure is to eliminate unneccessary system clock interrupt overhead when there are no delayed processes.

In some hardware environments it is not acutally possible to shut off the system time unit clock while still maintaining the one second flag used for the purposes of keeping time of day. (i.e. a single clock/timer interrupt source is used.) In this situation the STOPCLOCK procedure simply sets a boolean variable to false, indicating that there are no delayed processes. The clock interrupt handler can then determine if the system time unit flag is to be set by testing the boolean.

EXITREGION The purpose of the exit region procedure is to test a preempted flag, set by the interrupt handler, enabling interrupts if preempted is false. This procedure allows interrupt service routines to make MP/M system calls, leaving interrupts disabled until completion of the interrupt handling.

MAXCONSOLE The purpose of the maximum console procedure is to enable the calling program to determine the number of physical consoles which the BIOS is capable of supporting. The number of physical consoles is returned in the A register.

SYSTEMINIT The purpose of the system initialization

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procedure is to perform required MP/M cold start initialization. Typical initialization includes setting up interrupt jump vectors, interrupt masks, and setting up the base pagein each bank of a banked memory system.

The SYSTEMINIT entry point is called prior to any other XIOS call. The MPMLDR disables interrupts, thus it can be assumed that interrupts are still disabled upon entry to SYSTEMINIT. Interrupts are enabled by MP/M immediately upon return from SYSTEMINIT.

In systems with bank switched memory it is necessary to setup the base page (OOOOH 00FFH) within each bank of memory. Both the MPMLDR and MP/M itself assume that the base bank (bank#0) is switched in when the MPMLDR is executed. The base bank is properly initialized by MP/M prior to entering SYSTEMINIT. The information required for the initialization is provided on entry to SYSTEMINIT in the following registers:

C = MP/M Debugger restart #
DE = MP/M entry point address for the debugger
Place a jump at the proper debugger restart location to the address contained in DE.
HL = BIOS direct jump table address
Place a jump instruction at location 0000H in each banks base page to the address contained in HL.

IDLE

The idle entrypointis included to permit optimization of system performance when the user has an XIOS that is all interrupt driven. If you have polled devices in your XIOS, the IDLE procedure may be omitted by placing a NOP instruction at the BIOS+48H location where there would otherwise be a jump to an idle procedure.

The idle entry point is called repeatedly when MP/M is idling. That is, when there are no other processes ready to run. In systems that are entirely interrupt driven the idle procedure should be as follows:

```
IDLE:
     HLT
     RET
```


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INTERRPUT SERVICE ROUTINES

The MP/M operating system is designed to work with virtually any interrupt architecture, be it flat or vectored. The function of the code operating at the interrupt level is to save the required registers, determine the cause of the interrupt, remove the interrupting condition, and to set an appropriate flag. Operation of the flags are described in section 2.4. Briefly, flags are used to synchronize asynchronous processes. One process, such as an interrupt service routine, sets a particular flag while another process waits for the flag to be set.

At a logical level above the physical interrupts the flags can be regarded as providing 256 levels of virtual interrupts (32 flags are supported under release 1 of MP/M). Thus, logical interrupt handlers wait on flags to be set by the physical interrupt handlers. This mechanism allows a common XDOS to operate on all microcomputers, regardless of the hardware environment.

As an example consider a hardware environment with a flat interrupt structure. That is, a single interrupt level is provided and devices must be polled to determine the cause of the interrupt. Once the interrupt cause is determined a specific flag is set indicating that that particular interrupt has occurred.

At the conclusion of the interrupt processing a jump should be made to the MP/M dispatcher. This is done by jumping to the PDISP entry point. The effect of this jump is to give the processor to the highest priority ready process, usually the process readied by setting the flag in the interrupt handler, and then to enable interrupts before jumping to resume execution of the process.

The only XDOS or BDOS call which should be made from an interrupt handler is FUNCTION 133: FLAG SET. Any other XDOS or BDOS call will result in a dispatch which would then enable interrupts prior to completing execution of the interrupt handler.

It isrecommended that interrupts only be used for operations which are asynchronous, such as console input or disk operation complete. In general, operations such as console output should not be interrupt driven. The reason that interrupts are not desirable for console output is that the system is afforded some elasticity by performing polled console outputs while idling, rather than incurring the dispatch overhead for each character transmitted. This is particularily true at higher baud rates.

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On systems requiring the Z80 return from interrupt (RETI) instruction, the jump to PDISP at the end of the interrupt servicing can be done by placing the address of PDISP on the stack and then executing an RETI instruction.

TIME BASE MANAGEMENT

The time base management provided by the BIOS performs the operations of setting the system tick and one second flags. As described earlier the start and stop clock procedures control the system tick operation. The one second flag operation is logically separate from the system tick operation even though it may physically share the same clock/timer interrupt source.

The purpose of the system time unit tick procedure is to set flag #1 at system time unit intervals. The system time unit is used by MP/M to manage the delay list.

The recommended time unit is 16.67 milliseconds, corresponding to 60 Hz. When operating with 50 Hz the recommended time unit is 20 milliseconds.

The tick frequency is critical in that it determines the dispatch frequency for compute bound processes. If the frequency is too high, a significant amount of system overhead is incurred by excessive dispatches. If the frequency is too low, compute bound processes will keep the CPU resource for accordingly longer periods.

The purpose of the one second flag procedure is to set flag #2 at each second of real time. Flag #2 is used by MP/M to maintain a time of day clock.

XIOS EXTERNAL JUMP VECTOR

In order for the XIOS to access the BDOS/XDOS a jump vector is dynamically built by the MP/M loader and placed directly below the base address of the XIOS. The jump vector contains two entry points which provide access to the MP/M dispatcher, XDOS and BDOS.

The following code illustrates the equates used to access the jump table:

```
BASE    EQU  0000H;BASE OF THE BIOS
PDISPEQU BASE3;MP/M DISPATCHER
XDOS    EQU  PDISP3    ;MP/M BDOS/XDOS
...
CALL    XDOS           ;CALL TO XDOS THRU JUMP VECTOR
```


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3.4 System File Components

The MP/M system file, 'MPM.SYS' consists of five components: the system data page, the customized XIOS, the BDOS or ODOS, the XDOS, and the resident system processes. MPM.SYS resides in the directory with a user code of 0 and is usually read only. The MP/M loader reads and relocates the MPM.SYS file to bring up the MP/M system.

SYSTEM DATA

The system data page contains 256 bytes used by the loader to dynamically configure the system. The system data page can be prepared using the GENSYS program or it can be manually prepared using DDT or SID. The following table describes the byte assignments:

Byte	Assignment
000000	Top page of memory
001001	Number of consoles
002002	Breakpoint restart number
003003	Allocate stacks for user system calls, boolean
004004	Bank switched memory, boolean
005005	Z80 CPU, boolean
006006	Banked BDOS file manager, boolean
007015	Unassigned, reserved
016047	Initial memory segment table
048079	Breakpoint vector table, filled in by DDTs
080111	Stack addresses for user system calls
112122	Scratch area for memory segments
123127	Unassigned, reserved
128143	Submit flags
144255	Reserved

CUSTOMIZED XIOS

The customized XIOS is obtained from a file named 'XIOS.SPR'. The 'XIOS.SPR' file is actually a file of type PRL containing the page relocatable version of the user customized XIOS. A submit file on the distribution diskette named 'MACSPR.SUB' or 'ASMSPR.SUB' can be used to generate the user customized XIOS. The following sequence of commands will produce a 'XIOS.SPR' file given a user ‘XIOS.ASM' file:

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```
A>SUBMIT MACSPR XIOS
```

BDOS/ODOS

The Basic Disk Operating System (BDOS) file named 'BDOS.SPR' is a page relocatable file essentially containing the CP/M 2.0 disk file management. This module handles all the BDOS system calls providing both multiple console support and disk file management.

In systems with a banked BDOS, the file named 'ODOS.SPR' is a page relocatable file containing the resident portion of the banked BDOS.

XDOS

The XDOS file named 'XDOS.SPR' is a page relocatable file containing the priority driven MP/M nucleus. The nucleus contains the following code pieces: root module, dispatcher, queue management, flag management, memory management, terminal handler, terminal message process, command line interpreter, file name parser, and time base management.

RESIDENT SYSTEM PROCESSES

Resident system processes are identified by a file type of RSP. The RSP files distributed with MP/M include: runtime system status display (MPMSTAT), printer spooler (Spool), abort named process (ABORT), and a scheduler (SCHED).

At system generation time the user is prompted to select which RSPs are to be concatenated to the 'MPM.SYS' file.

It is possible for the user to prepare custom resident system processes. The resident system processes must follow these rules:

* The file itself must be page relocatable. Page relocatable files can be simply generated using the submit file 'MACSPR.SUB' or 'ASMSPR.SUB' and then renaming the file to change the type from 'SPR' to 'RSP'.

* The first two bytes of the resident system process are reserved for the address of the BDOS/XDOS. Thus a resident system process can access the BDOS/XDOS by loading the two bytes at relative 00000001H and then performing a PCHL.

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* The process descriptor for the resident system process

must begin at the third byte position. The contents of the process descriptor are described in section 2.3.

BNKBDOS

In addition to the MPM.SYS file a file named 'BNKBDOS.SPR' is used in systems with a banked BDOS. It is a page relocatable file containing the nonresident portion of the banked BDOS. This file is not used by systems without banked memory.

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3.5 System Generation

MP/M system generation consists of the preparation of a system data file and the concatenation of both required and optional code files to produce a file named 'MPM.SYS'. The operation is performed using a GENSYS program which can be run under either MP/M or CP/M. The GENSYS automates the system generation process by prompting the user for optional parameters and then prepares the 'MPM.SYS' file.

The operation of GENSYS is illustrated with two sample executions shown below:

```
A>GENSYS

MP/M System Generation



Top page of memory  = ff
Number of consoles  = 2
Breakpoint RST #    = 6
Add system call user stacks (Y/N)? y
Z80 CPU (Y/N)? y
Bank switched memory (Y/N)? n
Memory segment bases, (ff terminates list)
: 00
: 50
: aO
: ff
Select Resident System Processes: (Y/N)
ABORT     ? n
SPOOL     ? n
MPMSTAT        ? y
SCHED     ? y
```

The queries made during the system generation shown above are described as follows:

Top page of memory: Two hex ASCII digits are to be entered giving the top page of memory. A value of 0 can be entered in which case the MP/M loader will determine the size of memory at load time by finding the top page of RAM.

Number of consoles: Each console specified will require 256 bytes of memory. MP/M release 1 supports up to 16 consoles. During MP/M initialization an XIOS call is made to obtain the actual maximum number of physical consoles supported by the XIOS. This number is used if it is less than the number specified during the GENSYS.

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Breakpoint RST #: The breakpoint restart number to be used by the SID and DDT debuggers is specified. Restart 0 is not allowed. Other restarts required by the XIOS should also not be used.

Add system call user stacks (Y/N)?: If you desire to execute CP/M *.COM files then your response should be Y. A 'Y' response forces a stack switch with each system call from a user program. MP/M requires more stack space than CP/M.

Bank switched memory (Y/N)?: If your system does not have bank switched memory then you should respond with a 'N'. otherwise respond with a 'Y' and additional questions and responses (as shown in the second example) will be required.

Memory segment bases: Memory segmentation is defined by the entries which are made. Care must be taken in the entry of memory bases as all entries must be made with successively higher bases. If your system has ROM at OOOOH then the first memory segment base which you specify should be your first actual RAM location only page relocatable (PRL) programs can be run in systems that do not have RAM at location OOOOH.

Select Resident System Processes: A directory search is made for all files of type RSP. Each file found is listed and included in the generated system file if you respond with a 'Y'.

The second example illustrates a more complicated GENSYS in which a system is setup with bank switched memory and a banked BDOS. This procedure requires an initial GENSYS and MPMLDR execution to determine the exact size of the operating system, followed by a second GENSYS.

```
A>GENSYS

MP/M System Generation

Top page of memory = ff
Number of consoles = 2
Breakpoint RST #   = 6
Add system call user stacks (Y/N)? y
Z80 CPU (Y/N) y
Bank switched memory (Y/N)? y
Banked BDOS file manager (Y/N)? y
Enter memory segment table: (ff terminates list)
 Base,size,attrib,bank = 0,50,0,0
 Base,size,attrib,bank = ff
Select Resident System Processes: (Y/N)
ABORT     ? n
SPOOL     ? n.
```


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```
MPMSTAT        ? n

SCHED     ? y
```

The queries made during the system generation shown above which relate to bank switched memory are described as follows:

Bank switched memory: Respond with a 'Y'.

Bank switched BDOS file manager: Respond with a 'Y' if a bank switched BDOS is to be used, this will provide an additional OCOOH bytes of common area for large XIOS's and possibly some RSP's. The banked BDOS is slower than the nonbanked because FCB's must be copied from the bank of the calling program to common and then back again each time a BDOS disk function is invoked.

Memory segment bases: When bank switched memory has been specified, you are prompted for the base, size, attributes, and bank for each memory segment. Extreme care must be taken when making these entries as there is no error checking done by GENSYS regarding this function. The first entry made will determine the bank in which the banked BDOS is to reside. It is further assumed that the bank specified in the first entry is the bank which is switched in at the time the MPMLDR is executed. The attribute byte is normally defined as 00. However, if you wish to preallocate a memory segment a value of FFH should be specified. The bank byte value is hardware dependent and is usually the value sent to the bank switching hardware to select the specified bank.

Then execute the MPMLDR in order to obtain the base address of the operating system. The base address in this example will be the address of BNKBDOS.SPR (BCOOH).

```
A>MPMLDR

MP/M Loader

Number of consoles  =    2
Breakpoint RST #    =    6
Z80 CPU
Banked BDOS file manager
Top of memory  =    FFFFH

Memory Segment Table:
SYSTEM          DAT  FFOOH0100H
CONSOLE         DAT  FDOOH0200H
USERSYS         STK  FCOOH     0100H
```


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```
XIOS      SPR  F600H0600H

BDOS      SPR  EEOOH0800H
XDOS      SPR  CFOOH1FOOH
SchedRSP  CAOOH0500H
BNKBDOS   SPR  BCOOHOEOOH

---------
Memseg Usr OOOOH 5000H Bank OOH
```

Using the information obtained from the initial GENSYS and MPMLDR execution the following GENSYS can be executed:

```
A>GENSYS

MP/M System Generation

Top page of memory = ff
Number of consoles = 2
Breakpoint RST #   = 6
Add system call user stacks (Y/N)? y
Z80 CPU (Y/N)? y
Bank switched memory (Y/N)? y
Banked BDOS file manager. (Y/N)? y
Enter memory segment table: (ff terminates list)
     Base,size,attrib,bank = O,bc,0,0
     Base,size,attrib,bank = O,cO,O,l
     Base,size,attrib,bank = O,cO,0,2
     Base,size,attrib,bank = ff
Select Resident System Processes: (Y/N)
ABORT     ? n
SPOOL     ? n
MPMSTAT        ? n
SCHED     ? y
```


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3.6 MP/M Loader

The MPMLDR program loads the 'MPM.SYS' file and dynamically relocates and configures the MP/M operating system. MPMLDR can be run under CP/M or loaded from the first two tracks of a disk by the cold start loader.

The MPMLDR provides a display of the system loading and configuration. It does not require any operator interaction.

In the following example the 'MPM.SYS' file prepared by the first GENSYS example shown in section 3.5 is loaded:

```
A>MPMLDR

MP/M Loader

Number of consoles  = 2
Breakpoint RST #    = 6
Z80 CPU
Top of memory       = FFFFH

Memory Segment Table:
SYSTEM    DAT  FFOOH0100H
CONSOLE   DAT  FDOOH0200H
USERSYS   STK  FCOOH0100H
XIOS      SPR  F600H0600H
BDOS      SPR  E200H1400H
XDOS      SPR  C300HlF00H
MPMSTAT   RSP  B600HODOOH
SchedRSP  B100H0500H

Memseg    Usr AOOOH 1100H
Memseg    Usr 5000H 5000H
Memseg    Usr OOOOH 5000H

MP/M
0A>
```


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In the following example the 'MPM.SYS' file prepared by the second GENSYS example shown in section 3.5 is loaded:

```
A>MPMLDR

MP/M Loader

Number of consoles  = 2
Breakpoint RST #    = 6
Z80 CPU
Banked BDOS file manager
Top of memory       = FFFFH

Memory Segment Table:
SYSTEM    DAT FFOOH 0100H
CONSOLE   DAT FD00H 0200H
USERSYS   STK FCOOH 0100H
XIOS      SPR F600H 0600H
BDOS      SPR EEOOH 0800H
XDOS      SPR CFOOH lF00H
SchedRSP CAOOH 0500H
BNKBDOS   SPR BCOOH OEOOH

Memseg Usr OOOOH COOOH Bank 02H
Memseg Usr OOOOH COOOH Bank 01H
Memseg Usr OOOOH BCOOH Bank OOH

MP/M
0A>
```


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APPENDIX A: Flag Assignments

0	Reserved
1	System time unit tick
2	One second interval
3	One minute interval
4	Undefined
	Undefined
31	Undefined

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APPENDIX B: Process Priority Assignments

0	31	: Interrupt handlers
32	63	: System processes
64	197	: Undefined
	198	: Terminal message processes
	199	: Command line interpreter
	200	: Default user priority
201 -	254	: User processes
	255	: Idle process

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APPENDIX C: BDOS Function Summary

FUNC	FUNCTION NAME	INPUT PARAMETERS	OUTPUT RESULTS
0	System Reset	none	none
1	Console Input	none	A = char
2	Console output	E = char	none
3	Raw Console Input	none	A = char
4	Raw Console Output	E = char	none
5	List Output	E = char	none
6	Direct Console I/0	see def	see def
7	** Not supported **		
8	** Not supported **		
9	Print String	DE = .Buffer	none
10	Read Console Buffer	DE = .Buffer	see def
11	Get Console Status	none	A = 00/01
12	Return Version Number	none	HL= Version #
13	Reset Disk System	none	see def
14	Select Disk	E=Disk Numbersee def	
15	Open File	DE = .FCB	A = Dir Code
16	Close File	DE = .FCB	A = Dir Code
17	Search for First	DE = .FCB	A = Dir Code
18	Search for Next	none	A = Dir Code
19	Delete File	DE = .FCB	A = Dir Code
20	Read Sequential	DE = .FCB	A = Err Code
21	Write Sequential	DE = .FCB	A = Err Code
22	Make File	DE = .FCB	A = Dir Code
23	Rename File	DE = .FCB	A = Dir Code
24	Return Login Vector	none	HL= Login Vect*
25	Return Current Disk	none	A = Cur Disk#
26	Set DMA Address	DE = .DMA	none
27	Get Addr(Alloc)	none	HL= Alloc
28	Write Protect Disk	none	see def
29	Get R/O Vector	none	HL= R/O Vect*
30	Set File Attributes	DE = .FCB	see def
31	Get Addr(disk parms)	none	HL= DPB
32	Set/Get User Code	see def	see def
33	Read Random	DE = .FCB	A = Err Code
34	Write Random	DE = .FCB	A = Err Code
35	Compute File Size	DE = .FCB	rO, rl, r2
36	Set Random Record	DE = .FCB	rO, rl, r2
37	Reset Drive	DE = drive vctr	A = Err Code
38	Access Drive	DE = drive vctr	none
39	Free Drive	DE = drive vctr	none
40	Write Random zerofill	DE = .FCB	A = Err Code

Note that A = L, and B = H upon return

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APPENDIX D: XDOS Function Summary

FUNC	FUNCTION NAME	INPUT PARAMETERS	OUTPUT RESULTS
128	Absolute Memory Rqst	DE = .MD	A = err code
129	Relocatable Mem Rqst	DE = .MD	A = err code
130	Memory Free	DE = .MD	none
131	Poll	E = Device	none
132	Flag Wait	E = Flag	A = err code
133	Flag Set	E = Flag	A = err code
134	make Queue	DE = .QCB	none
135	Open Queue	DE = .UQCB	A = err code
136	Delete Queue	DE = .QCB	A = err code
137	Read Queue	DE = .UQCB	none
138	Conditional Read Que	DE = .QCB	A = err code
139	Write Queue	DE = .UQCB	none
140	Conditional Write Que	DE = .UQCB	A = err code
141	Delay	DE #ticks	none
142	Dispatch	none	none
143	Terminate Process	E = Term. code	none
144	Create Process	DE = .PD	none
145	Set Priority	E = Priority	none
146	Attach Console	none	none
147	Detach Console	none	none
148	Set Console	E = Console	none
149	Assign Console	DE = .APB	A = err code
150	Send CLI Command	DE = .CLICMD	none
151	Call Resident Sys Pr	DE .CPB	HL = result
152	Parse Filename	DE .PFCB	see def
153	Get Console Number	none	A = console #
154	System Data Address	none	HL = sys data adr
155	Get Date and Time	DE = TOD	none
156	Return Proc. Dsc. Adr	none	HL = proc descr adr
157	Abort Spec. Process	DE = .ABTPB	A = err code

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APPENDIX E: Memory Segment Base Page Reserved Locations

Each memory segment base page, between locations OOH and OFFH, contains code and data which are used during MP/M processing. The code and data areas are given below for reference purposes.

Locations from	to	Contents
OOOOH	0002H	Contains a jump instruction to XDOS which terminates the process. This allows simple process termination by executing a JMP OOOOH.
0005H	0007H	Contains a jump instruction to the BDOS & XDOS, and serves two purposes: JMP 0005H provides the primary entry point to the BDOS & XDOS, and LHLD 0006H brings the address field of the instruction to the HL register pair. This value is the top of the memory segment in which the program is executing.Note that the DDT program will change the address field to reflect the reduced memory size in debug mode.
0008H	003AH	(interrupt locations 1 through 7 not used) However, one restart must be selected for use by the debugger and specified during system generation.
003BH	003FH	(not currently used reserved)
0040H	004FH	16 byte area reserved for scratch, but is not used for any purpose in the distribution version of MP/M
0050H	005BH	(not currently used reserved)
005CH	007CH	default file control block produced for a transient program by the command line interpreter.
007DH	007FH	optional default random record position
0080H - OOFFH		default 128 byte disk buffer (also filled with the command line when a transient is loaded under the CLI).

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Appendix F: Operation of MP/M on the Intel MDS800

This section gives operating procedures for using MP/M on the Intel MDS microcomputer development system. A basic knowledge of the MDS hardware and software systems is assumed.

MP/M is initiated in essentially the same manner as Intel's ISIS operating system. The disk drives labelled 0 through 3 on the MDS, correspond to MP/M drives A through D, respectively. The MP/M system diskette is inserted into drive 0, and the BOOT and RESET switches are depressed in sequence. The interrupt 2 light should go on at this point. The space bar is then depressed on either console device, and the light should go out. The BOOT switch is then turned off, and the MP/M signon message should appear at both consoles, followed by the "OA>" for the CRT or "lA>" for the TTY. The user can then issue MP/M commands.

Use of the interrupt switches on the front panel is not recommended. Effective 'warmstarts' should be initiated at the console by aborting the running program rather than pushing the INT 0 switch. Also, depending on the choice of restart for the debugger the INT switch which will invoke the debugger is not necessarily #7.

Diskettes should not be removed from the drives until the user verifies that there are no other users with open files on the disk. This can be done with the 'DSKRESET' command.

When performing GENSYS operations on the MDS800, make certain that a negative response is always made to the Z80 CPU question. Responding with a 'Y' will lead to unpredictable results.

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APPENDIX G: Sample Page Relocatable Program

```
      ******************************************
      *  Note:                                 *
      *       This program listing has been    *
      *  included only as a sample and may not *
      *  reflect changes required by later MP/M *
      *  releases. For this reason the reader  *
      *  should assemble and list the program  *
      *  as provided on the distribution disk. *
      ******************************************
                page 0
0000            org  0000h
0000       base equ  $
0100            org  0100h

           ;note: either base0l00.asm or base0200.asm must be ap
           ;to the beginning of this file before assembling.

           ;    title'file dump program'
           ;    file dump program, reads an input file and
           ;    prints in hex

           ;copyright (c) 1975, 1976, 1977,.1978, 1979, 19
           ;digital research
           ;box 579, pacific grove
           ;california, 93950

0005 =     bdos      equ  base+5    ;dos entry point
0001 =     cons      equ  1         ;read console
0002 =     typefequ  2         ;type function
0009 =     printf    equ  9         ;buffer print entry
000b =     brkf      equ  11        ;break key function
000f =     openfequ  15        ;file open
0014 =     readfequ  20        ;read function

005c =     fcb       equ  base+5ch  ;file control block address
0080 =     buff      equ  base+80h  ;input disk buffer address

           ;non graphic characters
000d =     cr        equ  Odh       ;carriage return
000a =     lf        equ  Oah       ;line feed

           ;file control block definitions
005c =     fcbdnequ  fcb+O;disk name
005d =     fcbfnequ  fcb+l;pfile name
0065 =     fcbftequ  fcb+9;disk file type (3 characters)
0068 =     fcbrlequ  fcb+12    ;file's current reel number
```


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```
006b =    fcbrcequ  fcb+15    ;file's record count (0 to 128

007c =    fcbcrequ  fcb+32    ;current (next) record number
007d =    fcblnequ  fcb+33    ;fcb length
          ;         set up stack
0100 210000         lxi  h,O
0103 39             dad  sp
          ;         entry stack pointer in hl from the ccp
0104 22lfO2         shld oldsp
          ;         set sp to local stack area (restored at finis)
0107 316102         lxi  sp,stktop
          ;         read and print successive buffers
010a cdc601         call setup;set up input file
OlOd feff           cpi  255       ;255 if file not present
010f c2lbOl         jnz  openok    ;skip if open is ok

          ;         file not there, give error message and return
0112 llfdOl         lxi  d,opnmsg
0115 cdalOl         call err
0118 c35601         jmp  finis;to return
          openok:   ;open operation ok, set buffer index to end
Ollb 3e8O           mvi  a,80h
Olld 32ldO2         sta  ibp       ;set buffer pointer to 80h
          ;         hl contains next address to print
0120 210000         lxi  h,O       ;start with 0000

          gloop:
0123 e5             push h         ;save line position
0124 cda701         call gnb
0127 el             POP  h         ;recall line position
0128 da5601         jc   finis;carry set by gnb if end file
012b 47             mov  b,a
          ;         print hex values
          ;         check for line fold
012c 7d             mov  a,l
012d e60f           ani  Ofh       ;check low 4 bits
012f c24401         jnz  nonum
          ;         print line number
0132 cd7701         call crlf
          ;         check for break key
0135 cd5eOl         call break
          ;         accum lsb = 1 if character ready
0138 Of             rrc            ;into carry
0139 da5lOl         jc   purge;don't print any more
013c 7c             mov  a,h
013d cd9401         call phex
0140 7d             mov  a,l
0141 cd9401         call phex
          nonum:
0144 23             inx  h         ;to next line number
```


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```
0145 3e2O           mvi  a,' `

0147 cd6aOl         call pchar
014a 78             mov  a,b
014b cd9401         call phex
014e c32301         jmp  gloop

          purge:
0151 OeOl           mvi  c,cons
0153 cd05OO         call bdos
finis:
          ;         end of dump, return to cap
          ;         (note that a jmp to 0000h reboots)
0156 cd7701         call crlf
0159 2alfO2         lhld oldsp
015C f9             sphl
          ;         stack pointer contains cap's stack location
015d c9             ret       ;to the ccp

suDroutines

          break:    ;check break key (actually any key will do)
015e e5d5c5         push h! push d! push b; environment saved
0161 OeOb           mvi  c,brkf
0163 cd05OO         call bdos
0166 cldlel         pop b! pop d! pop h; environment restored
0169 c9             ret
          pchar:    ;print a character
016a e5d5cS         push h! push d! push b; saved
016d OeO2           mvi  c,typef
016f 5f             mov  e,a
0170 cd05OO         call bdos
0173 cldlel         pop b! pop d! pop h; restored
0176 c9             ret

crlf:
0177 3eOd           mvi  a,cr
0179 cd6aOl         call pchar
017c 3eOa           mvi  a,lf
017e cd6aOl         call pchar
0181 c9             ret

          pnib:;print nibble in reg a
0182 e60f           ani       Ofh  ;low 4 bits
0184 fe0a           cpi       10
0186 d28eOl         jnc       plo
          ;         less than or equal to 9
0189 c630           adi       `0'
018b c39001         jmp       prn
          ;         greater   or equal to 10
```


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```
018e c637      pl0: adi  'a'  10

0190 cd6aOl    prn: call pchar
0193 c9             ret

          phex:;print hex char in reg a
0194                f5   push psw
0195 Of             rrc
0196 Of             rrc
0197 Of             rrc
0198 Of             rrc
0199 cd8201         call pnib           ;print nibble
019C fl             POP  psw
019d cd8201         call pnib
OlaO c9             ret

          Err:      ;print error message
          ;         d,e addresses message ending with
Olal OeO9           mvi  c,printf  ;print buffer function
Ola3 cd05OO         call bdos
Ola6 c9             ret
          gnb:      ;get next byte
Ola7 3aldO2         lda  ibp
Olaa fe8O           cpi  80h
Olac c2b801         jnz  go
                    ;read another buffer
Olaf cdd30l         call diskr
Olb2 b7             ora  a         ;zero value if read ok
Olb3 cab.801        jz   go        ;for another byte
          ;         end of data, return with carry set for eof
Olb6 37             stc
Olb7 c9             ret
          go:       ;read the byte at buff+reg a
Olb8 5f             mov  e,a       ;ls byte of buffer index
Olb9 1600           mvi  d,O       ;double precision index to de
Olbb 3c             inr  a         ; i nd ex= i nd ex+l
Olbc 32ldO2         sta  ibp       ;back to memory
          ;         pointer   is incremented
          ;         save the current file address
Olbf 218000         lxi  h,buff
O.lc2 19            dad  d
          ;         absolute character address is in hl
Olc3 7e             mov  a,m
          ;         byte is   in the accumulator
Olc4 b7             ora  a         ;reset carry bit
Olc5 c9             ret

          setup:    ;set up file
          ;         open the file for input
```


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```
Olc6 af             xra  a              ;zero to accum

Olc7 327cOO         sta  fcbcr     ;clear current record
Olca 115cOO         Ixi  d,fcb
Olcd OeOf           mvi  c,openf
Olcf cd05OO         call bdos
          ;         255 in accum if open error
Old2 c9             ret

          diskr:    ;read disk file record
Old3 e5d5c5         push hl push d! push b
Old6 115cOO         lxi  d,fcb
Old9 Oe14           mvi  c,readf
Oldb cd05OO         call bdos
Olde cldlel         pop b! pop d! pop h
Olel c9             ret
          ;         fixed message area
          signon:
Ole2 46696c6520db   'file dump mp/m version 1.0$'
          opnmsg:
Olfd OdOa4e6f2Odb   cr,lf,'no input file present on disk$'

          ;         variable area
021d      ibp:      ds   2    ;input buffer pointer
021f      oldsp:    ds   2    ;entry sp value from ccp
          ;         stack area
0221                ds   64   reserve 32 level stack
          stktop:
0261                end
```


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Proprietary to Digital Research.)

APPENDIX H: Sample Resident System Process

```
*********************************************
*  Note:                                    *
*  This program listing has been            *
*  included only as a sample and may not    *
*  reflect changes required by later MP/M   *
*  releases. For this reason the reader     *
*  should assemble and list the program     *
*  as provided on the distribution disk.    *
*********************************************


                page 0

                title'type file on console'
                ;file type program, reads an input file and pri
                ;it on the console

                ;copyright (c) 1979, 1980
                ;digital research
                ;p.o. box 579
                ;pacific grove, ca 93950

0000                    org  0000h     ;standard rsp start

001a      =     ctlz      equ  lah            ; controlz used for e
0002      =     conout    equ  2              ; bdos conout function
0009      =     printf    equ  9              ; print buffer
0014      =     readfequ  20             ; read next record
000f      =     openfequ  15             ; open fcb
0098      =     parsefn   equ  152       ; parse file name
0086      =     mkqueequ  134       ; make queue
0089      =     rdqueequ  137       ; read queue
0091      =     stprior   equ  145       ; set priority
0093      =     detach    equ  147       ; detach console

              ; bdos entry point address
                    bdosadr:
0000 0000             dw   $$   ldr will fill this i

              ; type process descriptor

                    typepd:
0002 0000             dw   0              ;link
0004 00               db   0              ;status
0005 Oa               db   10             ;priority (initial)
0006 1001             dw   stack+38       ;stack pointer
0008 5459504520     db   'type    ';name in upper case
```


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```
          pdconsole:

0010                ds   1              ;console
0011 ff             db   Offh           ;memseg
0012                ds   2              ;b
0014                ds   2              ;thread
0016 3601           dw   buff           ;disk set dma address
0018                ds   1              ;user code & disk sel
0019                ds   2              ;dcnt
001b                ds   1              ;searchl
001C                ds   2              ;searcha
001e                ds   2              ;active drives
0020                ds   20             ;register save area
0034                ds   2              ;scratch

               ; type linked queue control block

          typelqcb:
0036 0000           dw   0              ;link
0038 5459504520db   'type    ';name in upper case
0040 4800           dw   72             ;msglen
0042 0100           dw   I              ;nmbmsgs
0044                ds   2              ;dqph
0046                ds   2              ;nqph
0048                ds   2              ;mh
004a                ds   2              ;mt
004c                ds   2              ;bh
004e                ds   74             ;buf(72 + 2 byte lin

               ; type user queue control block

          typeuserqcb:
0098 3600           dw   typelqcb       ; pointer
009a 9cOO           dw   field     ; msgadr

                    ;field for message read from type linked qcb

          field:
009C                ds   1              ;disk select
          console:
009d                ds   1              ;console
          filename:
009e                ds   72             ;message body

               ; parse file name control block

          pcb:
OOe6 9eOO           dw                  ;filename file name address
OOe8 1201           dw   fcb            ;file control block a
```


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```
                ;type stack & other local data structures


                stack:
00ea                 ds   38              ;20 level stack
0110 ba0:       dw   type            ;process entry point
0112       fcb:      ds   36              ;file control block
0136       buff:ds   128             ;file buffer

                ;bdos call prdeedure

                bdos:
Olb6 2aOOOO          lhld bdosadr         ;hl = bdos address
Olb9 e9              pchl

           ;type main program

                type:
Olba Oe86            mvi  c,mkque
Olbc 113600          lxi  d,typelqcb
Olbf cdb60l          call bdos            ; make typelqcb
Olc2 Oe9l            mvi  c,stprior
Olc4 llc800          lxi  d,200
Olc7 cdb601          call bdos            ; set priority to 200

           forever:
Olca Oe89            mvi  c,rdque
Olcc 119800          lxi  d,typeuserqcb
Olcf cdb60l          call bdos            ; read from type queue
Old2 0698            mvi  c,parsefn
Old4 lle600          lxi  d,pcb
Old7 cdb601          call bdos            ; parse the file name
Olda 23              inx  h
Oldb 7c              mov  a,h
Oldc b5              ora  1               ; test for Offffh
Oldd calf02          jz   error
OleO 3a9dOO          Ida  console
Ole3 321000          sta  pdconsole       ; typepd.console = con
Ole6 OeOf            mvi  c,openf
Ole8 111201          Ixi  d,fcb
Oleb cdb601          call bdos            ; open file
Olee 3c              inr  a               ;test return code
Olef calf02          jz   error      ;if it was Offh, no f
Olf2 af              xra  a               ;else,
Olf3 323201          sta  fcb+32          ;set next record to
           new$sector:
Olf6 Oe14            mvi  c,readf
Olf8 111201          lXi  d,fcb
```


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```
Olfb cdb601          call bdos            ;read next record

Olfe b7              ora  a
Olff c22702          jnz  done            ;exit if eof or error
0202 213601          Ixi  h,buff          ;point to data sector
0205 Oe8O            mvi  c,128      ;get byte count
          next$byte:
0207 7e              mov  a,m             ;get the byte
0208 5f              mov  e,a             ;save in e
0209 fela            cpi  ctlz
020b ca2702          jz                   ;doneexit if eof
020e c5              push b               ;save byte counter
020f e5              push h               ;save address registe
0210 OeO2            mvi  c,conout
0212 cdb601          call bdos            ;write console
0215 el              POP  h               ;restore pointer
0216 cl              POP  b               ;and counter
0217 23              inx  h               ;bump pointer
0218 Od              dcr  c               ;dcr byte counter
0219 c207O2          jnz  next$byte       ; more in this sector
021c c3f601          jmp  new$sector;else, we need a new

          error:
021f 112fO2          lxi  d,err$msg       ;point to error messa
0222 OeO9            mvi  c,printf        ; get function code to
0224 cdb601          call bdos

               done:
0227 Oe93            mvi  c,detach
0229 cdb601          call bdos            ;detach the console
022c c3ca01          jmp  forever

          err$msg:
022f OdOa46696cdb    Odh,Oah,'file not found or bad file na

0251                 end
```


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APPENDIX I: Sample XIOS

```
        ******************************************
        *  Note:                                 *
        *  This program listing has been         *
        *  included only as a sample and may not  *
        *  reflect changes.required by later MP/M *
        *  releases. For this reason the reader   *
        *  should assemble and list the program   *
        * as provided on the distribution disk.   *
        ******************************************

                page 0
0000            org  0000h

     ;note: this module assumes that an org statement will
     ;provided by concatenating either base0000.asm or b
     ;to the front of this file before assembling.
          ;title    1xios for the mds800'

     ;(four drive single density version)
                ;or
     ;(four drive mixed double/single density)
     ;version 1.1 january, 1980
;
     ;copyright (c) 1979, 1980
     ;digital research
     ;box 579, pacific grove
     ;california, 93950

0000 =    falseequ  0
ffff =    true      equ  not false
ffff =    asm       equ  true
0000 =    mac       equ  not asm
ffff =    sgl       equ  true
0000 =    dbl       equ  not sgl
                    if   mac
                    maclib    diskdef
                    endif
0004 =    numdisks  equ  4    ;number of drives available

                    ;external jump table (below xios base)
fffd =    pdispequ  $3
```


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```
fffa =    xdos      equ  pdisp3


                    ;mds interrupt controller equates
00fd =    revrtequ  Ofdh      ; revert port
Oofc =    intc      equ  Ofch      ; mask port
OOf3 =    icon      equ  Of3h      ; control port
Ooff =    rtc       equ  Offh      ; real time clock
00fd =    inte      equ  1111$110lb ; enable rst 1

                    ;mds disk controller equates
0078      dskbase   equ  78h       ; base of disk io prts
0078 =    dstatequ  dskbase   ; disk status
0079 =    rtypeequ  dskbase+l ; result type
007b =    rbyteequ  dskbase+3 ; result byte
0079 =    ilow      equ  dskbase+l ; iopb low address
007a =    ihighequ  dskbase+2 ; iopb high address
0004 =    readfequ  4h        ; read function
0006 =    writfequ  6h        ; write function
0004 =    iordyequ  4h        ; i/o finished mask
000a =    retryeq6  10        ; max retries on disk i/o

                    ;basic i/o system jump vector
0000 c34bOO         jmp  coldstart ;cold start
wboot:
0003 c34bOO         jmp  warmstart      ;warm start
0006 c35000         jmp  const     ;console status
0009 c35700         jmp  conin     ;console character in
000c c35eOO         jmp  conout         ;console character out
000f c3acOO         jmp  list           ;list character out
0012 c36cOO         jmp  rtnempty       ;punch not implemented
0015 c36cOO         jmp  rtnempty       ;reader'not implemente
0018 c306O2         jmp  home           ;move head to home
001b c3e501         jmp  seldsk         ;select disk
001e c308O2         jmp  settrk         ;set track number
0021 c30dO2         jmp  setsec         ;set sector number
0024 c31202         jmp  setdma         ;set dma address
0027 c32402         jmp  read           ;read disk
002a c32902         jmp  write     ;write disk
002d c3clOO         jmp  pollpt         ;list status
0030 c31802         jmp  sect$tran      ;sectortransl

                    ;extended i/o system jump vector
0033 c31501         jmp  selmemory ;select memory
0036 c3fcOO         jmp  polldevice     ;poll device
0039 c31601         jmp  startclock     ;start clock
003c c3lcOl         jmp  stopclock ;stop clock
003f c32101         jmp  exitregion     ;exit region
0042 c32801         jmp  Maxconsole     ;maximum console numb
0045 c32bOl         jmp  systeminit;system initializatio
0048 c34001         jmp  idle           ;idle procedure
```


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```
          coldstart:

          warmstart:
004b OeOO           mvi  C,0        ;see system init
                                    ;cold & warm start in
                                    ;for compatibility wi
004d c3faff         jmp  xdos       ;system reset, termin
                    ;mp/m1.0  console handlers

0002 =    nmbcns    equ  2          ;number of consoles
0083 =    poll      equ  131        ;xdos poll function
0000 =    pllptequ  0          ;poll printer
0001 =    pldskequ  1          ;poll disk
0002 =    plcooequ  2          ;poll console out #0 (crt:)
0003 =    plcolequ  3          ;poll console out #1 (tty:)
0004 =    plcioequ  4          ;poll console in #0 (crt:)
0005 =    plcilequ  5          ;poll console in #1 (tty:)
          const:                    ;console status
0050 cd6500         call ptbljmp    ; compute and jump to hndlr
0053 7900 dw        ptost      ; console #0 status routine
0055 c900 dw        ptlst      ; console #1 (tty:) status rt

          conin:                    ; console input
0057 cd65OO         call ptbljmp    ; compute and jump to hndlr
005a 8100           dw   pt0in      ;console #0 input
005c dlOO           dw   ptlin      ;console #1 (tty:) input
          conout:                   ;console output
005e cd6500         call ptbljmp    ;compute and jump to hndlr
0061 8dOO           dw   pt0out     ;console #0 output
0063 ddOO           dw   ptlout     ;console #1 (tty:) output
     ptbljmp:                       ;compute and jump to handler
                                    ;d = console #
                                    ;do not destroy <d>
0065 7a             mov  a,d
0066 fe02           cpi  nmbcns
0068 da6eOO         jc   tbljmp
006b fl             POP  psw        ;throw away table address
rtnempty:
006c af             xra  a
006d c9             ret
          tbljmp:                   ; compute and jump to handler
                                    ;a = table index
006e 87             add  a          ;double table index for adr o
006f el             POP  h          ;return adr points to jump tb
0070 5f             mov  e,a
0071 1600           mvi  d,O
```


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```
0073 19             dad  d          ; add table index * 2 to tbl b

0074 5e             mov  e,m        ; get handler address
0075 23             inx  h
0076 56             mov  d,m
0077 eb             xchg
0078 e9             pc hl      ; jump to computed cns handler

ascii character equates

007f =    rubout    equ  7fh
0020 =    spaceequ  20h

; serial i/o port address equates

00f6 =    dataOequ  Of6h
OOf7 =    stso      equ  dataO+l
OOf4 =    datalequ  Of4h
OOf5 =    stsl      equ  datal+l
00fa =    lptport   equ  Ofah
00fb =    lptsts    equ  lptport+l

               ; poll console #0 input

          polcio:
          ptost:         ;return Offh if ready,
                         ;000h if not
0079 dbf7           in   stso
007b e602           ani  2
007d c8             rz
007e 3eff           mvi  a,Offh
0080 C9             ret

               ;console #0 input

          pt0in:         ;return character in reg a
0081 Oe83           mvi  C,poll
0083 le04           mvi  e,plciO
0085 cdfaff         call xdos      ; poll console #0 inpu
0088 dbf6           in   dataO; read character
008a e67f           ani  7fh       ; strip parity bit
008c c9             ret

               ;console #0 output

          pt0out:                ;req c = character to output
008d dbf7           in   stso
008f e601           ani  Olh
0091 c29900         jnz  coOrdy
0094 c5             push b
0095 cd9dOO         call ptOwait   ;poll console #0 outp
0098 cl             POP  b
     coOrdy:
```


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```
0099 79             mov  a,c

009a d3f6           out  dataO;transmit character
009C C9             ret
                    ;wait for console #0 output ready
          ptOwait:
009d Oe83           mvi  C,poll
009f le02           mvi  e,plcoO
00al c3faff         jmp  xdos      ;poll console #0 outp
                    ret

                    ;poll console #0 output

          polcoo:
                              ;return Offh if ready,
                              ;000h if not
OOa4 dbf7           in   stso
OOa6 e601           ani  Olh
OOa8 c8             rz
OOa9 3eff           mvi  a,0ffh
00ab c9             ret

               ;line printer driver:

          list:          ;list output
00ac dbfb           in   lptsts
00ae e601           ani  Olh
OObO c2bcOO         jnz  lptrdy
OOb3 c5             push b
OOb4 Oe83           mvi  C, poll
OOb6 leOO           mvi  e, pllpt
OOb8 cdfaff         call xdos
00bb cl             POP  b
          lptrdy:
OObc 79             mov  a,c
OObd 2f             cma
00be d3fa           out  lptport
00CO C9             ret

               ;poll printer output

          pollpt:        ;return Offh if ready,
                         ;000h if not
00cl dbfb           in   lptsts
OOc3 e601           ani  Olh
OOc5 c8             rz
OOc6 3eff           mvi  a,Offh
00cs C9             ret
```


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```
;               poll console #1 (tty) input


          polcil:
          ptlst:
                                ;return Offh if ready,
                    000h ;if not
OOc9 dbf5           in   stsl
00cb e602           ani  2
00cd c8             rz
00ce 3eff           mvi  a,Offh
OOdO c9             ret

console #1 (tty:) input

          ptlin:
                                ;return character in reg a
OOdl Oe83           mvi  C,poll
OOd3 le05           mvi  e,plcil
OOd5 cdfaff         call xdos       ;poll console #1 inpu
OOd8 dbf4           in   datal;read character
00da e67f           ani  7fh        ;strip parity bit
OOdc c9             ret

console #1 (tty:) output

          ptlout:
OOdd dbf5           in   stsl
OOdf e601           ani  Olh
00el c2e9OO         jnz  colrdy
                                ;reg c character to output
OOe4 c5             push b
0Oe5 cdedOO         call ptlwait
OOe8 cl             POP  b
          colrdy:
OOe9 79             mov  a,c
00ea d3f4           out  datal;transmit character
00ec c9             ret

               ;wait for conso1e #1 (tty: output r eady

          ptlwait:
00ed Oe83           mvi  c,pol1
00ef le03           mvi  e,plcol
00fl c3faff         jmp  xdos       ; poll console #1 outp
                    ret

               ;poll console #1 (tty:) output

          polcol:
                                ;return Offh if ready,
                                ;000h if not
OOf4 dbf5           in   stsl
OOf6 e601           ani  Olh
```


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```
OOf8 c8             rz

OOf9 3eff           mvi  a,Offh
00fb c9             ret
               ;mp/m     1.0  extended i/o system

0006       nmbdev   equ  6          ; number of devices in poll tb
           polldevice:
                                     ; reg c   device # to be polle
                                     ; return Offh if ready,
                                     ;000h if not
00fc 79             mov  a,c
00fd fe06           cpi  nmbdev
00ff da0401         jc   devok
0102 3eO6           mvi  a,nmbdev  ;if dev # >= nmbdev,
                                   ;set to nmbdev
devok:
0104 cd6eOO         call tbljmp    ;jump to dev poll code

0107 clOO           dw   pollpt    ;poll printer output
0109 7dO2           dw   poldsk    ;poll disk ready
010b a400           dw   polcoO    ;poll console  #0   output
010d f400           dw   polcol    ;poll console  #1   (tty:) outpu
010f 7900           dw   polciO    ;poll console  #0   input
0111 C900           dw   polcil    ;poll console  #1   (tty:)input
0113 6cOO           dw   rtnempty  ;bad device handler

           ;select / protect memory

           selmemory:
                                   ;reg bc = adr of mem descript
                                   ;bc ->    base      1 byte,
                                   ;         size      1 byte,
                                   ;         attrib    1 byte,
                                   ;         bank      1 byte.

           ;this hardware does not have memory protection or
           ;bank switching

0115 c9             ret

           ;start clock
           startclock:
                                   ; will cause flag #1 to be set
                                   ; at each system time unit tick
0116 3eff           mvi  a,Offh
0118 32e301         sta  tickn
```


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```
011b c9             ret


          ;stop clock

          stopclock:
                                    ;will stop flag #1 setting at
                                    ;system time unit tick
011c af             xra  a
011d 32e301         sta  tickn
0120 c9             ret

          ;exit region

          exitregion:
                                    ; ei if not preempted
0121 3ae401         lda  preempt
0124 b7             ora  a
0125 c0             rnz
0126 fb             ei
0127 c9             ret

          ;maximum console number

          maxconsole:
0128 3e02           mvi  a,nmbcns
012a c9             ret

          system initialization

     systeminit:
          ;         note: this system init assumes that the usarts
          ;         have been initialized by the coldstart boot

          ;         setup restart jump vectors
012b 3ec3           mvi  a,0c3h
012d 320800         sta  1*8
0130 214501         lxi  h,intlhnd
0133 220900         shld 1*8+1      ;jmp intlhnd at resta

          ;         setup interrupt controller & real time clock
0136 3efd           mvi  a,inte
0138 d3fc           out  intc           ;enable int 0',1,7
013a af             xra  a
013b d3f3           out  icon           ;clear int mask
013d d3ff           out  rtc            ;enable real time clo
013f c9             ret

          ; idle procedure

          idle:
0140 0e8e           mvi  c,dsptch
0142 c3faff         jmp  xdos           ;perform a dispatch,
```


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```
                                    ;of idle must be use

                                    ;without interrupts,

                ;or

                ;ei  simply halt until aw
                ;hlt      interrupt
                ;ret

                ; mp/m 1.0interrupt handlers

0085      =     flagset   equ  133
008e      =     dsptch    equ  142

          intlhnd:
                                ;interrupt1 handler entry po
                                ;location 0008h contains a j
                                ;to intlhnd.
0145 f5             push psw
0146 3eO2           mvi  a,2h
0149 d3ff           out  rtc       ;reset real time clock
014a d3fd           out  revrt;revert intr cntlr
014c 3aabOl         lda  slice
014f 3d             dcr  a         ;only service every 16th slic
0150 32abOl         sta  slice
0153 ca5901         jz   tl6ms;jump if 16ms elapsed
0156 fl             POP  psw
0157 fb             ei
0158 c9             ret
          tl6ms:
0159 3elO           mvi  a,16
015b 32abOl         sta  slice;reset slice counter
015e fl             POP  psw
015f 22ddOl         shld svdhl
0162 el             POP  h
0163 22elOl         shld svdret
0166 f5             push psw
0167 210000         Ixi  h,O
016a 39             dad  sp
016b 22dfOl         shld svdsp; save users stk ptr
016e 3lddOl         lxi  sp,intstk+48   ;lcl stk for intr hnd
0171 d5             push d
0172 c5             push b
0173 3eff           mvi  a,Offh
0175 32e401         sta  preemp    ;set preempted flag
0178 3ae301         lda  tickn
017b b7             ora  a         ; test tickn, indicate
;                                  ; delayed process(es)
```


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```
017c ca8601          jz   notickn

017f Oe85            mvi  c,flagset
0181 le0l            mvi  e,l
0183 cdfaff          call xdos      ;set flag #1 each tic
          notickn:
0186 21acOl          lxi  h,cnt64
0189 35              dcr  m         ;dec 64 tick cntr
018a c29601          jnz  notlsec
018d 3640            mvi  m,64
018f Oe85            mvi  c,flagset
0191 le02            mvi  e,2
0193 cdfaff          call xdos      ;set flag #2 @ 1 sec
          notlsec:
0196 af              xra  a
0197 32e401          sta  preemp    ;clear preempted flag
019a cl              POP  b
019b dl              POP  d
019c 2adfOl          lhld svdsp
019f f9              sphl           ;restore stk ptr
OlaO fl              POP  psw
Olal 2aelOl          lhld svdret
Ola4 e5              push h
Ola5 2addOl          lhld svdhl

          ;the following dispatch call will force round robin
          ;scheduling of processes executing at the same prior
          ;each 1/64th of a second.
          ;note: interrupts are not enabled until the ditpatche
          ;resumes the next process. this prevents interrupt
          ;overrun of the stacks when stuck or high frequency
          ;interrupts are encountered.

Ola8 c3fdff          jmp  pdisp;mp/m dispatch

          ;bios data segment

Olab 10   slice:     db   16        ;16 slices = 16ms = 1 tick
Olac 40   cnt64:     db   64        ;64 tick cntr = 1 sec
Olad      intstk:    ds   48        ;local intrpt stk
Oldd 0000 svdhl:     dw   0         ;saved regs hl during int hnd
Oldf 0000 svdsp:     dw   0         ;saved sp during int hndl
Olel 0000 svdret:    dw   0         ;saved return during int hndl
Ole3 00   tickn:     db   0         ;ticking boolean,true delay
Ole4 00   preemp:    db   0         ;preempted boolean

         * * * * * * * * * * * * * * * * * * * * * * * * * * * *
         *
         *    intel mds800 diskette interface routines
         *
         * * * * * * * * * * * * * * * * * * * * * * * * * * * *
```


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```
          seldsk:    ;select disk given by register c

Ole5 210000          lxi  h, 0
Ole8 79              mov  a,c
Ole9 fe04            cpi  numdisks
Oleb dO              rnc             ;first, insure good select
Olec e602            ani  2
Olee 32baO2          sta  dbank;then save it
Olfl 21c202          lxi  h,sel$table
Olf4 0600            mvi  b,O
Olf6 09              dad  b
Olf7 7e              mov  a,m
Olf8 32bcO2          sta  iof
Olfb 60              mov  h,b
Olfc 69              mov  l,c
Olfd 29              dad  h
Olfe 29              dad  h
Olff 29              dad  h
0200 29              dad  h          ;times 16
0201 llc602          Ixi  d,dpbase
0204 19              dad  d
0205 c9              ret

          home:;move to home position
                     ;treat as track 00 seek
0206 OeOO            mvi  C,0

          settrk:    ;set track address given by c
0208 21beO2          lxi  h,iot
020b 71              mov  m,c
020c c9              ret

          setsec:    ;set sector number given by c
020d 79              mov  a,c        ;sector number to accum
020e 32bfO2          sta  ios        ;store sector number to iopb
0211 c9              ret

          setdma:    ;set dma address given by regs b,c
0212 69              mov  l,c
0213 60              mov  h,b
0214 22cOO2          shld iod
0217 c9              ret
          sect$tran:           ;translate the sector # in <c
0218 60              mov  h,b
0219 69              mov  l,c
021a 23              inx  h          ;in case of no translation
021b 7a              mov  a,d
021c b3              ora  e
021d c8              rz
021e eb              xchg
021f 09              dad  b          ;point to physical sector
0220 6e              mov  l,m
0221 2600            mvi  h,O
```


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```
0223 c9             ret


          read:;read next disk record (assuming disk/trk/sec/
0224 OeO4           mvi  c,readf ;set to read function
0226 c32bO2         jmp  setfunc

          write:    ;disk write function
0229 OeO6           mvi  c,writf

          setfunc:
          ;         set function for next i/o (command in regc)
022b 21bcO2         lxi  h,iof     ;io function address
022e 7e             mov  a,m            ;get it to accumulator for mas
022f e6f8           ani  1111$1000b;remove previous comma
0231 bl             ora  c              ;set to new command
0232 77             mov  m,a            ;replaced in iopb
          ;         single density drive 1 requires bit 5 on in se
          ;         mask the bit from the current i/o function
0233 e620           ani  0010$0000b;mask the disk select
0235 2lbfO2         lxi  h,ios     ;address the sector se
0238 b6             ora  m              ;select proper disk ba
0239 77             mov  m,a            ;set disk select bit o

          waitio:
023a OeOa           mvi  c,retry        ;max retries before perm error
          rewait:
          ;         start the i/o function and wait fok completion
023c cd9302         call intype         ;in rtype
023f cda002         call inbyte         ;clears   the controller
0242 3abaO2         lda  dbank     ;set bank flags
0245 b7             ora  a              ;zero if drive 0,1 and
0246 3ebb           mvi  a,iopb and Offh;low address for iopb
0248 0602           mvi  b,iopb shr 8   ;high address for iopb
024a c25502         jnz  iodrl     ;drive bank 1?
024d d379           out  ilow           ;low address to contro
024f 78             mov  a,b
0250 d37a           out  ihiqh     ;high address
0252 c35aO2         jmp  waitO     ;towait for complete

          iodrl:    ;drive bank 1
0255 d389           out  ilow+10h       ;88 for drive bank 10
0257 78             mov  a,b
0258 d38a           out  ihigh+loh
          waitO:
025a c5             push b              ; save retry count
025b Oe83           mvi  C, poll        ; function poll
025d leOl           mvi  e, pldsk       ; device is disk
025f cdfaff         call xdos
0262 cl             POP  b              ; restore retry counte
```


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```
          ;         check io completion ok

0263 cd9302         call intype         ;must be io complete
          ;         00 unlinked i/o complete,   01 linked i/o com
          ;         10 disk status changed      11 (not used)
0266 fe02           cpi  10b            ;ready status change?
0268 ca8602         jz   wready
          ;         must be 00 in the accumulator
026b b7             ora  a
026c c28cO2         jnz  werror         ;some other condition,

          ;         check i/o error bits
026f cda002         call inbyte
0272 17             ral
0273 da8602         jc   wready         ;unit not ready
0276 lf             rar
0277 e6fe           ani  11111110b      ;any other errors? (d
0279 c28cO2         jnz  werror

          ;         read or write is ok, accumulator contains zero
027c c9             ret

          poldsk:
027d cdad02         call instat         ;get current
0280 e604           ani  iordy          ; operation co
0282 c8             rz                  ;not done
0283 3eff           mvi  a,Offh         ;done flag
0285 c9             ret                 ;to xdos

          wready:        ;not ready, treat as error for now
0286 cda002         call inbyte    ;clear result byte
0289 c38cO2         jmp  trycount

          werror:        ;return hardware malfunction (crc, track, seek
          ;              the mds controller has returned a bit in each
          ;              of the accumulator, corresponding to the condi
          ;              0         deleted data (accepted as ok above)
          ;              1         crc error
          ;              2         seek error
          ;              3         address error (hardware malfunction)
          ;              4         data over/under flow (hardware malfu
          ;              5         write protect (treated as not ready)
          ;              6         write error (hardware malfunction)
          ;              7         not ready
          ;              (accumulator bits are numbered 7 6 5 4 3 2 1 0
          trycount:
          ;              register c contains retry count, decrement 'ti
028c Od             dcr       c
028d c23cO2         jnz       rewait ;for another try
          ;              cannot recover from error
```


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```
0290 3eOl           mvi  a,l  ;error code

0292 c9             ret

          ;         intype,   inbyte, instat read drive bank 00 or 1
0293 3abaO2intype:  lda  dbank
0296 b7             ora  a
0297 c29dO2.        jnz  intypl         ;skip to bank 10
029a db79           in   rtype
029c c9             ret
029d db89 intypl:   in   rtype+10h      ;78 for 0,1    88 for 2,
029f c9             ret

02aO 3abaO2inbyte:  lda  dbank
02a3 b7             ora  a
02a4 c2aaO2         jnz  inbytl
02a7 db7b           in   rbyte
02a9 c9             ret
02aa db8b inbytl:   in   rbyte+10h
02ac c9             ret
02ad 3abaO2instat:  lda  dbank
02bO b7             ora  a
02bl c2b7O2         jnz  instal
02b4 db78           in   dstat
02b6 c9             ret
02b7 db88 instal:   in   dstat+10h
02b9 c9             ret

     ;              data areas (must be in ram)

02ba 00   dbank:    db   0    ;disk bank 00 if drive 0,1
                               ;          10 if drive 2,3

          iopb:          ;io parameter block
02bb 80             db   80h       ;normal i/o operation
02bc 04   i0f:      db   readf;io function, initial read
02bd 01   ion:      db   1         ;number of sectors to read
02be 02   iot:      db   2         ;track number
02bf 01   ios:      db   1         ;sector number
02cO 0000 iod:      dw   $$        ;io address

     sel$table:
                    if   sgl
02c2 00300030       db   00h, 30h, 00h, 30h  ; drive select
                    endif
                    if   dbl
                    db   00h, 10h, 00h, 30h  ; drive select
                    endif

                    if   mac and sgl
```


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```
                    disksnumdisks                   ;generate dri

                    diskdef   0,1,26,6,1024,243,64,64,2
                    diskdef   1,0
                    diskdef   2,0
                    diskdef   3,0
                    endef
                    endff

                    if   mac and dbl
                    disksnumdisks                   ;generate dri
                    diskdef 0,1,52,,2048,243,128,128,2,0
                    diskdef 1,0
                    diskdef 2,1,26,6,1024,243,64,64,2
                    diskdef 3,2
                    endef
                    endif

                    if   asm
02c6            dpbase    equ  $              ;base of disk param bl
02c6 15030000 dpeO: dw   xltO,0000h     ;translate table
02ca 00000000       dw   0000h,0000h          ;scratch area
02ce 2fO3O6O3       dw   dirbuf,dpbO          ;dir buff, parm block
02d2 ce03afO3       dw   csvO,alvO            ;check, alloc vectors
02d6 15030000 dpel: dw   xltl,0000h     ;translate table
02da 00000000       dw   0000h,0000h          ;scratch area
02de 2fO3O6O3       dw   dirbuf,dpbl          ;dir buff, parm block
02e2 fd03deO3       dw   csvl,alvl            ;check, alloc vectors
02e6 15030000 dpe2: dw   xlt2,0000h     ;translate table
02ea 00000000       dw   0000h,0000h          ;scratch area
02ee 2fO3O6O3       dw   dirbuf,dpb2          ;dir buff, parm block
02f2 2cO4OdO4       dw   csv2,alv2            ;check, alloc vectors
02f6 15030000 dpe3: dw   xlt3,0000h     ;translate table
02fa 00000000       dw   0000h,0000h          ;scratch area
02fe 2fO3O6O3       dw   dirbuf,dpb3          ;dir buff, parm block
0302 5bO43cO4       dw   csv3,alv3            ;check, alloc vectors
0306            dpbO equ  $                   ;disk param block
                endif

                    if   asm and dbl
                    dw   52   ;sec per track
                    db   4    ;block shift
                    db   15   ;block mask
                    db   0    ;extnt mask
                    dw   242  ;disk size1
                    dw   127  ;directory max
                    db   192  ;allocO
                    db   0    ;allocl
                    dw   32   ;check size
                    dw   2    ;offset
                x1to equ  0    ;translate table
                dpbl equ  dpbO
                xltl equ  x1to
                dpb2 equ  $
```


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```
                    endif


                    if   asm
0306 laOO           dw   26   ;sec per track
0308 03             db   3    ;block shift
0309 07             db   7    ;block mask
030a 00             db   0    ;extnt mask
030b f200           dw   242  ;disk size1
030d 3fOO           dw   63   ;directory max
030f cO             db   192  ;allocO
0310 00             db   0    ;allocl
0311 1000           dw   16   ;check size
0313 0200           dw   2    ;offset
                    endif
                    if   asm and sgl
0315           x1to equ  $
                    endif
                    if   asm and dbl
               xlt2 equ  $
                    endif
                    if   asm
0315 01             db   1
0316 07             db   7
0317 Od             db   13
0318 13             db   19
0319 19             db   25
031a 05             db   5
031b Ob             db   11
031c 11             db   17
031d 17             db   23
031e 03             db   3
031f 09             db   9
0320 Of             db   15
0321 15             db   21
0322 02             db   2
0323 08             db   8
0324 Oe             db   14
0325 14             db   20
0326 la             db   26
0327 06             db   6
0328 Oc             db   12
0329 12             db   18
032a 18             db   24
032b 04             db   4
032c Oa             db   10
032d 10             db   16
032e 16             db   22
                    endif

                    if   asm and sgl
```


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```
0306 =          dpbl       equ  dpb0

0315 =          xltl       equ  x1to
0306 =          dpb2       equ  dpb0
0315 =          xlt2       equ  x1to
0306 =          dpb3       equ  dpb0
0315 =          xlt3       equ  x1to
                           endif

                           if   asm and dbl
                dpb3       equ  dpb2
                xlt3       equ  xlt2
                           endif

                           if   asm
032f       begdat          equ  $
032f       dirbuf:         ds   128  ;directory access buff
                           endif

                           if   asm and sgl
03af alvO:            ds   31
03ce cSVO:            ds   16
03de alvl:            ds   31
03fd csvl:            ds   16
                           endif

                           if   asm and dbl
                alvo:ds    31
                cSVO:ds    32
                alvl:ds    31
                csvl:ds    32
                           endif

                           if asm
040d            alv2:ds    31
042c            csv2:ds    16
043c            alv3:ds    31
045b            csv3:ds    16
046b =          enddat     equ  $
013c =          datsiz     equ  $begdat
                           endif

046b 00                    db   0    ; this last db is reqld to
                                     ; ensure that the hex file
                                     ;output includes the entire
                                     ;diskdef
046c                       end
```


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APPENDIX J: MP/M DDT Enhancements

The following commands have been added to the MP/M debugger to provide a function similar to CP/M's SAVE command and to simplify the task of patching and debugging PRL programs.

W: WRITE DISK

The purpose of the WRITE DISK command is to provide the capability to write a patched program to disk. A single parameter immediately follows the 'W' which is the number of sectors (128 bytes/sector) to be written. This parameter is entered in hexadecimal.

V: VALUE

The purpose of the VALUE command is to facilitate use of the WRITE DISK comm6nd by computing the parameter to follow the 'W'. A single parameter immediately follows the 'V' which is the NEXT location following the last byte to be written to disk.

Normally a user would read in a file, edit it, and then write it back to disk. The read command produces a value for NEXT. This value can be entered as a parameter folllowitig the 'V' command and the number of sectors to be written out using the 'W' command will be computed and displayed.

N: NORMALIZE

The purpose of the NORMALIZE command is to relocate a page relocatable file which has been read into memory by the debugger. To debug a PRL program the user would read it in with the 'R' command and then use the 'N' command to relocate it within the memory segment the debugger is executing.

B: BITMAP BIT SET/RESET

The purpose of the BITMAP BIT SET/RESET command is to enable the user to update the bitmap of a page relocatable file. To edit a PRL file the user would read the file in, make changes to the code, and then determine the bytes which needed relocation (E.G. the high order address bytes of jump instructions). The 'B' command would then be used to update the bit map. There are two parameters specified, the address to be modified (0100H is the base of the program segment), followed by a zero or a one. A value of one specifies bit setting.

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APPENDIX K: Page Relocatable (PRL) File Specification

Page relocatable files are stored on diskette in the following format:

Address:	Contents:
00010002H	Program size
00040005H	Minimum buffer requirements (additional memory)
0006OOFFH	Currently unused, reserved for future allocation

0100H + Program size = Start of bit map

The bit map is a string of bits identifying which bytes are to be relocated. There is one bit map byte per 8 bytes of program. The most significant bit (7) of the first byte of the bit map indicates whether or not the first byte of the program is to be relocated. A bit which is on indicates that relocation is required. The next bit, bit(6), of the first byte of the bit map corresponds to the second byte of the program.

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